# CS473 - Algorithms I

# Lecture 9 Sorting in Linear Time

View in slide-show mode

#### How Fast Can We Sort?

- □ The algorithms we have seen so far:
  - > Based on comparison of elements
  - > We only care about the relative ordering between the elements (not the actual values)
  - > The smallest worst-case runtime we have seen so far: O(nlgn)
  - $\rightarrow$  Is O(nlgn) the best we can do?
- □ <u>Comparison sorts</u>: Only use comparisons to determine the relative order of elements.

# Decision Trees for Comparison Sorts

- □ Represent a sorting algorithm abstractly in terms of a decision tree
  - A binary tree that represents the comparisons between elements in the sorting algorithm
  - Control, data movement, and other aspects are ignored
- □ One decision tree corresponds to one sorting algorithm and one value of n (input size)

# Reminder: Insertion Sort (from Lecture 1)

#### <u>Insertion-Sort</u> (A)

- 1. for  $j \leftarrow 2$  to n do
- 2.  $\text{key} \leftarrow A[j]$ ;
- $3. \quad i \leftarrow j 1;$
- 4. while i > 0 and A[i] > keydo
- 5.  $A[i+1] \leftarrow A[i];$
- 6.  $i \leftarrow i 1;$

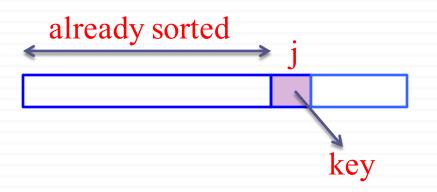
#### endwhile

7.  $A[i+1] \leftarrow \text{key};$  endfor

Iterate over array elts j

#### **Loop** invariant:

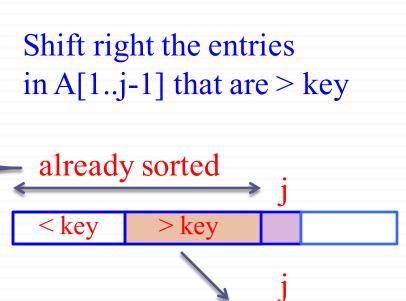
The subarray A[1..j-1] is always sorted



# Reminder: Insertion Sort (from Lecture 1)

#### Insertion-Sort (A)

- 1. for  $j \leftarrow 2$  to n do
- 2.  $\text{key} \leftarrow A[j]$ ;
- 3.  $i \leftarrow j 1$ ;
- 4. while i > 0 and A[i] > keydo
- 5.  $A[i+1] \leftarrow A[i];$
- 6.  $i \leftarrow i 1;$ 
  - endwhile
- 7.  $A[i+1] \leftarrow \text{key};$ endfor



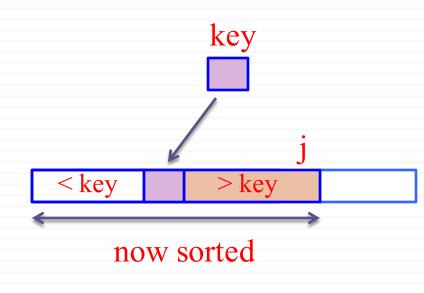
# Reminder: Insertion Sort (from Lecture 1)

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- 4. while i > 0 and A[i] > key
- 5.  $A[i+1] \leftarrow A[i];$
- 6.  $i \leftarrow i 1;$

endwhile

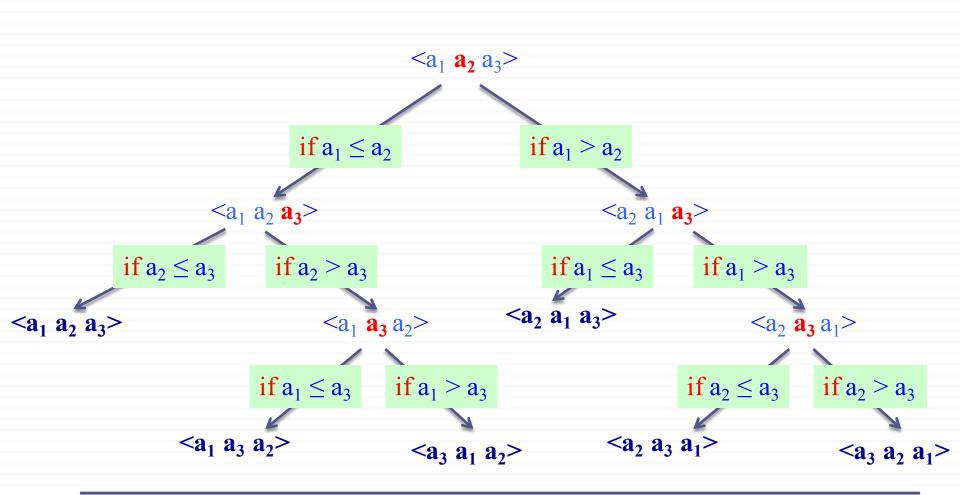
7.  $A[i+1] \leftarrow \text{key};$ endfor



