

ASPECT-ORIENTED SIMULATOR FOR DISTRIBUTED MST CONSTRUCTION ON WIRELESS NETWORKS

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Course Project

Outline

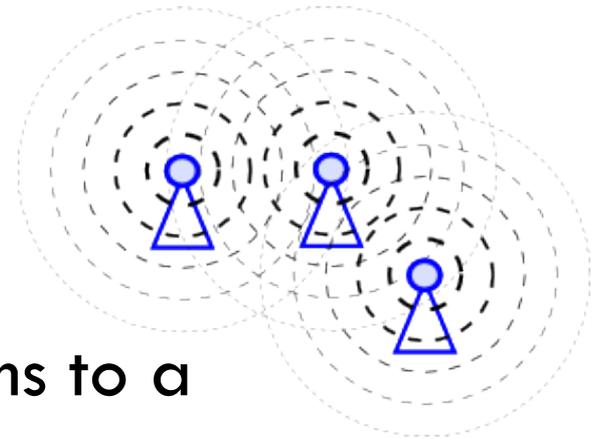
- Introduction
- Background
 - ▣ Wireless Networks
 - ▣ Simulators for Wireless Environments
 - ▣ Distributed Algorithms
 - ▣ MST Problem
- Legacy Work
- Problem Statement
- Object Oriented Design
- Identified Aspects & Aspect Oriented Programming
- Conclusion

Introduction

- Wireless networks are integral parts of our lives
- Simulating the behavior of a network is a key concern
 - Real
 - Difficult to deploy
 - Costly
 - Restricted test conditions
 - More reliable
 - Simulation
 - Easy configuration
 - Cheaper
 - Broader test cases
- Distributed algorithms are very important to wireless networks
- AOSD can be used to develop elegant solutions to the problems of network simulators

Wireless Networks

- ❑ Covers our daily life inevitably
 - ❑ Mobile phones
 - ❑ Wireless internet
- ❑ Benefit from distributed algorithms to a broader extent
- ❑ Time consuming and costly to deploy
- ❑ All nodes cannot be connected directly



Distributed Algorithms

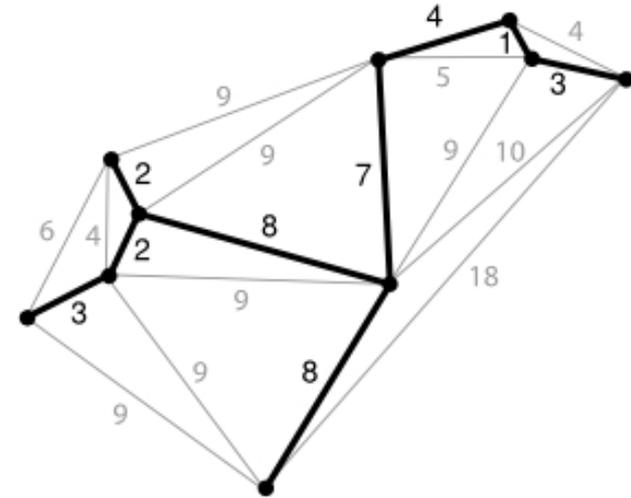
- Multiple hosts run an algorithm collectively to accomplish a goal
- Harder to design and implement than their centralized counterparts
 - Synchronization
 - Stability
 - Communication
 - Even harder if all nodes are not directly connected

Simulators for Wireless Env.

