

CS473 - Algorithms I



Lecture 12-b Dynamic Tables

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Why Dynamic Tables?

- Assume we need a data structure that needs to reside in contiguous memory (e.g. linear array, etc.).
- But, we don't know how many objects will be stored in the table ahead of time.
- We may allocate space for a table, but later find out that it is **not enough**.
 - Then, the table must be **reallocated with a larger size**.
 - All the objects stored in the original table must be **copied over into the new table**.

Why Dynamic Tables?

- Similarly, if many objects are deleted from the table:
 - ▣ It may be worthwhile to reallocate the table with a smaller size.
- This problem is called:
dynamically expanding and contracting a table

Why Dynamic Tables?

Using **amortized analysis** we will show that,

The amortized cost of **insertion** and **deletion** is $O(1)$.

Even though the actual cost of an operation is large when it **triggers** an **expansion** or a **contraction**.

We will also show how to guarantee that

The unused space in a dynamic table never exceeds a **constant fraction of the total space**.

Operations

TABLE-INSERT:

Inserts into the table an item that occupies a single slot.

TABLE-DELETE:

Removes an item from the table & frees its slot.

Load Factor

Load Factor of a Dynamic Table T

$$\alpha(T) = \frac{\text{Number of items stored in the table}}{\text{size}(\text{number of slots}) \text{ of the table}}$$

For an empty table

$$\alpha(T) = \frac{0}{0} = 1$$

by definition

Insertion-Only Dynamic Tables

Table-Expansion:

- Assumption:
 - Table is allocated as an array of slots
- A table **fills up** when
 - all slots have been used
 - equivalently, when its load factor becomes 1
- **Table-Expansion** occurs when
 - An item is to be **inserted** into a **full table**

Insertion-Only Dynamic Tables

- A Common Heuristic
 - Allocate a new table that has twice as many slots as the old one.
- Hence, we have:

$$1 / 2 \leq \alpha(T) \leq 1$$

Table Insert

TABLE-INSERT (T, x)

if size[T] = 0 then

 allocate table[T] with 1 slot

 size[T] ← 1

if num[T] = size[T] then

 allocate new-table with 2.size[T] slots

 copy all items in table[T] into new-table

 free table[T]

 table[T] ← new-table[T]

 size[T] ← 2.size[T]

insert x into table[T]

num[T] ← num[T] + 1

end

table[T] : pointer to
block of table storage

num[T] : number of
items in the table

size[T] : total number of
slots in the table

Initially, table is empty, so
num[T] = size[T] = 0

Example: Dynamic Table Insertion

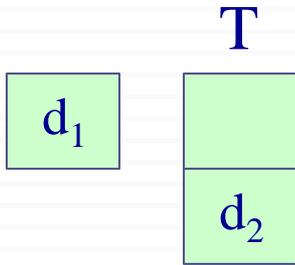
T

d_1

INSERT(d_1)

INSERT(d_2)

Example: Dynamic Table Insertion

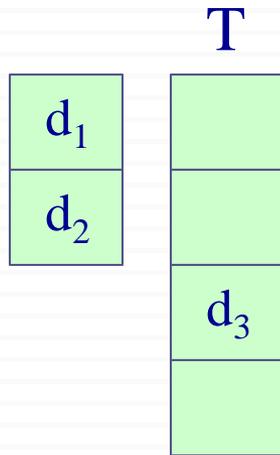


INSERT(d_1)

INSERT(d_2)

INSERT(d_3)

Example: Dynamic Table Insertion



INSERT(d_1)

INSERT(d_2)

INSERT(d_3)

Example: Dynamic Table Insertion

T

d_1
d_2
d_3
d_4

INSERT(d_1)

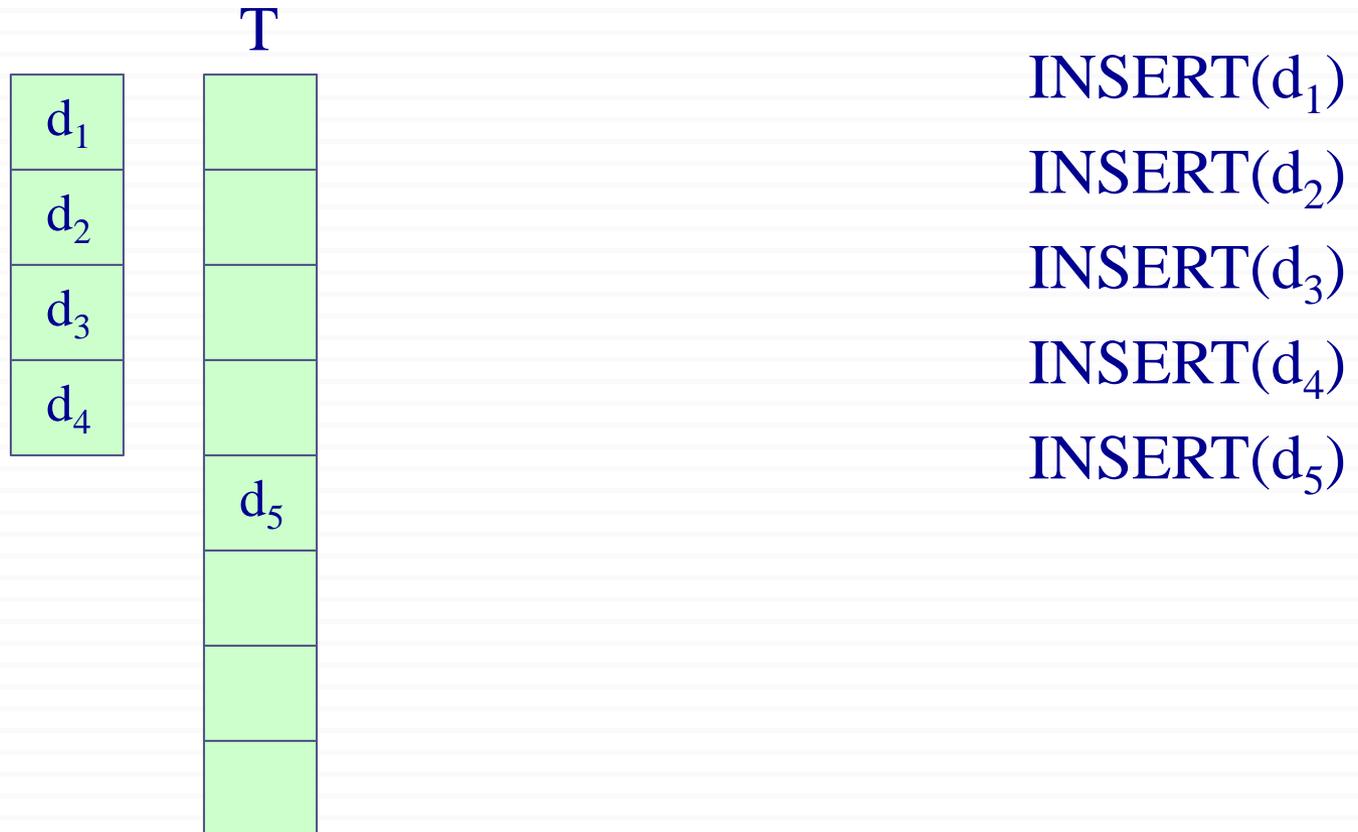
INSERT(d_2)