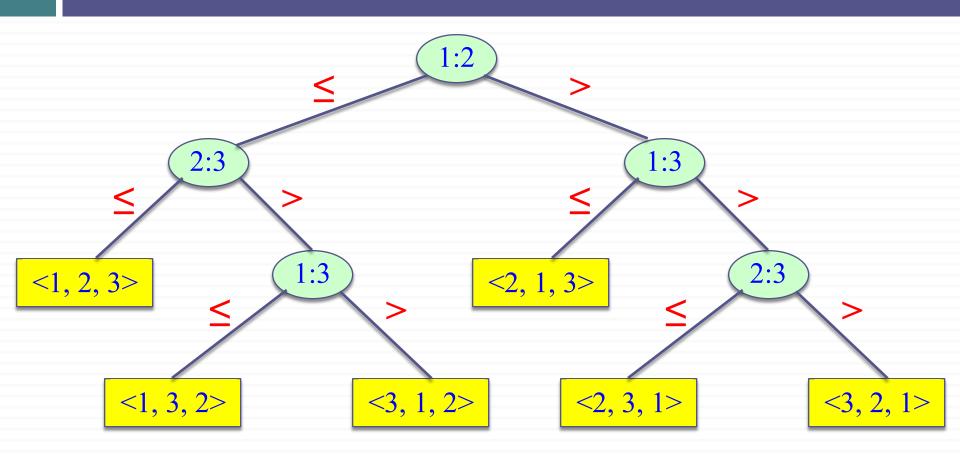
Insert key to the correct location End of iter j: A[1..j] is sorted

# Different Outcomes for Insertion Sort and n=3

Input:  $< a_1, a_2, a_3 >$ 



### Decision Tree for Insertion Sort and n=3

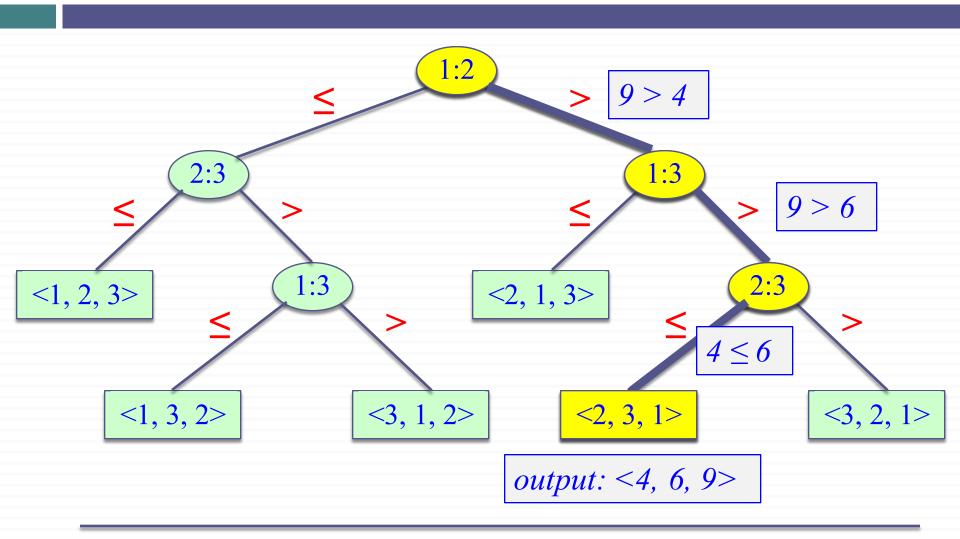


# Decision Tree Model for Comparison Sorts

- $\square$  Internal node (i:j): Comparison between elements  $a_i$  and  $a_j$
- □ <u>Leaf node</u>: An output of the sorting algorithm
- □ <u>Path from root to a leaf:</u> The execution of the sorting algorithm for a given input
- □ All possible executions are captured by the decision tree
- □ All possible outcomes (permutations) are in the leaf nodes