- Deploying wireless networks is time consuming and costly
 - ▣ Deploying a network which is not suitable for the needs of the situation is out of question
- Simulating the network prior to actually building it is a key concern
 - ▣ Understand the behavior of the network
 - ▣ Brings diversity to test cases
 - ▣ Can test marginal cases which are hard to reproduce

Minimum Spanning Tree

- Spanning tree: A tree that includes all nodes of a network
- Minimum spanning tree: The spanning tree on which the total weights of the tree edges are the minimum
- A fundamental problem in the fields of Graph Theory and Computer Networks
- Centralized algorithms: Kruskal's & Prim's Algorithms
- Distributed algorithm: GHS Algorithm
 - ▣ Proposed by Gallager, Humblet and Spira
 - ▣ Assumes Synchronized Environment



Legacy Work

- In a previous study, a distributed program that builds an MST for a network is implemented
 - ▣ First, creates network topology and sets up connections
 - ▣ Then, builds the MST in $O(\log n)$ rounds
 - ▣ Finally, broadcasts given messages
 - ▣ Text based outputs

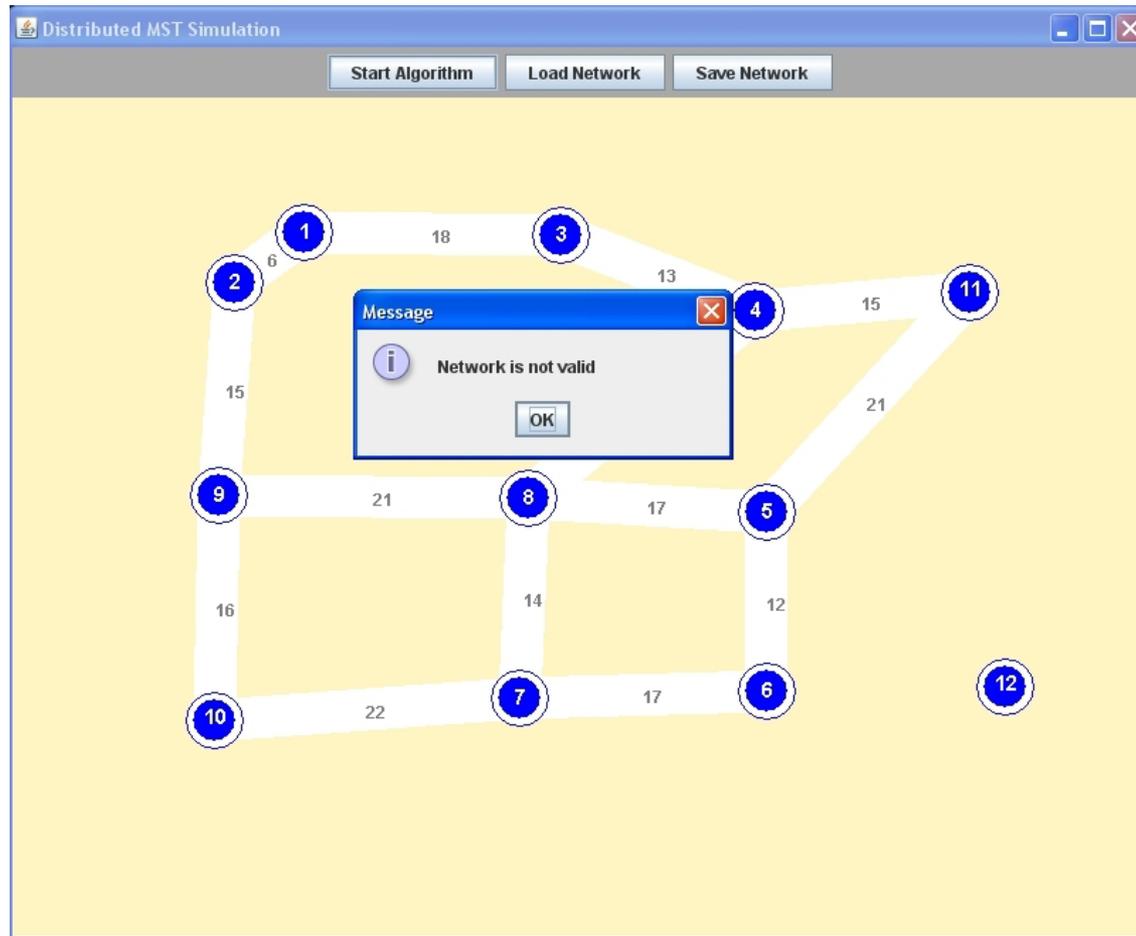
Problem Statement

- Inspired by this program, we designed and implemented:
 - ▣ An aspect oriented simulator for distributed MST construction on wireless networks
 - ▣ In a centralized manner
 - ▣ With better user interaction