INSERT(d_3)

INSERT(d_4)

INSERT(d_5)

Example: Dynamic Table Insertion



Example: Dynamic Table Insertion

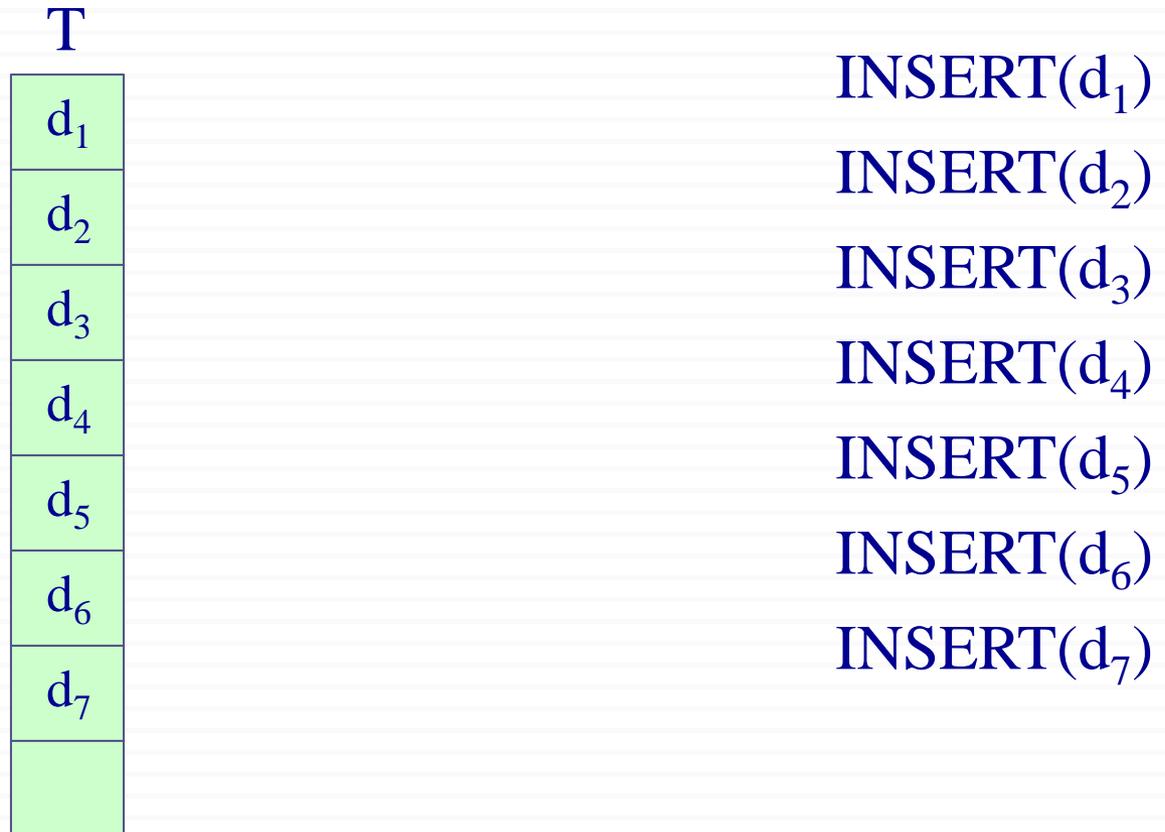


Table Expansion: Runtime Analysis

- The actual running time of **TABLE-INSERT** is linear in the time to insert individual items.
- Assume that **allocating and freeing** storage is dominated by the **cost of transferring items**.
- Assign a **cost of 1** to each **elementary insertion**.
- Analyze a sequence of **n TABLE-INSERT** operations on an **initially empty table**.

Cost of Table Expansion

- What is the cost c_i of the i^{th} operation if there is room in the current table?

$$c_i = 1 \quad (\text{only one elementary insert operation})$$

- What is the cost c_i of the i^{th} operation if the current table is full?

$$c_i = i$$

$i-1$ for the items that must be copied from the old table to the new table.

1 for the elementary insertion of the new item

Cost of Table Expansion

- What is the worst-case runtime of n **INSERT** operations?

The worst case cost of 1 **INSERT** operation is $O(n)$

Therefore, the total running time is $O(n^2)$

- **This bound is not tight!**

Expansion does not occur so often in the course of n **INSERT** operations

Amortized Analysis of INSERT: Aggregate Method

- Table is initially empty.
- Compute the total cost of n INSERT operations.
- When does the i^{th} operation require an expansion?

only when $i-1$ is a power of 2

i	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	...
c_i	1	2	3	1	5	1	1	1	9	1	1	1	1	1	1	1	17	1	1	1	...
elem. ins	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	...
Expansion cost		1	2		4				8								16				

Amortized Analysis of INSERT: Aggregate Method

Reminder: c_i is the actual cost of the i^{th} **INSERT** operation

$$c_i = \begin{cases} i & \text{if } i-1 \text{ is an exact power of } 2 \\ 1 & \text{otherwise} \end{cases}$$

Therefore the total cost of n **TABLE-INSERT** operations is:

$$\sum_{i=1}^n c_i \leq n + \sum_{j=0}^{\lfloor \lg n \rfloor} 2^j < n + 2n = 3n$$

The amortized cost of a single operation is $3n/n = 3 = O(1)$

The Accounting Method

Assign the following **amortized costs**

- **Table-Expansion** : \$0
- **Insertion** of a new item : \$3

Insertion of a new item:

- \$1 (**as an actual cost**) for inserting itself into the table
- + \$1 (**as a credit**) for **moving itself** in the next expansion
- + \$1 (**as a credit**) for **moving another item** (in the next expansion) that has already **moved in the last expansion**

Accounting Method Example

	T	
\$1	d ₁	
\$1	d ₂	

INSERT(d₂) \$3

Note: Amortized cost of INSERT(d₂): \$3

\$1 spent for the actual cost of inserting d₂

\$1 credit for moving d₂ in the next expansion

\$1 credit for moving d₁ in the next expansion

Accounting Method Example



Note: When expansion is needed for the next INSERT operation, we have $\$1$ stored credit for each item to move it to the new memory location.