# Decision Tree for Insertion Sort and n=3

Input: <9, 4, 6>



### Decision Tree Model

- □ A decision tree can model the execution of any comparison sort:
  - One tree for each input size n
  - View the algorithm as splitting whenever it compares two elements
  - The tree contains the comparisons along all possible instruction traces

<u>The running time of the algorithm</u> = the length of the path taken <u>Worst case running time</u> = height of the tree

# Lower Bound for Comparison Sorts

- $\square$  Let n be the number of elements in the input array.
- □ What is the min number of leaves in the decision tree?
  - n! (because there are n! permutations of the input array, and all possible outputs must be captured in the leaves)
- What is the max number of leaves in a binary tree of height h?

2h

□ So, we must have:

$$2^h \ge n!$$

# Lower Bound for Decision Tree Sorting

**Theorem**: Any comparison sort algorithm requires  $\Omega(nlgn)$  comparisons in the worst case.

**Proof**: We'll prove that any decision tree corresponding to a comparison sort algorithm must have height  $\Omega(nlgn)$ 

```
2^{h} \ge n! (from previous slide)

h \ge lg(n!)

\ge lg((n/e)^{n}) (Stirling's approximation)

= nlgn - n lge

= \Omega(nlgn)
```

# Lower Bound for Decision Tree Sorting

<u>Corollary</u>: Heapsort and merge sort are asymptotically optimal comparison sorts.

**Proof**: The O(nlgn) upper bounds on the runtimes for heapsort and merge sort match the  $\Omega(nlgn)$  worst-case lower bound from the previous theorem.

# Sorting in Linear Time

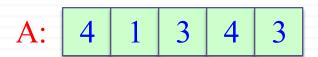
**Counting sort**: No comparisons between elements

```
Input: A[1 .. n], where A[j] ∈ \{1, 2, ..., k\}
```

Output: B[1 .. n], sorted

*Auxiliary storage*: C[1 .. k]

```
for i \leftarrow 1 to k do
    C[i] \leftarrow 0
for j \leftarrow 1 to n do
   C[A[j]] \leftarrow C[A[j]] + 1
// C[i] = |\{key = i\}|
for i \leftarrow 2 to k do
   C[i] \leftarrow C[i] + C[i-1]
// C[i] = |\{\text{key} \le i\}|
for j \leftarrow n downto 1 do
   B[C[A[j]]] \leftarrow A[j]
   C[A[j]] \leftarrow C[A[j]] - 1
```



```
for i ← 1 to k do

C[i] ← 0

for j ← 1 to n do

C[A[j]] ← C[A[j]] + 1

// C[i] = |{key = i}|
```

for 
$$i \leftarrow 2$$
 to  $k$  do
$$C[i] \leftarrow C[i] + C[i-1]$$
//  $C[i] = |\{key \le i\}|$ 

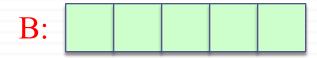
for 
$$j \leftarrow n$$
 downto 1 do  

$$B[C[A[j]]] \leftarrow A[j]$$

$$C[A[j]] \leftarrow C[A[j]] - 1$$

#### **Step 1**: Initialize all counts to 0





```
for i \leftarrow 1 to k do
C[i] \leftarrow 0
for j \leftarrow 1 to n do
C[A[j]] \leftarrow C[A[j]] + 1
// C[i] = |\{key = i\}|
```

for 
$$i \leftarrow 2$$
 to  $k$  do  

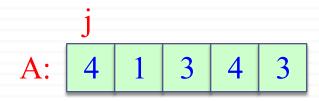
$$C[i] \leftarrow C[i] + C[i-1]$$
//  $C[i] = |\{key \le i\}|$ 