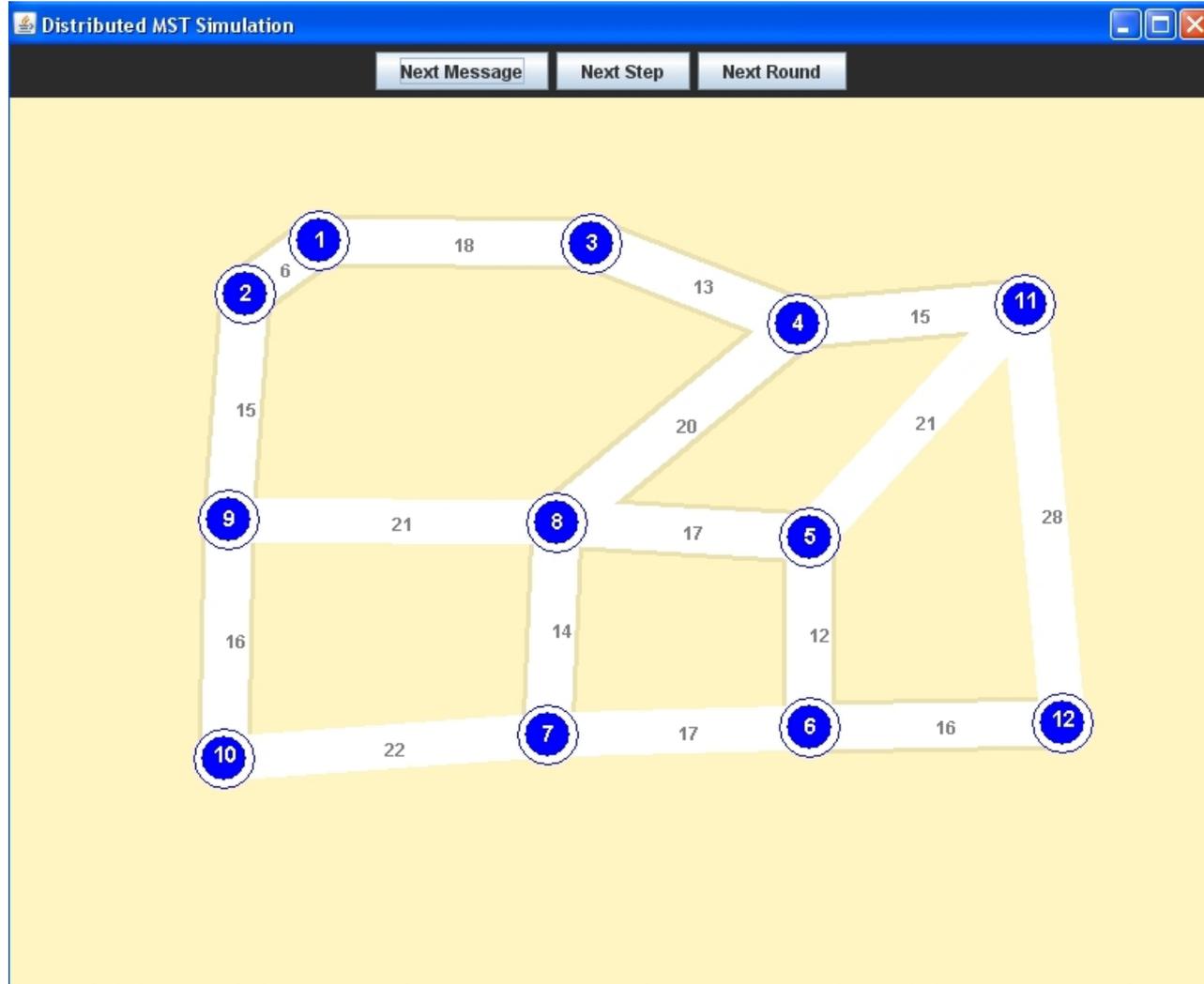
Requirements Analysis

- Synchronization
 - ▣ Algorithm stability
- Step-by-step observation of algorithm
- Central visualization of different components
- Nodes oblivious to the overall structure
 - ▣ Preserve distributiveness

