

# Sorting

CS 202 – Fundamental Structures of  
Computer Science II

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Computer Engineering Department

# Sorting

- Sorting is ordering a set of elements in increasing or decreasing order.
- We will assume that
  - Elements are comparable
  - They are kept in an array
  - Each cell of the array keep one element
  - For simplicity the elements are integers. But the same methods are valid for any type of element that can be ordered.
  - We will express the number of element to be sorted as  $N$ .

## Sorting

- There are various sorting algorithms
  - Easy algorithms:  $O(N^2)$  running time
    - Insertion sort, etc.
  - Very easy to implement ones:  $o(N^2)$ 
    - Efficient in practice
  - More complicated ones
    - Running time of  $O(N \log N)$
    - Such as Quick Sort, Merge Sort, etc.
- A general purpose sorting algorithm requires  $\Omega(N \log N)$  comparisons.

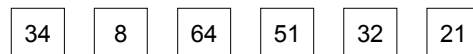
## Sorting

- The data to be sorted can fit in memory;
  - We will first see the algorithms for this case.
- The data can also be residing in disk and algorithm can be run over disk
  - This is called **external sorting**.

## Insertion Sort

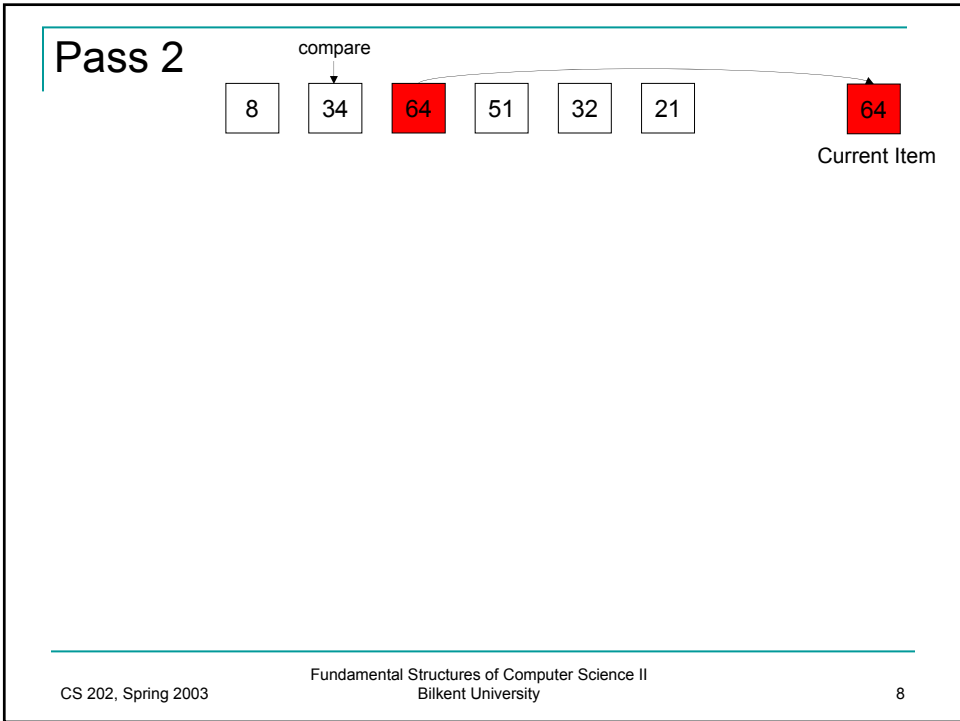
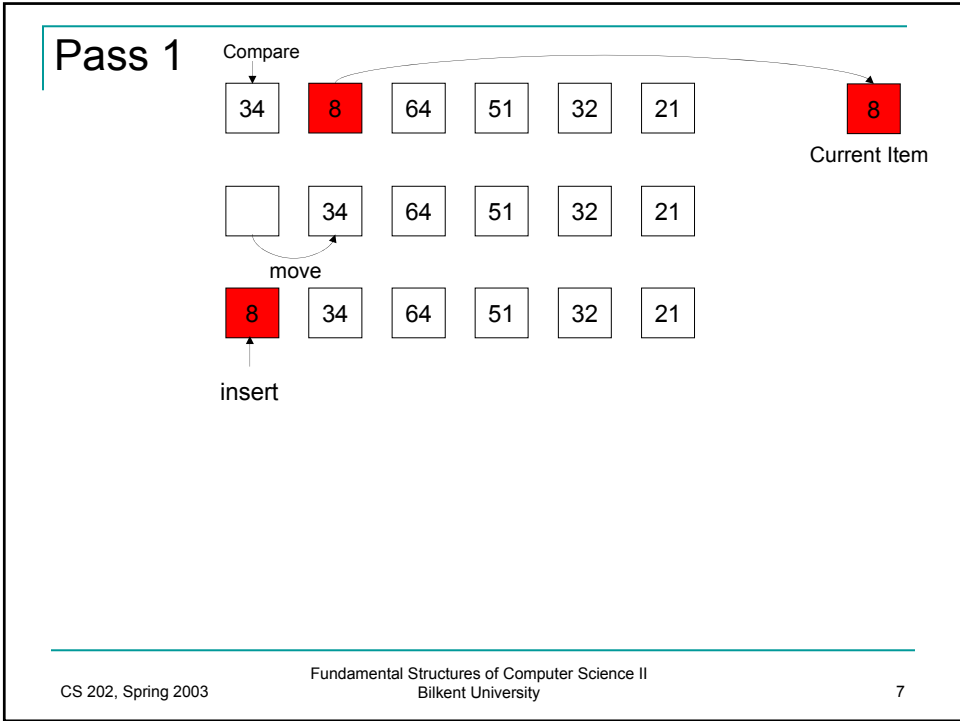
- A simple algorithm
- Requires  $N-1$  passes over the array to be sorted (of size  $N$ ).
- For passes  $p=1$  to  $N$ 
  - Ensures that the elements in positions  $0$  through  $p$  are in sorted order.