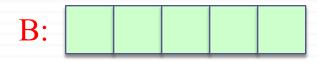
for 
$$j \leftarrow n$$
 downto 1 do  

$$B[C[A[j]]] \leftarrow A[j]$$

$$C[A[j]] \leftarrow C[A[j]] - 1$$

<u>Step 2</u>: Count the number of occurrences of each value in the input array







```
for i \leftarrow 1 to k do
C[i] \leftarrow 0
for j \leftarrow 1 to n do
C[A[j]] \leftarrow C[A[j]] + 1
// C[i] = |\{key = i\}|
```

for 
$$i \leftarrow 2$$
 to  $k$  do
$$C[i] \leftarrow C[i] + C[i-1]$$
//  $C[i] = |\{key \le i\}|$ 

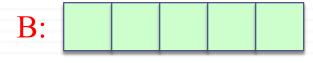
for 
$$j \leftarrow n$$
 downto 1 do  

$$B[C[A[j]]] \leftarrow A[j]$$

$$C[A[j]] \leftarrow C[A[j]] - 1$$

**Step 3**: Compute the number of elements less than or equal to each value





i
1 2 3 4
C: 1 1 3 5

```
for i \leftarrow 1 to k do
C[i] \leftarrow 0
for j \leftarrow 1 to n do
C[A[j]] \leftarrow C[A[j]] + 1
// C[i] = |\{key = i\}|
```

for 
$$i \leftarrow 2$$
 to  $k$  do  

$$C[i] \leftarrow C[i] + C[i-1]$$
//  $C[i] = |\{key \le i\}|$ 

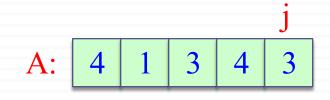
for 
$$j \leftarrow n$$
 downto 1 do  

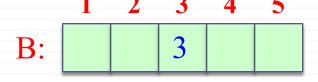
$$B[C[A[j]]] \leftarrow A[j]$$

$$C[A[j]] \leftarrow C[A[j]] - 1$$

#### **Step 4**: Populate the output array

There are C[3] = 3 elts that are  $\leq 3$ 





```
for i \leftarrow 1 to k do
C[i] \leftarrow 0
for j \leftarrow 1 to n do
C[A[j]] \leftarrow C[A[j]] + 1
// C[i] = |\{key = i\}|
```

for 
$$i \leftarrow 2$$
 to  $k$  do  

$$C[i] \leftarrow C[i] + C[i-1]$$
//  $C[i] = |\{key \le i\}|$ 

for 
$$j \leftarrow n$$
 downto 1 do  

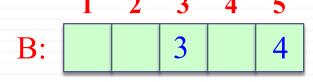
$$B[C[A[j]]] \leftarrow A[j]$$

$$C[A[j]] \leftarrow C[A[j]] - 1$$

#### **Step 4**: Populate the output array

There are C[4] = 5 elts that are  $\leq 4$ 





```
for i \leftarrow 1 to k do
C[i] \leftarrow 0
for j \leftarrow 1 to n do
C[A[j]] \leftarrow C[A[j]] + 1
// C[i] = |\{key = i\}|
```

for 
$$i \leftarrow 2$$
 to  $k$  do  

$$C[i] \leftarrow C[i] + C[i-1]$$
//  $C[i] = |\{key \le i\}|$ 

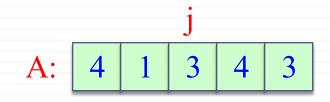
for 
$$j \leftarrow n$$
 downto 1 do  

$$B[C[A[j]]] \leftarrow A[j]$$

$$C[A[j]] \leftarrow C[A[j]] - 1$$

#### **Step 4**: Populate the output array

There are C[3] = 2 elts that are  $\leq 3$ 



```
for i \leftarrow 1 to k do
C[i] \leftarrow 0
for j \leftarrow 1 to n do
C[A[j]] \leftarrow C[A[j]] + 1
// C[i] = |\{key = i\}|
```

for 
$$i \leftarrow 2$$
 to  $k$  do
$$C[i] \leftarrow C[i] + C[i-1]$$
//  $C[i] = |\{key \le i\}|$ 

for 
$$j \leftarrow n$$
 downto 1 do  

$$B[C[A[j]]] \leftarrow A[j]$$

$$C[A[j]] \leftarrow C[A[j]] - 1$$

#### **Step 4**: Populate the output array

There are C[1] = 1 elts that are  $\leq 1$ 

```
for i \leftarrow 1 to k do
C[i] \leftarrow 0
for j \leftarrow 1 to n do
C[A[j]] \leftarrow C[A[j]] + 1
// C[i] = |\{key = i\}|
```