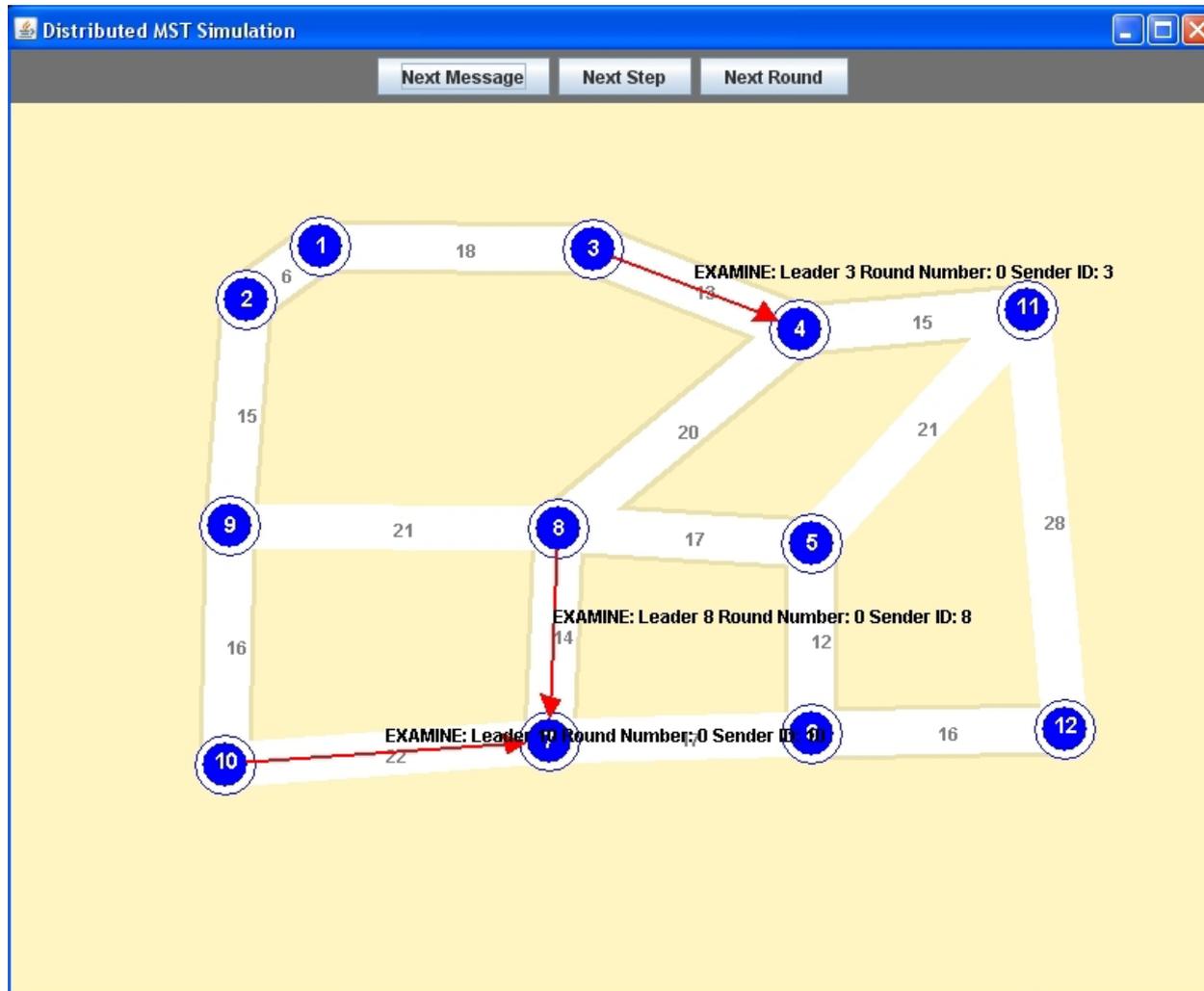
User Interface Prototypes