Accounting Method Example



Note: Amortized cost of INSERT(d₃): \$3

\$1 spent for the actual cost of inserting d₃

\$1 credit for moving d₃ in the next expansion

\$1 credit for moving d₁ in the next expansion

Accounting Method Example

T		
\$1	d ₁	INSERT(d ₂) \$3
\$1	d ₂	INSERT(d ₃) \$3
\$1	d ₃	INSERT(d ₄) \$3
\$1	d ₄	

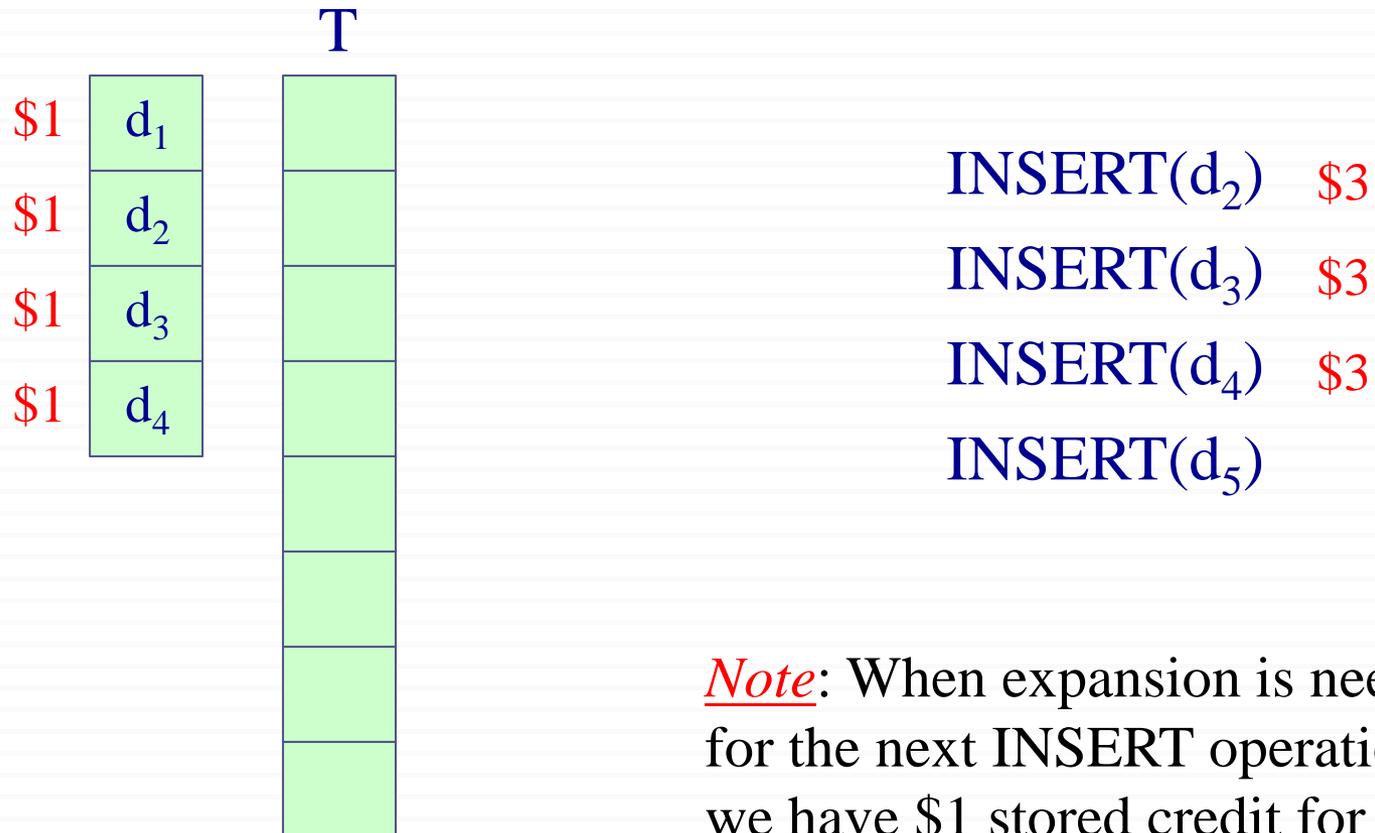
Note: Amortized cost of **INSERT(d₄)**: \$3

\$1 spent for the actual cost of inserting d₄

\$1 credit for moving d₄ in the next expansion

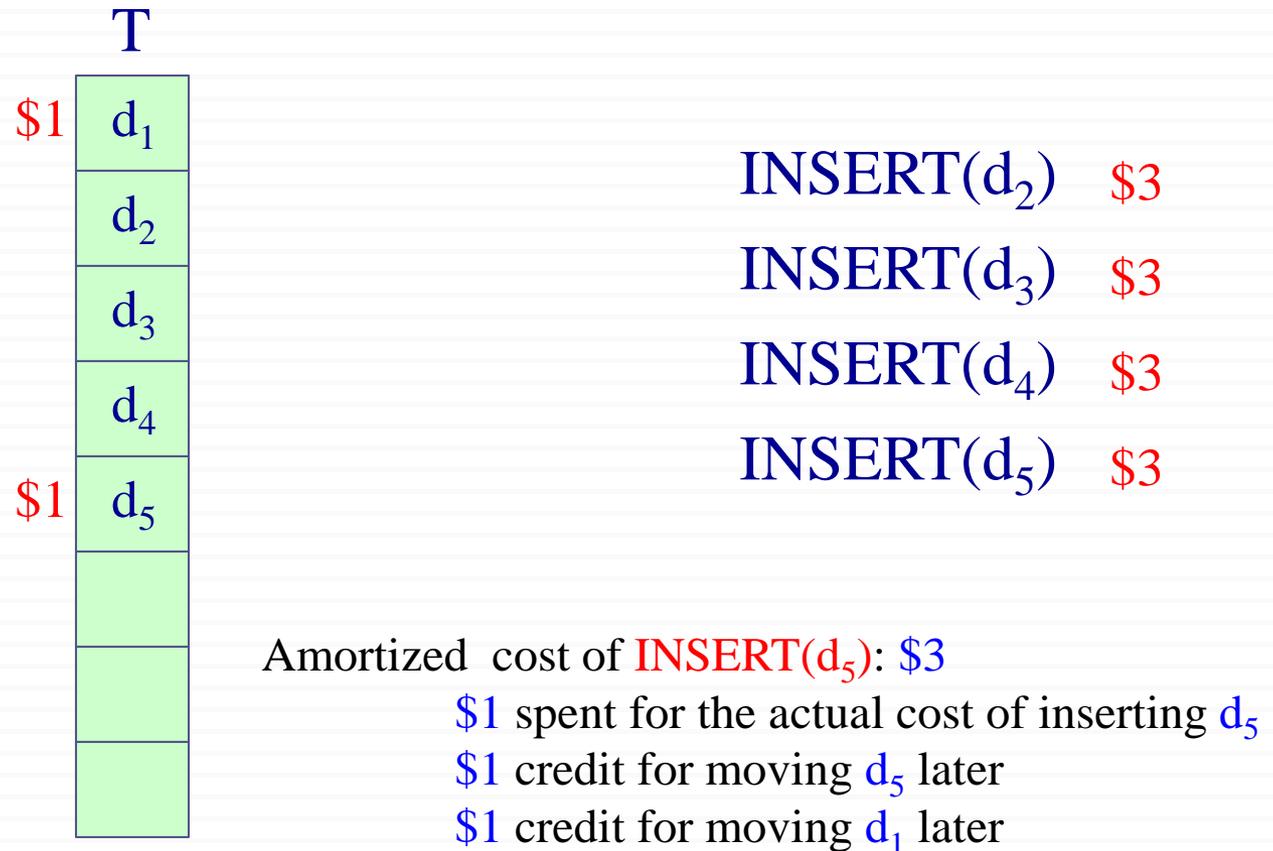
\$1 credit for moving d₂ in the next expansion