for 
$$i \leftarrow 2$$
 to  $k$  do  

$$C[i] \leftarrow C[i] + C[i-1]$$
//  $C[i] = |\{key \le i\}|$ 

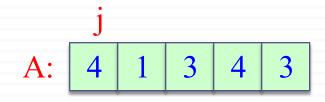
for 
$$j \leftarrow n$$
 downto 1 do  

$$B[C[A[j]]] \leftarrow A[j]$$

$$C[A[j]] \leftarrow C[A[j]] - 1$$

#### **Step 4**: Populate the output array

There are C[4] = 4 elts that are  $\leq 4$ 



```
for i \leftarrow 1 to k do
C[i] \leftarrow 0
for j \leftarrow 1 to n do
C[A[j]] \leftarrow C[A[j]] + 1
// C[i] = |\{key = i\}|
```

for 
$$i \leftarrow 2$$
 to  $k$  do  

$$C[i] \leftarrow C[i] + C[i-1]$$
//  $C[i] = |\{key \le i\}|$ 

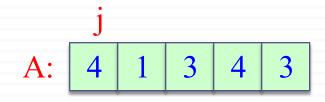
for 
$$j \leftarrow n$$
 downto 1 do  

$$B[C[A[j]]] \leftarrow A[j]$$

$$C[A[j]] \leftarrow C[A[j]] - 1$$

#### **Step 4**: Populate the output array

There are C[4] = 4 elts that are  $\leq 4$ 



# Counting Sort: Runtime Analysis

```
for i \leftarrow 1 to k do
    C[i] \leftarrow 0
for i \leftarrow 1 to n do
   C[A[i]] \leftarrow C[A[i]] + 1
// C[i] = |\{key = i\}|
                                                                Total runtime: \Theta(n+k)
for i \leftarrow 2 to k do
   C[i] \leftarrow C[i] + C[i-1]
// C[i] = |\{\text{key} \le i\}|
for j \leftarrow n downto 1 do
                                                            n: size of the input array
   B[C[A[j]]] \leftarrow A[j]
                                          \Theta(n)
                                                            k: the range of input values
   C[A[i]] \leftarrow C[A[j]] - 1
```

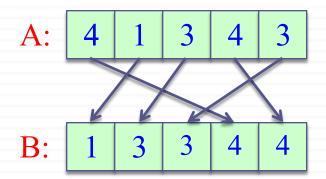
# Counting Sort: Runtime

- $\square$  Runtime is  $\Theta(n+k)$
- $\square$  If k = O(n), then counting sort takes  $\Theta(n)$

- □ *Question*: We proved a lower bound of  $\Theta(nlgn)$  before! Where is the fallacy?
- □ *Answer*:
  - $\Box$   $\Theta$ (nlgn) lower bound is for comparison-based sorting
  - Counting sort is not a comparison sort
  - In fact, not a single comparison between elements occurs!

# Stable Sorting

- □ Counting sort is a *stable sort*: It preserves the input order among equal elements.
  - i.e. The numbers with the same value appear in the output array in the same order as they do in the input array.



**Exercise**: Which other sorting algorithms have this property?

#### Radix Sort

- □ *Origin*: Herman Hollerith's card-sorting machine for the 1890 US Census.
- □ *Basic idea*: Digit-by-digit sorting

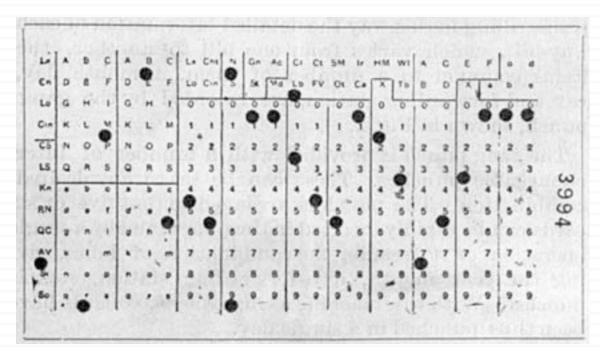
- ☐ Two variations:
  - Sort from MSD to LSD (bad idea)
  - Sort from LSD to MSD (good idea)
  - LSD/MSD: Least/most significant digit

### Herman Hollerith (1860-1929)

- □ The 1880 U.S. Census took almost 10 years to process.
- □ While a lecturer at MIT, Hollerith prototyped punched-card technology.
- □ His machines, including a "card sorter," allowed the 1890 census total to be reported in 6 weeks.
- He founded the Tabulating Machine
   Company in 1911, which merged with other companies in 1924 to form
   International Business Machines (IBM).