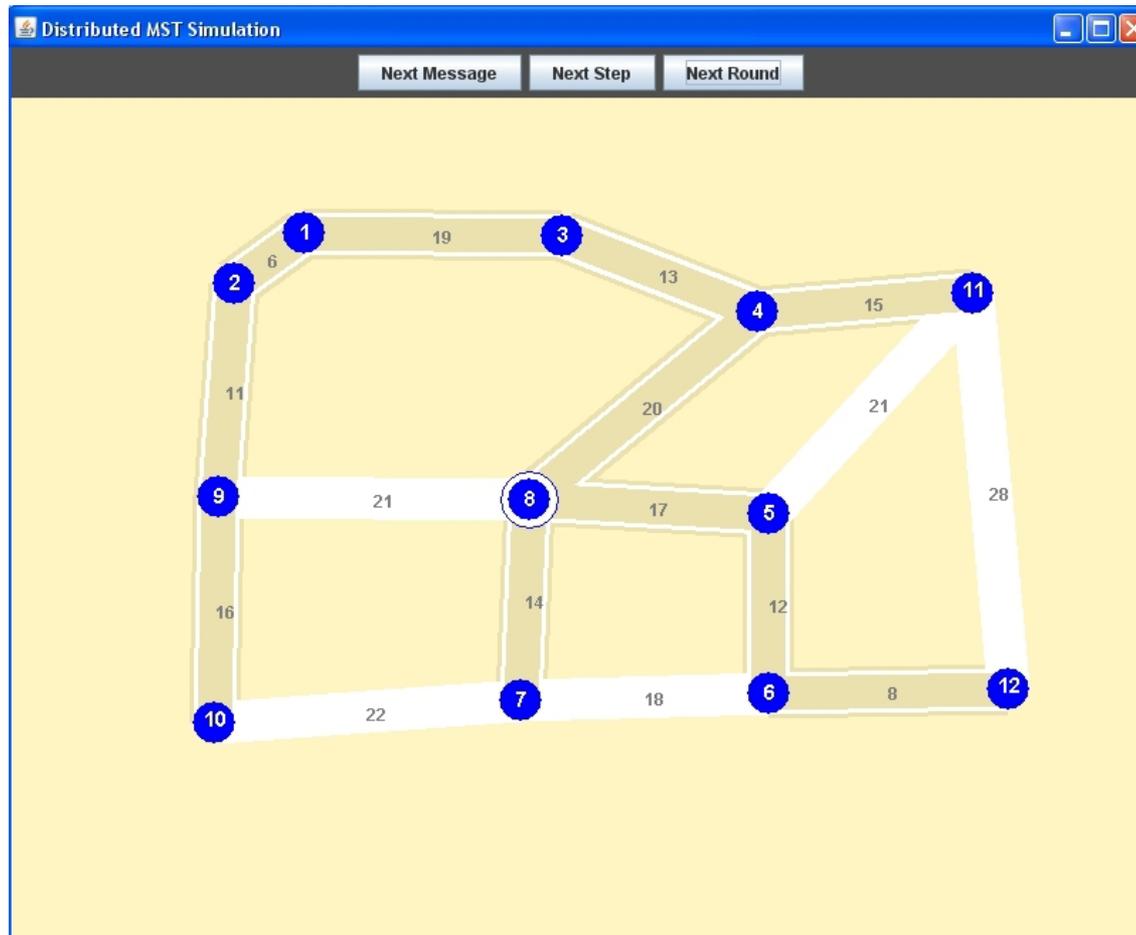
User Interface Prototypes (2)