Accounting Method Example

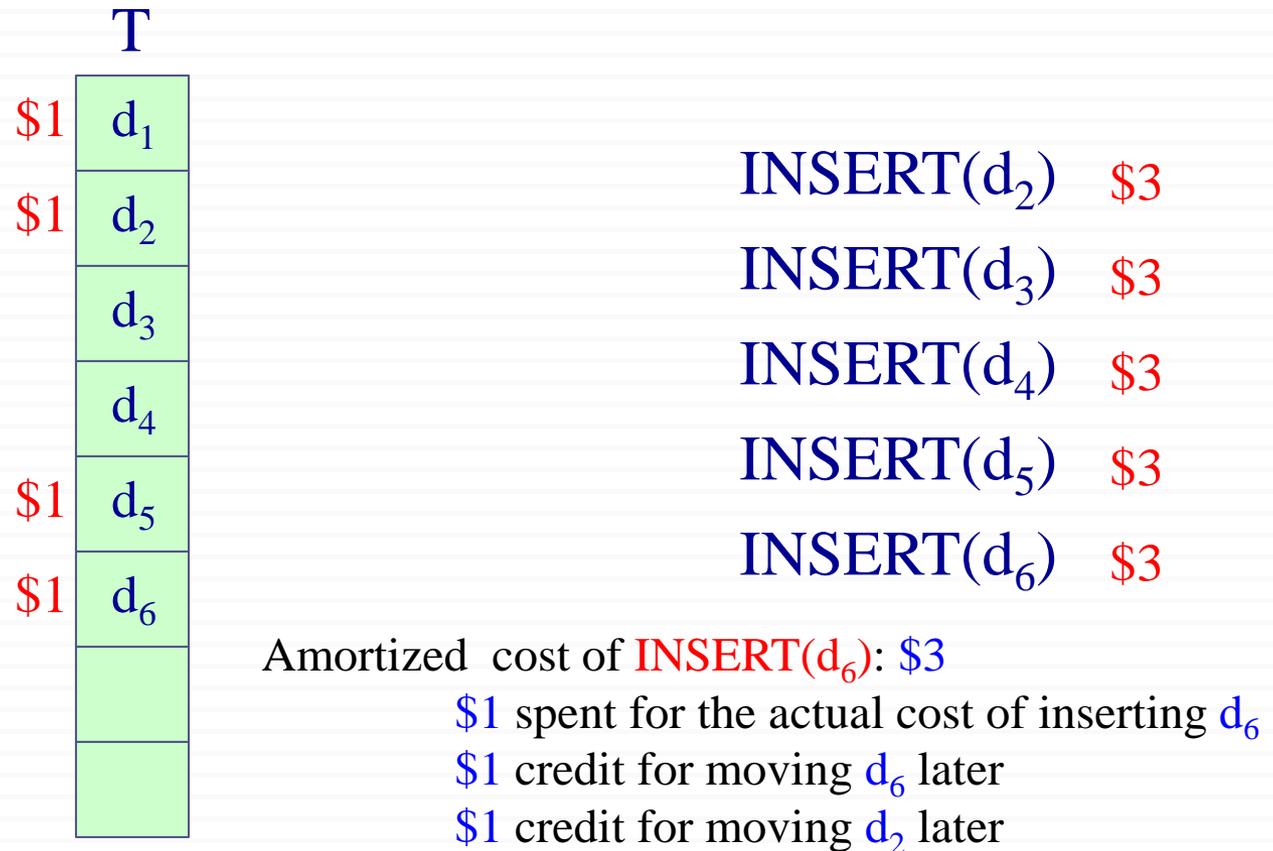


Note: When expansion is needed for the next INSERT operation, we have \$1 stored credit for each item to move it.

Accounting Method Example



Accounting Method Example



Accounting Method Example

Size of the table: M

Immediately after an expansion (just before the insertion)

$\text{num}[T] = M/2$ and $\text{size}[T] = M$ where M is a power of 2.

Table contains **no credits**

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
X	X	X	X	X	X	X	X								

Accounting Method Example

1st insertion

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
X	X	X	X	X	X	X	X	Z							
\$1								\$1							

(c) (b) (a) \$1 for insertion

2nd insertion

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
X	X	X	X	X	X	X	X	Z	Z						
\$1	\$1							\$1	\$1						

Accounting Method Example

$M/2$ th Insertion

1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16
X	X	X	X	X	X	X	X	Z	Z	Z	Z	Z	Z	Z	Z
\$1	\$1	\$1	\$1	\$1	\$1	\$1	\$1	\$1	\$1	\$1	\$1	\$1	\$1	\$1	\$1

Thus, by the time the table contains M items and is full

- each item in the table has \$1 of credit to pay for its move during the next expansion

Amortized Analysis of INSERT: Potential Method

Practical guideline reminder:

Choose a potential function that increases a little after every cheap operation, and decreases a lot after an expensive operation.

- Define a potential function Φ
 - that is 0 immediately after an expansion, and
 - that builds to the table size by the time table becomes full.
- This way the next expansion can be paid for by the potential.

Definition of Potential

- One possible potential function Φ can be defined as:

$$\Phi(T) = 2 * \text{num}[T] - \text{size}[T]$$

where:

$\text{num}[T]$: the # of entries stored in table T

$\text{size}[T]$: the size allocated for table T

- What is the potential value immediately after an expansion?

$$\Phi(T) = 0 \quad \textit{because } \text{size}[T] = 2 * \text{num}[T]$$

- What is the potential value immediately before an expansion?

$$\Phi(T) = \text{num}[T] \quad \textit{because } \text{size}[T] = \text{num}[T]$$

- The initial value of the potential is 0.

Definition of Potential

Potential function: $\Phi(T) = 2 * \text{num}[T] - \text{size}[T]$

□ Can the potential be ever negative?

No, because the table is always at least half full.

i.e. $\text{num}[T] \geq \text{size}[T] / 2$

□ Since $\Phi(T)$ is always nonnegative:

The sum of the amortized costs of n **INSERT** operations is an upper bound on the sum of the actual costs.