#### Hollerith Punched Card

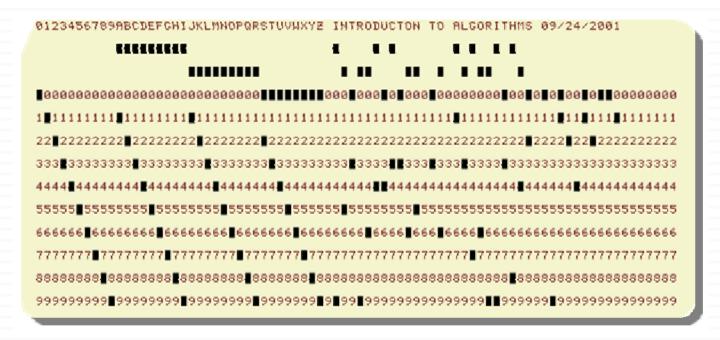


- > 12 rows and 24 columns
- > coded for age, state of residency, gender, etc.

<u>Punched card</u>: A piece of stiff paper that contains digital information represented by the presence or absence of holes.

#### "Modern" IBM card

#### □ One character per column



So, that's why text windows have 80 columns!

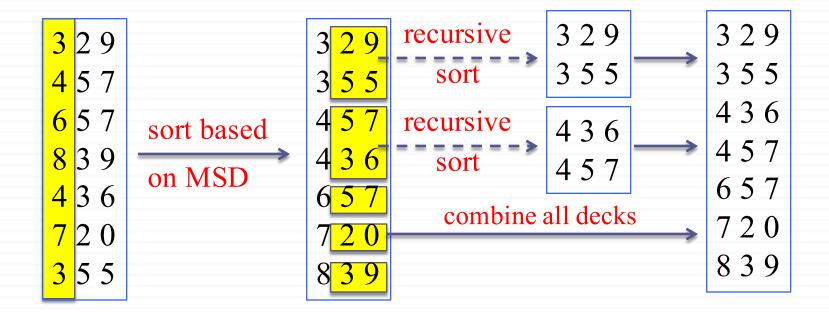
# Hollerith Tabulating Machine and Sorter



- > Mechanically sorts the cards based on the hole locations.
- Sorting performed for one column at a time
- > Human operator needed to load/retrieve/move cards at each stage

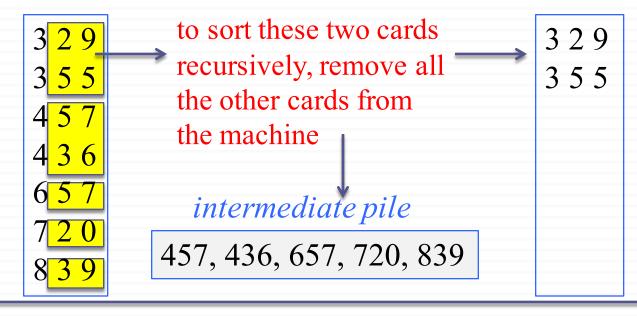
#### Hollerith's MSD-First Radix Sort

- □ Sort starting from the most significant digit (MSD)
- □ Then, sort each of the resulting bins recursively
- □ At the end, combine the decks in order



#### Hollerith's MSD-First Radix Sort

- □ To sort a subset of cards recursively:
  - All the other cards need to be removed from the machine, because the machine can handle only one sorting problem at a time.
  - The human operator needs to keep track of the intermediate card piles



#### Hollerith's MSD-First Radix Sort

- □ MSD-first sorting may require:
  - -- very large number of sorting passes
  - -- very large number of intermediate card piles to maintain
- □ S(d): # of passes needed to sort d-digit numbers (worst-case)
- □ Recurrence:

$$S(d) = 10 S(d-1) + 1 \text{ with } S(1) = 1$$

Reminder: Recursive call made to each subset with the same most significant digit (MSD)