User Interface Prototypes (3)



User Interface Prototypes (5)



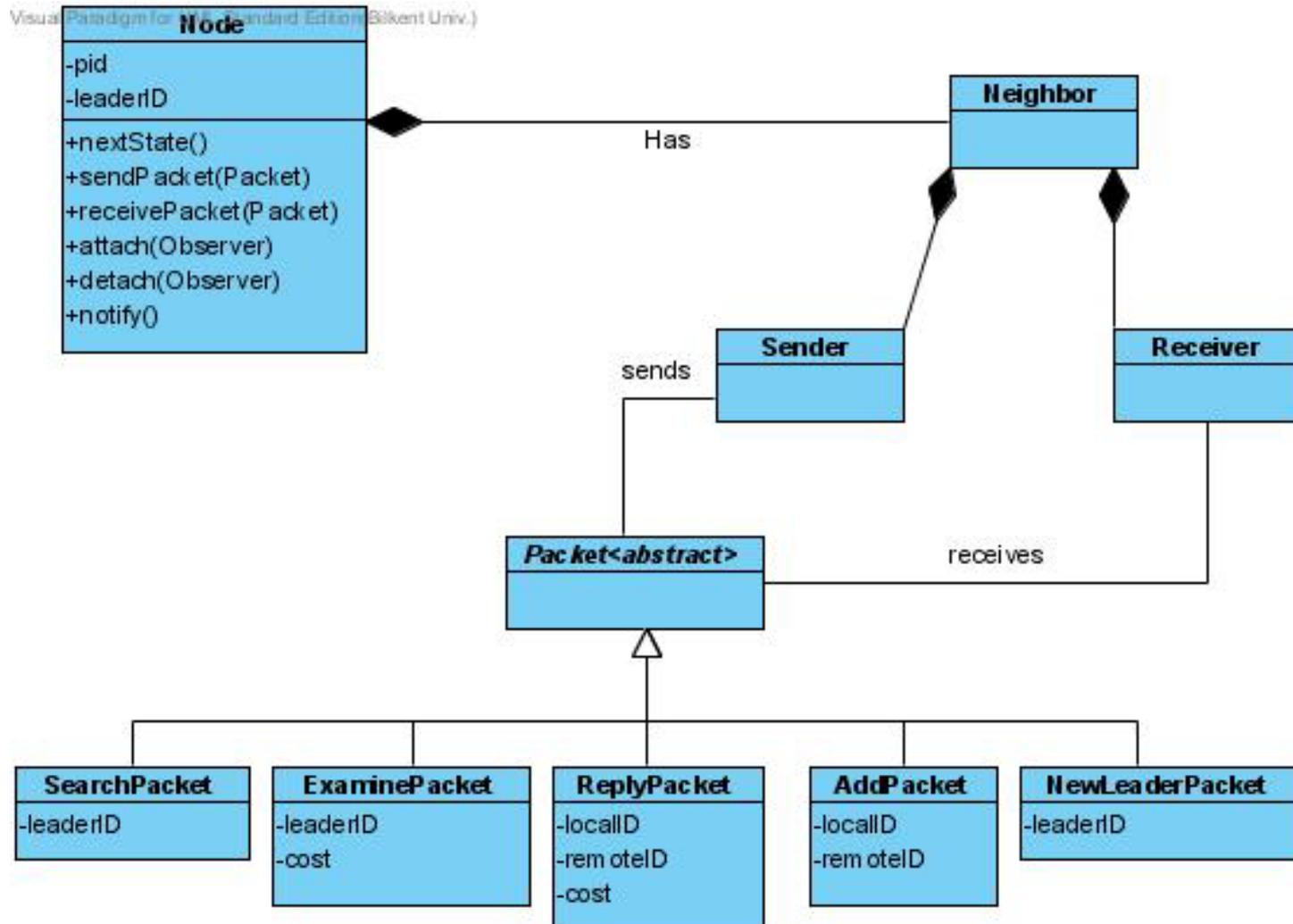
Our Approach

- Apply Object-Oriented Design
 - ▣ Use OO Design Patterns
- Identify the Crosscutting Concerns
- Define the Necessary Aspects
- Implement Aspects using AOP