Analysis of i -th Table Insert

n_i : **num**[T] after the i -th operation

s_i : **size**[T] after the i -th operation

Φ_i : **Potential** after the i -th operation

Initially we have $n_i = s_i = \Phi_i = 0$

Note that, $n_i = n_{i-1} + 1$ always holds.

Amortized Cost of TABLE-INSERT

Potential function: $\Phi(T) = 2 * \text{num}[T] - \text{size}[T]$

If the i^{th} **TABLE-INSERT** does not trigger an expansion:

Intuitively:

$\text{size}[T]$ remains the same

$\text{num}[T]$ increases by 1

\Rightarrow potential change = 2

amortized cost = real cost + potential change

= 1 + 2 = 3

Amortized Cost of TABLE-INSERT

Potential function: $\Phi(T) = 2 * \text{num}[T] - \text{size}[T]$

If the i^{th} **TABLE-INSERT** does not trigger an expansion:

Formally:

$$s_i = s_{i-1} \text{ and } c_i = 1$$

$$\begin{aligned}\hat{c}_i &= c_i + \phi_i - \phi_{i-1} = 1 + (2n_i - s_i) - (2n_{i-1} - s_{i-1}) \\ &= 1 + (2(n_{i-1} + 1) - s_{i-1}) - (2n_{i-1} - s_{i-1}) \\ &= 1 + 2n_{i-1} + 2 - s_{i-1} - 2n_{i-1} + s_{i-1} = 3\end{aligned}$$

Amortized Cost of TABLE-INSERT

Potential function: $\Phi(T) = 2 * \text{num}[T] - \text{size}[T]$

If the i^{th} **TABLE-INSERT** triggers an expansion:

Intuitively:

$\text{size}[T]$ is doubled, i.e. increases by n_{i-1}

$\text{num}[T]$ increases by 1

\Rightarrow **potential change** = $2 - n_{i-1}$

real cost: $n_{i-1} + 1$ (*copy n_{i-1} entries to new memory
+ insert the new element*)

amortized cost = **real cost** + **potential change**
 $= n_{i-1} + 1 + 2 - n_{i-1} = 3$

Amortized Cost of TABLE-INSERT

Potential function: $\Phi(T) = 2 * \text{num}[T] - \text{size}[T]$

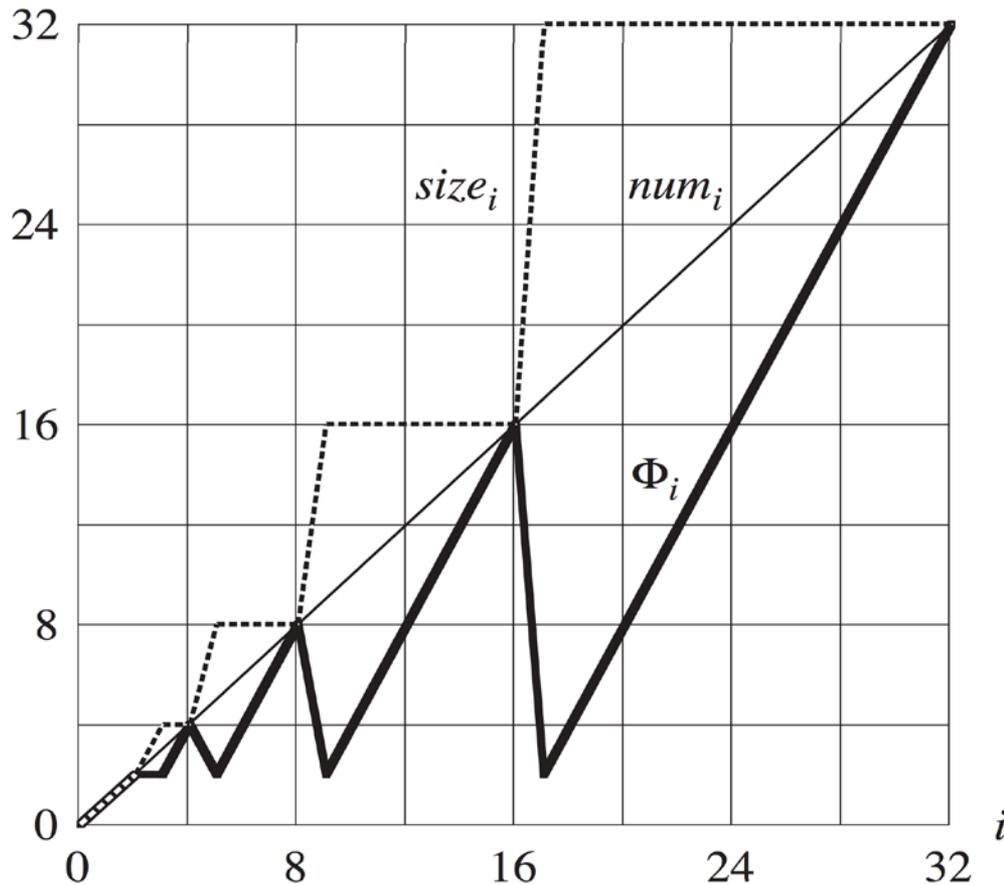
If the i^{th} TABLE-INSERT triggers an expansion:

Formally:

$$n_{i-1} = s_{i-1}; \quad s_i = 2s_{i-1}; \quad c_i = n_i = n_{i-1} + 1$$

$$\begin{aligned} \hat{c}_i &= c_i + \phi_i - \phi_{i-1} = n_i + (2n_i - s_i) - (2n_{i-1} - s_{i-1}) \\ &= (n_{i-1} + 1) + (2(n_{i-1} + 1) + 2s_{i-1}) - (2n_{i-1} - s_{i-1}) \\ &= n_{i-1} + 1 + 2n_{i-1} + 2 - 2n_{i-1} - 2n_{i-1} + n_{i-1} = 3 \end{aligned}$$

A Sequence of TABLE-INSERT Operations



Size of the table is doubled when $i-1$ is a power of 2.

The potential function **increases gradually** after every INSERT that **doesn't require table expansion**.

The potential function **drops to 2** after every INSERT that **requires table expansion**.

Supporting Insertions and Deletions

- So far, we have assumed that we only **INSERT** elements into the table. Now, we want to support **DELETE** operations as well.
- **TABLE-DELETE**: Remove the specified item from the table. Contract the table if needed.
- In table contraction, we want to preserve two properties:
 - ▣ The **load factor** of the table is bounded below by a constant.
 - ▣ **Amortized cost** of an operation is bounded above by a constant.
- As before, we assume that the cost can be measured in terms of elementary insertions and deletions.