#### Hollerith's MSD-First Radix Sort

Recurrence: S(d) = 10S(d-1) + 1

$$S(d) = 10 S(d-1) + 1$$

$$= 10 (10 S(d-2) + 1) + 1$$

$$= 10 (10 (10 S(d-3) + 1) + 1) + 1$$

$$= 10^{i} S(d-i) + 10^{i-1} + 10^{i-2} + ... + 10^{1} + 10^{0}$$

Iteration terminates when i = d-1 with S(d-(d-1)) = S(1) = 1

$$S(d) = \sum_{i=0}^{d-1} 10^{i} = \frac{10^{d} - 1}{10 - 1} = \frac{1}{9}(10^{d} - 1)$$

$$S(d) = \frac{1}{9}(10^{d} - 1)$$

### Hollerith's MSD-First Radix Sort

P(d): # of intermediate card piles maintained (worst-case)

**Reminder**: Each routing pass generates 9 intermediate piles except the sorting passes on least significant digits (LSDs)

There are 10<sup>d-1</sup> sorting calls to LSDs

$$P(d) = 9 (S(d) - 10^{d-1}) = 9 ((10^{d} - 1)/9 - 10^{d-1})$$
$$= (10^{d} - 1 - 9 \cdot 10^{d-1}) = 10^{d-1} - 1$$

$$P(d) = 10^{d-1} - 1$$

Alternative solution: Solve the recurrence: P(d) = 10P(d-1) + 9

$$P(d) = 10P(d-1) + 9$$
  
 $P(1) = 0$ 

### Hollerith's MSD-First Radix Sort

□ Example: To sort 3 digit numbers, in the worst case:

$$S(d) = (1/9) (10^3-1) = 111$$
 sorting passes needed

$$P(d) = 10^{d-1}-1 = 99$$
 intermediate card piles generated

- MSD-first approach has more recursive calls and intermediate storage requirement
  - Expensive for a "tabulating machine" to sort punched cards
  - Overhead of recursive calls in a modern computer

#### LSD-First Radix Sort

- □ Least significant digit (LSD)-first radix sort seems to be a folk invention originated by machine operators.
- □ It is the counter-intuitive, but the better algorithm.
- □ Basic algorithm:

Sort numbers on their LSD first

Stable sorting needed!!!

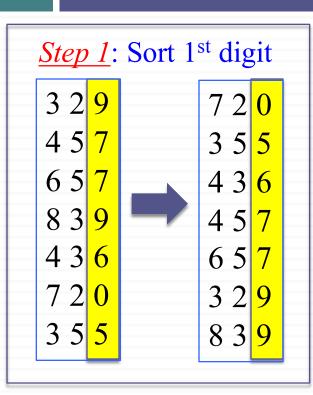
Combine the cards into a single deck in order

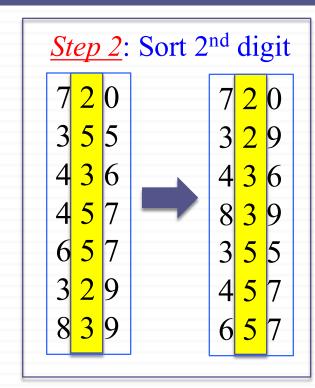
Continue this sorting process for the other digits

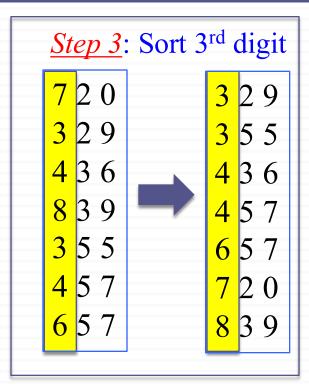
from the LSD to MSD

- > Requires only d sorting passes
- ➤ No intermediate card pile generated

### LSD-first Radix Sort: Example



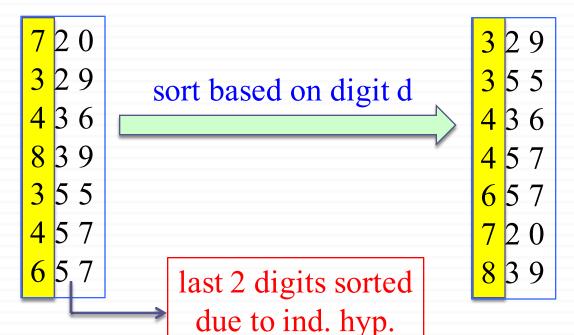




### Correctness of Radix Sort (LSD-first)

**Proof by induction**: Base case: d=1 is correct (trivial)

<u>Inductive hyp</u>: Assume the first d-1 digits are sorted correctly Prove that all d digits are sorted correctly after sorting digit d