Object Oriented Design

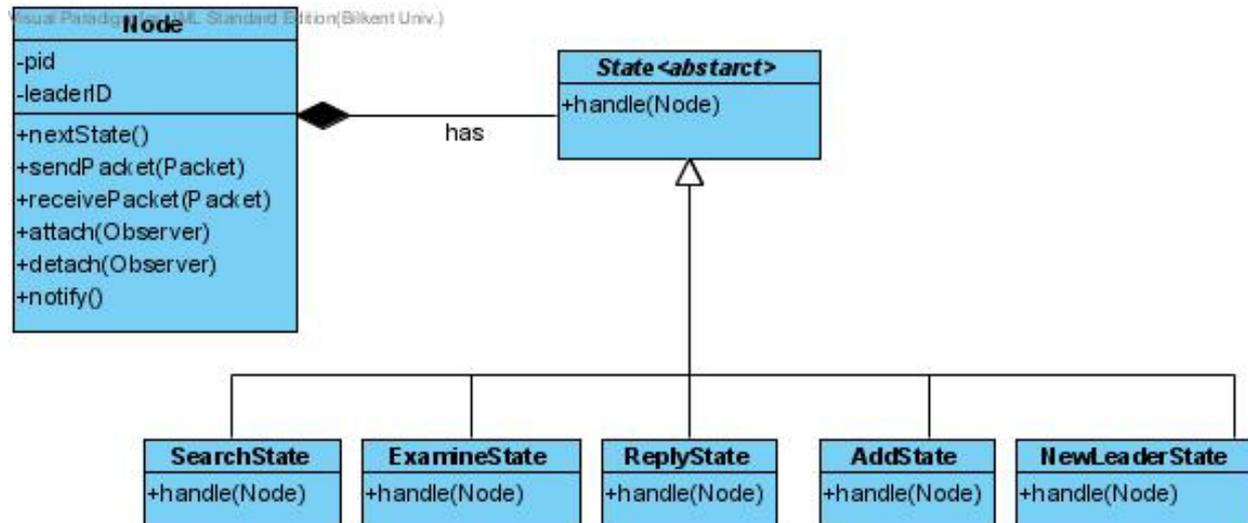
- The network is mainly represented by Node, Neighbor and Packet objects
- Includes 17 classes
- State and Observer patterns are utilized
 - ▣ State pattern is used for processing incoming/outgoing packets according to the current state
 - ▣ Observer pattern is used for updating the user interface

Object Oriented Design (2)

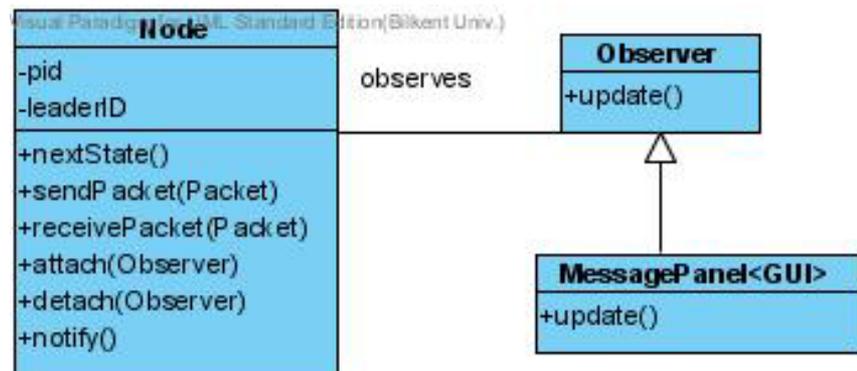


Object Oriented Design Patterns

□ State pattern



□ Observer Pattern



Crosscutting Concerns

- Synchronization
 - ▣ Required to make all state transitions at the same time
- Validation
 - ▣ Validates input and output
- Display
 - ▣ Enables the usage of different views according to attribute values
- Control
 - ▣ Required to view intermediate steps