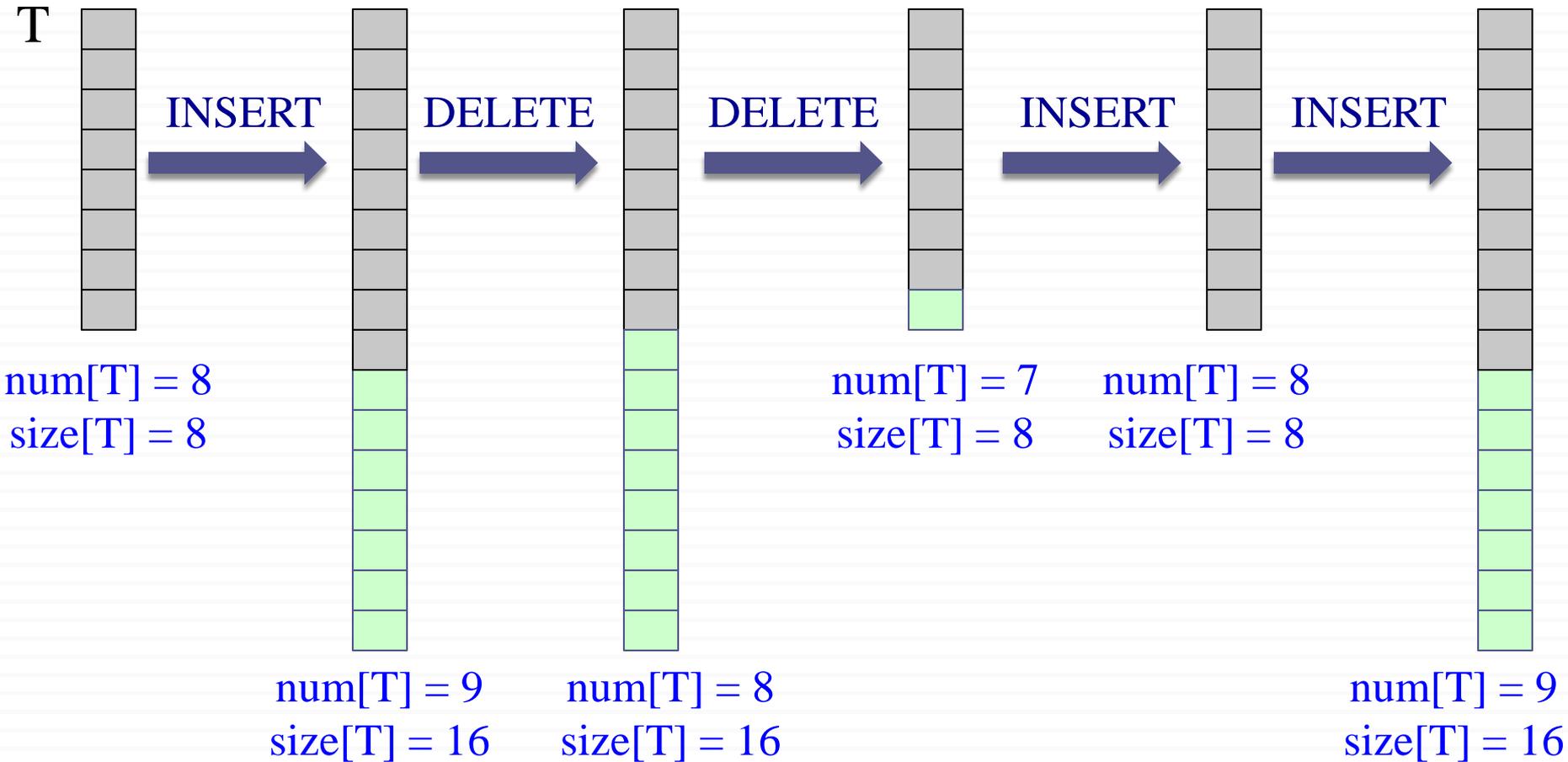
Expansion and Contraction

Load factor reminder: $\alpha(T) = \frac{\text{Number of items stored in the table}}{\text{size(number of slots) of the table}}$

- An intuitive strategy for expansion and contraction:
 - ▣ Double the table size when an item is to be inserted into a full table.
 - ▣ Halve the size when a deletion would cause $\alpha(T) < \frac{1}{2}$

- What is the problem with this strategy?
 - ▣ **Good:** It guarantees $\frac{1}{2} \leq \alpha(T) \leq 1.0$
 - ▣ **Bad:** Amortized cost of an operation can be quite large.

Worst-Case Behavior for $\alpha(T) \geq \frac{1}{2}$



Worst-Case for $\alpha(T) \geq 1/2$

Consider the following **worst case** scenario

- We perform n operations on an **empty table** where n is a power of 2
- First $n/2$ operations are all **insertions**, cost a total of $\Theta(n)$

at the end: we have $\text{num}[T] = \text{size}[T] = n/2$

- Second $n/2$ operations repeat the sequence

I D D I

that is **I D D I I D D I I D D I ...**

Worst-Case for $\alpha(T) \geq 1/2$

Example: $n=16$

$i:$	1	2	...	7	8		9	10	11	12	13	14	15	16
oper:	I	I	...	I	I		I	D	D	I	I	D	D	I
n_i	1	2	...	7	8		9	8	7	8	9	8	7	8
s_i	1	2	...	8	8		16	16	8	8	16	16	8	8
							E		C		E		C	

In the second $n/2$ operations

- The first **INSERT** cause an expansion
- Two further **DELETE**s cause contraction
- Two further **INSERT**s cause expansion ... and so on

Hence there are $n/8$ expansions and $n/8$ contractions

The cost of each expansion and contraction is $\approx n/2$

Worst-Case for $\alpha(T) \geq 1/2$

Thus the total cost of n operations is $\Theta(n^2)$ since

- First $n/2$ operations : $3n/2$
- Second $n/2$ operations : $(n/4)*(n/2)=n^2/8$

The amortized cost of an operation is $\Theta(n)$

The problem with this strategy is

- After an expansion, we do not perform enough deletions to pay for a contraction
- After a contraction, we do not perform enough insertions to pay for an expansion

Improving Amortized Time of Expansion and Contraction

- We saw that if we enforce $\frac{1}{2} \leq \alpha(T) \leq 1$, the amortized time becomes $O(n)$ in the worst case.

- To improve the amortized cost:

Allow $\alpha(T)$ to drop below $\frac{1}{2}$.

- Basic idea:

- Expansion: Double the table size when an item is inserted into a full table (same as before).

- Contraction: Halve the table size when a deletion causes:

$$\alpha(T) < \frac{1}{4}$$

Improving Amortized Time of Expansion and Contraction

- In other words, we enforce: $\frac{1}{4} \leq \alpha(T) \leq 1$

- Intuition:
 - Immediately after an expansion, we have $\alpha(T) = \frac{1}{2}$
 - \Rightarrow At least half of the items in the table must be deleted before a contraction can occur (i.e. when $\alpha(T) < \frac{1}{4}$)

 - Immediately after a contraction, we have $\alpha(T) = \frac{1}{2}$
 - \Rightarrow The number of items in the table must be doubled before an expansion can occur (i.e. when $\alpha(T)=1$).