Two numbers that differ in digit d are correctly sorted (e.g. 355 and 657)

Two numbers equal in digit d are put in the same order as the input

→ correct order

#### Radix Sort: Runtime

□ Use counting-sort to sort each digit

<u>Reminder</u>: Counting sort complexity:  $\Theta(n+k)$ 

n: size of input array

k: the range of the values

 $\square$  Radix sort runtime:  $\Theta(d(n+k))$ 

d: # of digits

 $\square$  How to choose the d and k?

# Radix Sort: Runtime – Example 1

- □ We have flexibility in choosing d and k
- □ Assume we are trying to sort 32-bit words
  - We can define each digit to be 4 bits
  - Then, the range for each digit  $k = 2^4 = 16$ So, counting sort will take  $\Theta(n+16)$
  - The number of digits d = 32/4 = 8
  - Radix sort runtime:  $\Theta(8(n+16)) = \Theta(n)$



## Radix Sort: Runtime – Example 2

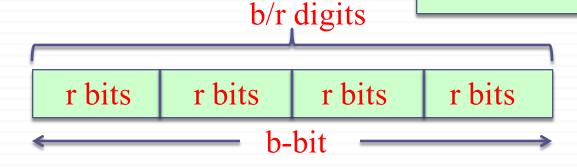
- □ We have flexibility in choosing d and k
- □ Assume we are trying to sort 32-bit words
  - Or, we can define each digit to be 8 bits
  - Then, the range for each digit  $k = 2^8 = 256$ So, counting sort will take  $\Theta(n+256)$
  - The number of digits d = 32/8 = 4
  - Radix sort runtime:  $\Theta(4(n+256)) = \Theta(n)$



### Radix Sort: Runtime

- ☐ Assume we are trying to sort b-bit words
  - Define each digit to be r bits
  - Then, the range for each digit  $k = 2^r$ So, counting sort will take  $\Theta(n+2^r)$
  - The number of digits d = b/r

Radix sort runtime: 
$$T(n,b) = \Theta\left(\frac{b}{r}(n+2^r)\right)$$



## Radix Sort: Runtime Analysis

$$T(n,b) = \Theta\left(\frac{b}{r}\left(n+2^r\right)\right)$$

Minimize T(n, b) by differentiating and setting to 0 Or, intuitively:

We want to balance the terms (b/r) and  $(n + 2^r)$ 

Choose  $r \approx lgn$ 

If we choose  $r << lgn \rightarrow (n + 2^r)$  term doesn't improve If we choose  $r >> lgn \rightarrow (n + 2^r)$  increases exponentially

### Radix Sort: Runtime Analysis

$$T(n,b) = \Theta\left(\frac{b}{r}\left(n+2^r\right)\right)$$

Choose 
$$r = lgn$$



Choose 
$$r = lgn$$
  $T(n, b) = \Theta(bn/lgn)$ 

For numbers in the range from 0 to  $n^d - 1$ , we have:

The number of bits  $b = \lg(n^d) = d \lg n$ 

 $\rightarrow$  Radix sort runs in  $\Theta(dn)$ 

### Radix Sort: Conclusions

Choose 
$$r = lgn$$



Choose 
$$r = lgn$$
  $T(n, b) = \Theta(bn/lgn)$ 

□ Example: Compare radix sort with merge sort/heapsort

1 million ( $2^{20}$ ) 32-bit numbers ( $n = 2^{20}$ , b = 32)

Radix sort: [32/20] = 2 passes

Merge sort/heap sort: lgn = 20 passes

Downsides:

Radix sort has little locality of reference (more cache misses)

The version that uses counting sort is not in-place

On modern processors, a well-tuned quicksort implementation typically runs faster.