## Example

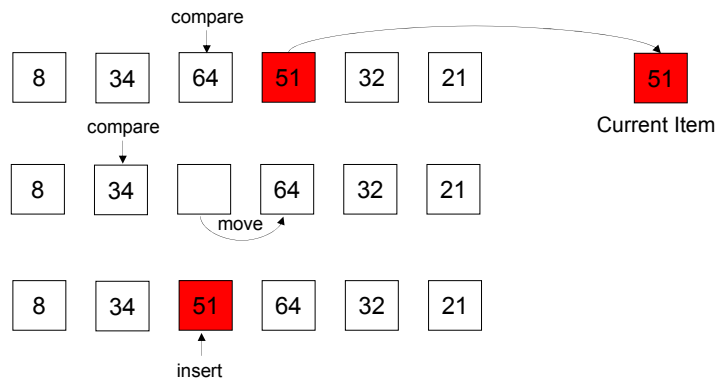


Array to be sorted.

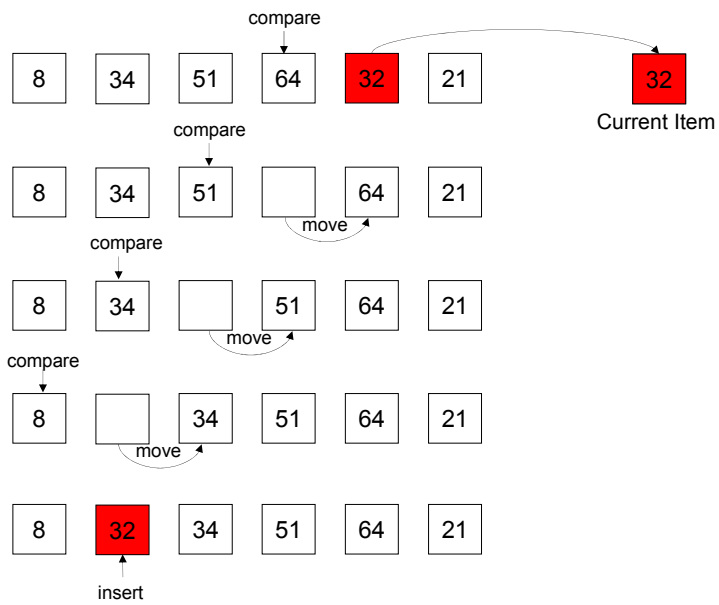
$N = 6$



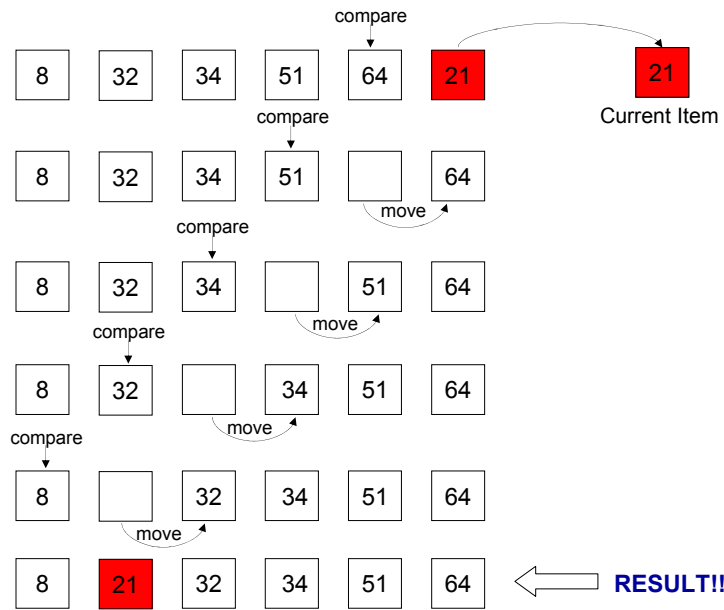
### Pass 3



### Pass 4



## Pass 5



## Pseudo-Code

```
void
insertionSort(vector<int> &a)
{
    int j;

    for ( int p = 1; p < a.size(); ++p )
    {
        int tmp = a[p];
        test → for (j=p; j > 0 && tmp < a[j-1]; j--) /* compare */
                a[j] = a[j-1]; /*move */
                a[j] = tmp; /* insert */
    }
}
```

## Analysis of Insertion Sort

- The test the line shown in the previous slide is done at most:
  - $p+1$  times for each value of  $p$ .

$$\sum_{i=2}^N i = 2 + 3 + 4 + \dots + N = \Theta(N^2)$$

## Lower bound for simple sorting algorithms

- Simple sorting algorithms are the ones that make swaps of adjacent items.
  - Insertion sort
  - Bubble sort
  - Selection sort
- *Inversion* definition:
  - An inversion in an array of numbers is any ordered pair  $(i,j)$  having the property that  $i < j$  but  $a[i] > a[j]$

## Inversion

- Example:
  - Array items: 34 8 64 51 32 21
  - Inversions:
    - (34,8), (34,32), (34,21), (64,51), (64,32), (64,21), (51,32), (51,21), and (32,21).
    - We have total of 9 inversions.
  - *Each inversion requires a swap* in insertion sort to order the list.