Potential Method for INSERT & DELETE

□ We want to define the potential function $\Phi(T)$ as follows:

▣ Immediately after an expansion or contraction:

$$\Phi(T) = 0$$

▣ Immediately before an expansion or contraction:

$$\Phi(T) = \text{num}[T]$$

because we need to copy over $\text{num}[T]$ elements, and the cost of expansion or contraction should be paid by the decrease in potential.

Potential Method for INSERT & DELETE

- **Reminder:** Immediately after an expansion or contraction,

$$\alpha(T) = \frac{1}{2}$$

- So, we want to define a potential function $\Phi(T)$ such that:

$\Phi(T)$ **starts at 0** when $\alpha(T) = \frac{1}{2}$

$\Phi(T)$ **gradually increases to** $\text{num}[T]$,

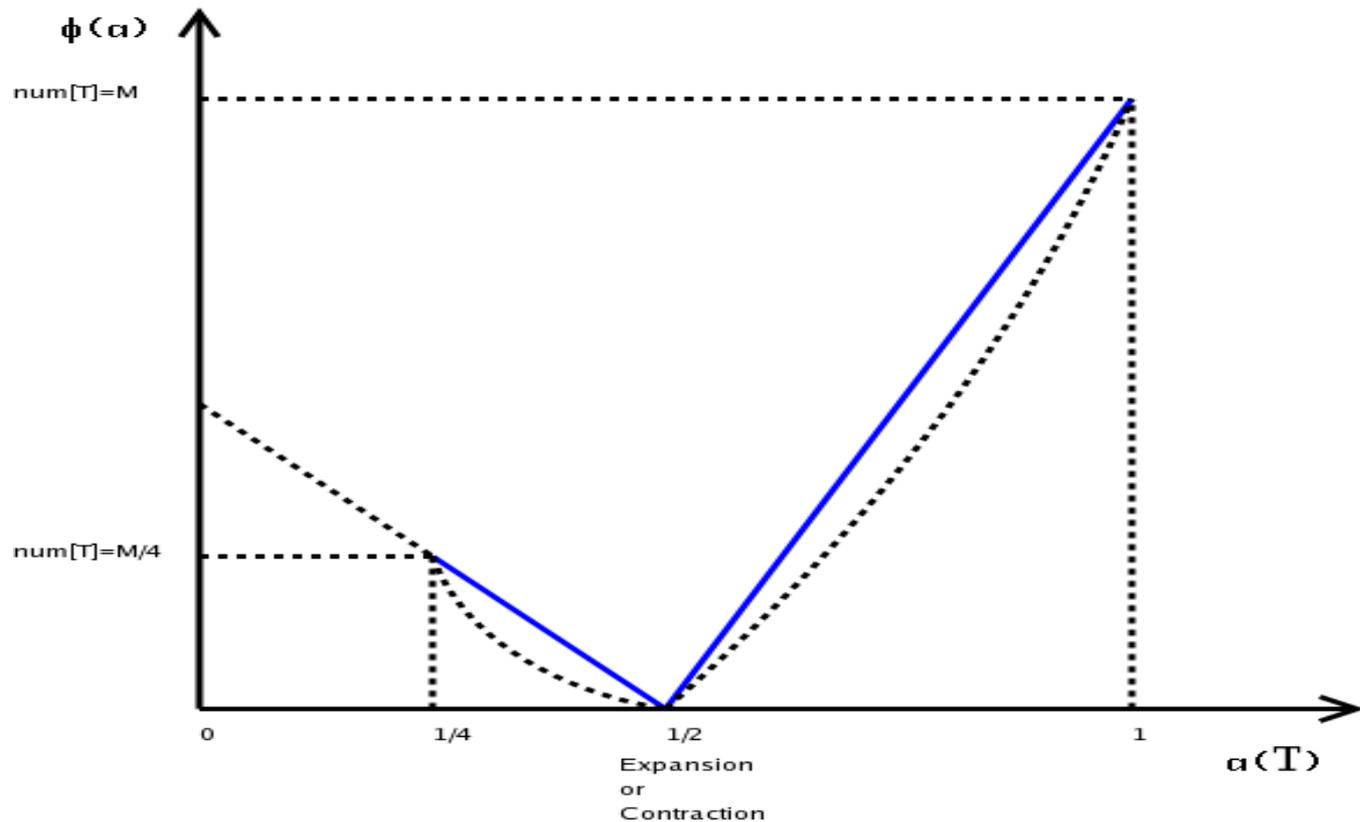
when $\alpha(T)$ increases to 1, or

when $\alpha(T)$ decreases to $\frac{1}{4}$

- This way, the next expansion or contraction can be paid by the decrease in potential.

$\Phi(\alpha)$ w.r.t. $\alpha(T)$

$M = \text{num}[T]$ when an **expansion** or **contraction** occurs



Definition of New Φ

One such Φ is

$$\Phi(T) = \begin{cases} 2num[T] - size[T] & \text{if } \alpha(T) \geq \frac{1}{2} \\ \frac{size[T]}{2} - num[T] & \text{if } \alpha(T) < \frac{1}{2} \end{cases}$$

or

$$\Phi(T) = \begin{cases} num[T](2 - 1/\alpha) & \text{if } \alpha(T) \geq \frac{1}{2} \\ num[T](1/2\alpha - 1) & \text{if } \alpha(T) < \frac{1}{2} \end{cases}$$

Description of New Φ

$$\Phi(T) = \begin{cases} 2num[T] - size[T] & \text{if } \alpha(T) \geq \frac{1}{2} \\ \frac{size[T]}{2} - num[T] & \text{if } \alpha(T) < \frac{1}{2} \end{cases}$$

$$\alpha = \frac{num[T]}{size[T]}$$

- ✓ $\Phi = 0$ **when** $\alpha = 1/2$
- ✓ $\Phi = num[T]$ **when** $\alpha = 1/4$
- ✓ $\Phi = num[T]$ **when** $\alpha = 1$
- ✓ $\Phi = 0$ **when** the table is empty
($num[T] = size[T] = 0, \alpha(T) = 0$)
- ✓ Φ is always nonnegative

Amortized Analysis

We need to analyze the operations:

TABLE-INSERT and **TABLE-DELETE**

Notations:

c_i : Actual cost of the i^{th} operation

\hat{c}_i : Amortized cost of the i^{th} operation

Φ_i : Potential $\Phi(T)$ after the i^{th} operation

n_i : Number of elements $\text{num}[T]$ after the i^{th} operation

s_i : Table size $\text{size}[T]$ after the i^{th} operation

α_i : Load factor $\alpha(T)$ after the i^{th} operation

Amortized Analysis: Table Insert – Case 1

- There is no possibility of contraction in any case.
- In all cases: $n_i = n_{i-1} + 1$

Case 1: $\alpha_{i-1} \geq \frac{1}{2}$

Analysis is identical to the one we did before for only TABLE-INSERT operation.