Synchronization Aspect

- GHS algorithm assumes an already synchronized environment
 - ▣ Synchronization should be checked at multiple points
 - ▣ Providing synchronization inside the algorithm causes tangling
- Synchronization aspect solves the problem
 - ▣ pointcut nextState: call(* Node.nextState(..))
 - ▣ before nextState()
 - set *Node i* as ready for next state
 - suspend *Node i* until all nodes become ready for next state

Validation Aspect

- There are two points to validate:
 - ▣ Input validation
 - Separate this concern from main algorithm
 - Avoid scattering
 - ▣ Output validation
 - Used for development
 - Needs to be removed after development stage

Validation Aspect (2)

- Input validation (around advice)
- Around program execution
 - check if input is correct or not
 - run program if it is correct
 - warn user and terminate otherwise

Validation Aspect (3)

- Output validation
- After program finishes
 - check if MST is constructed correctly
 - warn developer if it is not

Display Aspect

- Display concern causes tangling
 - ▣ Network elements should not be responsible for visualizing themselves
- Network visualizer
 - ▣ Traces the changes in the network
 - ▣ Visualizes them

Display Aspect (2)

□ Catch communication (messages transmitted among nodes)

```
after(Neighbor n, Packet p) returning() : target(n) && args(p) &&
    (call( * Neighbor.sendMessage( Packet ) ) ) {
    NetworkVisualizer.getInstance().sendMessage(n.getNodeId(),(int)(n.getPid()), p);
    NetworkVisualizer.getInstance().getVisualizer().repaint();
}
```

□ Catch leader changes

```
pointcut newLeader( ) : set( int Node.leaderID );
after( Node n ) : target(n) && newLeader() {
    NetworkVisualizer.getInstance().setLeaderMessage(n.getPid(),n.getLeaderID());
}
```

□ Catch addition of new MST edges

```
after(int node1, int node2,int senderId ) : args(node1,node2,senderId) &&
    call(ADD_MWOE.new(..)) {
    NetworkVisualizer.getInstance().addMSTedge( node1, node2 );
}
```

Control Aspect

- Controlled execution of the algorithm
 - ▣ User determines the continuation at control points
 - Stop at each message
 - Stop at each state
 - Stop at each round
 - ▣ Oblivious to the algorithm
- Aspect avoids scattered code
 - ▣ Check for user input at each control point >> scattering
 - ▣ Separate the control concern from the main module

Control Aspect (2)

- Control Aspect (pseudocode)
 - After a button is clicked
 - If the button is “next message” button
 - Send one message
 - Stop and visualize
 - If the button is “next step” button
 - Continue until all nodes finish this step (finished nodes waits)
 - Stop and visualize
 - If the button is “next round” button
 - Continue until all nodes pass to the next round (passed nodes waits)
 - Stop and visualize

Advantages of AOSD

- Avoid crosscutting concerns by separating
 - ▣ Synchronization,
 - ▣ Validation,
 - ▣ Display,
 - ▣ Control
 - ▣ Concerns from the distributed algorithm design
- Provide a synchronized network environment
- Easier to extend & modify the visualization component
 - ▣ Oblivious to the distributed algorithm
- Control and validation aspects ease debugging the algorithm
- Easier to develop distributed algorithms
 - ▣ Do not deal with extra concerns other than algorithm design

Conclusion

- Implemented a simulator for distributed MST construction on wireless networks
 - OOSD
 - AOSD
- Handled Croscutting Concerns with AOP
 - Synchronization
 - Validation
 - Control
 - Display

End of Presentation



Thank you

Questions?