  - A sorted array has no inversions.
  - Running time =  $O(I + N)$ , where  $I$  is number of inversions.

## Inversion

- Compute the average number of inversions in an array.
  - Assume no duplicates in the array (or list).
  - Assume there are  $N$  elements in range  $[1, N]$ .
- Then input to the sorting algorithms is a permutation of these  $N$  distinct elements.



## Theorem

- **Theorem:** *The average number of inversions in an array of  $N$  distinct elements is  $N(N-1)/4$ .*
- **Proof:**
  - For any list of items,  $L$ , consider the list in reverse order  $L_r$ .
    - $L = 34$  8 64 51 32 21
    - $L_r = 21$  32 51 64 8 34
  - Consider any pair  $(x,y)$  in list  $L$ , with  $x < y$ .
  - The pair  $(x,y)$  is certainly an inversion in one of the lists  $L$  and  $L_r$

## Theorem

- **Proof continued**
  - The total number of these pairs (which are inversions) in a list  $L$  and its reverse  $L_r$  is  $N(N-1)/2$ .
  - Therefore, an average list  $L$  has half of this amount, which is  $N(N-1)/4$ .

## Shell Sort

- Invented by Donald Shell.
- Also referred to as *diminishing increment sort*.
- Shell sort uses a sequence  $h_1, h_2, \dots, h_t$ , called the increment sequence.
  - $h_1$  must be 1.
  - Any sequence will do.