\Rightarrow Amortized cost $\hat{c}_i = 3$ whether the table expands or not.

Amortized Analysis: Table Insert – Case 2

$$\Phi(T) = \begin{cases} 2num[T] - size[T] & \text{if } \alpha(T) \geq \frac{1}{2} \\ \frac{size[T]}{2} - num[T] & \text{if } \alpha(T) < \frac{1}{2} \end{cases}$$

Case 2: $\alpha_{i-1} < \frac{1}{2}$ and $\alpha_i < \frac{1}{2}$

There is no possibility of expansion.

Intuitively:

Potential change: -1

Real cost: 1

Amortized cost = 1 - 1 = 0

Amortized Analysis: Table Insert – Case 2

$$\Phi(T) = \begin{cases} 2\text{num}[T] - \text{size}[T] & \text{if } \alpha(T) \geq \frac{1}{2} \\ \frac{\text{size}[T]}{2} - \text{num}[T] & \text{if } \alpha(T) < \frac{1}{2} \end{cases}$$

Case 2: $\alpha_{i-1} < 1/2$ and $\alpha_i < 1/2$

There is no possibility of expansion.

Formally: $c_i = 1$; $s_i = s_{i-1}$; $n_i = n_{i-1} + 1$

$$\begin{aligned} \hat{c}_i &= c_i + \Phi_i - \Phi_{i-1} = 1 + (s_i / 2 - n_i) - (s_{i-1} / 2 - n_{i-1}) \\ &= 1 + \frac{s_i}{2} - n_i - \frac{s_i}{2} + (n_i - 1) = 0 \end{aligned}$$

Amortized Analysis: Table Insert – Case 3

$$\Phi(T) = \begin{cases} 2\text{num}[T] - \text{size}[T] & \text{if } \alpha(T) \geq \frac{1}{2} \\ \frac{\text{size}[T]}{2} - \text{num}[T] & \text{if } \alpha(T) < \frac{1}{2} \end{cases}$$

Case 3: $\alpha_{i-1} < 1/2$ and $\alpha_i \geq 1/2$ (which means $\alpha_i = 1/2$ because $\text{size}[T]$ is even)

There is no possibility of expansion.

Intuitively: $n_i = s_i/2$; $n_{i-1} = s_i/2 - 1$

Old potential: 1

New potential: 0

Real cost: 1

Amortized cost = 1 - 1 = 0

Amortized Analysis: Table Insert – Case 3

$$\Phi(T) = \begin{cases} 2\text{num}[T] - \text{size}[T] & \text{if } \alpha(T) \geq \frac{1}{2} \\ \frac{\text{size}[T]}{2} - \text{num}[T] & \text{if } \alpha(T) < \frac{1}{2} \end{cases}$$

Case 3: $\alpha_{i-1} < 1/2$ and $\alpha_i \geq 1/2$ (which means $\alpha_i = 1/2$ because $\text{size}[T]$ is even)

There is no possibility of expansion.

Formally: $c_i = 1$; $n_i = s_i/2$; $n_{i-1} = s_i/2 - 1$; $s_i = s_{i-1}$

$$\begin{aligned} \hat{c}_i &= c_i + \Phi_i - \Phi_{i-1} = 1 + (2n_i - s_i) - (s_{i-1}/2 - n_{i-1}) \\ &= 1 + (2(s_i/2) - s_i) - (s_i/2 - (s_i/2 - 1)) \\ &= 0 \end{aligned}$$

Amortized Analysis: Table Insert - Summary

Case 1: $\alpha_{i-1} \geq \frac{1}{2}$

Amortized cost of **TABLE-INSERT** = 3

Case 2: $\alpha_{i-1} < \frac{1}{2}$ and $\alpha_i < \frac{1}{2}$

Amortized cost of **TABLE-INSERT** = 0

Case 3: $\alpha_{i-1} < \frac{1}{2}$ and $\alpha_i \geq \frac{1}{2}$

Amortized cost of **TABLE-INSERT** = 0

So, the amortized cost of **TABLE-INSERT** is at most 3

Table Delete

$$n_i = n_{i-1} - 1 \Rightarrow n_{i-1} = n_i + 1$$

Table **expansion** cannot occur.

- $\alpha_{i-1} \leq 1/2$ and $1/4 \leq \alpha_i < 1/2$ (It does not trigger a **contraction**)

$$s_i = s_{i-1} \text{ and } c_i = 1 \text{ and } \alpha_i < 1/2$$

$$\begin{aligned} \hat{c}_i &= c_i + \Phi_i - \Phi_{i-1} = 1 + (s_i / 2 - n_i) - (s_{i-1} / 2 - n_{i-1}) \\ &= 1 + s_i / 2 - n_i - s_i / 2 + (n_i + 1) = 2 \end{aligned}$$

Table Delete

- $\alpha_{i-1} = 1/4$ (It does **trigger** a **contraction**)

$$s_i = s_{i-1}/2 ; n_i = s_{i-1}/2; \text{ and } c_i = n_i + 1$$

$$\begin{aligned}\hat{c}_i &= c_i + \Phi_i - \Phi_{i-1} = (n_i + 1) + (s_i / 2 - n_i) - (s_{i-1} / 2 - n_{i-1}) \\ &= n_i + 1 + s_i / 2 - n_i - s_i + s_i / 2 = 1\end{aligned}$$

- $\alpha_{i-1} > 1/2$ ($\alpha_i \geq 1/2$)

Contraction cannot occur ($c_i=1 ; s_i = s_{i-1}$)

$$\begin{aligned}\hat{c}_i &= c_i + \Phi_i - \Phi_{i-1} = 1 + (2n_i - s_i) - (2n_{i-1} - s_{i-1}) \\ &= 1 + 2n_i - s_i - 2(n_i + 1) + s_i = -1\end{aligned}$$

Table Delete

- $\alpha_{i-1} = 1/2$ ($\alpha_i < 1/2$)

Contraction cannot occur

$$c_i = 1 ; s_i = s_{i-1} ; n_i = s_{i-1}/2; \text{ and } \Phi_{i-1}=0)$$

$$\begin{aligned}\hat{c}_i &= c_i + \Phi_i - \Phi_{i-1} = 1 + (s_i / 2 - n_i) - 0 \\ &= 1 + s_i / 2 - n_i \quad \text{but} \quad n_{i+1} = s_i / 2 \\ &= 1 + (n_i + 1) - n_i = 2\end{aligned}$$

Table Delete

Thus, the amortized cost of a **TABLE-DELETE** operation is at most 2

Since the amortized cost of each operation is bounded above by a constant

The actual time for any sequence of n operations on a Dynamic Table is $O(n)$