## Shell Sort

- It is executed in phase.
  - One phase for each  $h_k$
- After a phase where increment were  $h_k$ 
  - For every  $i$ ,  $a[i] \leq a[i+h_k]$ .
    - This means all elements spaced  $h_k$  apart are sorted.
    - The input is then said to be  $h_k$  sorted.
- An  $h_k$  sorted input, which is then  $h_{k-1}$  sorted, is still  $h_k$  sorted.

## Shell Sort

Original List	81	94	11	96	12	35	17	95	28	58	41	75	15
After 5-sort	37	17	11	28	12	41	75	15	96	58	81	94	95
After 3-sort	28	12	11	35	15	41	58	17	94	75	81	96	95
After 1-sort	11	12	15	17	28	35	41	58	75	81	94	95	96

## Shellsort Algorithm

```
void shellsort (vector<int> &a)
{
    int j, i;
    int gap;

    for (gap = a.size() / 2; gap > 0; gap /= 2)
    {
        for (i=gap; i < a.size(); i++)
        {
            int tmp = a[i];
            for (j=i; j>=gap && tmp < a[j-gap]; j -= gap)
                a[j] = a[j-gap];
            a[j] = tmp;
        }
    }
}
```

## Choosing Increment Sequence

$$h_t = \left\lfloor \frac{N}{2} \right\rfloor$$

$$h_k = \left\lfloor \frac{h_{k+1}}{2} \right\rfloor$$

$$h_1 = 1$$

Suggested by Donald Shell  
N: the number of items to sort.

## Worst Case Analysis of Shell Sort

- Theorem:
  - *The worst case running time of Shell sort using Shell's increments is  $\Theta(N^2)$ .*
- .
  - We will show a *lower bound* for the running time.
  - We will also show an *upper bound* for the running time.

## Lower bound

- We will show that there exists an input that causes the algorithm to run in  $\Omega(N^2)$  time.
  - Assume  $N$  is power of 2.
  - Assume these  $N$  elements is stored in an array indexed from 1 to  $N$ .
  - Assume that
    - odd index values contain the  $N/2$  largest elements and
    - even index values contain the  $N/2$  smallest element.
- 1,9,2,10,3,11,4,12,5,13,6,14,7,15,8,16 is such as sequence.

## Lower bound

- Shell's increments are:
  - 1, 2, 3, ...,  $N/2$
- All increments except the last one are even.
- When we come to the last pass,
  - all largest items are in even positions and
  - all smallest items are in odd positions.
- Snapshot before last pass
  - 1,9,2,10,3,11,4,12,5,13,6,14,7,15,8,16

## Lower bound

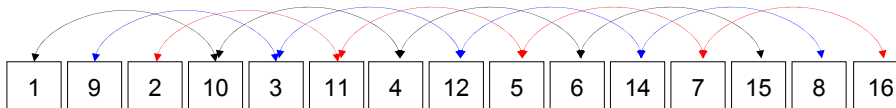
- The  $i^{\text{th}}$  smallest number is at position  $2i-1$  before the last pass.
- Restoring the  $i^{\text{th}}$  element to its correct position requires:
  - $2i-1-i = i-1$  moves towards the beginning of the array (each move make the item go one cell left).
- Therefore to place  $N/2$  smallest elements to their correct positions require amount of work in the order:

$$\sum_{i=1}^{N/2} i-1 = \Omega(N^2)$$

## Upper Bound

- A pass with increment  $h_k$  consists of  $h_k$  insertion sorts of about  $N/h_k$  elements

$$h_k = 3, \quad N = 16$$



— Insertion sort of  $16/3 \approx 5$  items, items are = 1, 10, 4, 6, 15

— Insertion sort of  $16/3 \approx 5$  items, items are = 9, 3, 12, 14, 8

— Insertion sort of  $16/3 \approx 5$  items

$$h_k * (N/h_k)^2$$

## Upper Bound

- Summing over all passed

$$\sum_{i=1}^t N^2 / h_i = O(N^2 \sum_{i=1}^t 1/h_i) = O(N^2)$$

since  $\sum_{i=1}^t 1/h_i < 2$