CS473 - Algorithms I

Lecture 8

Heapsort

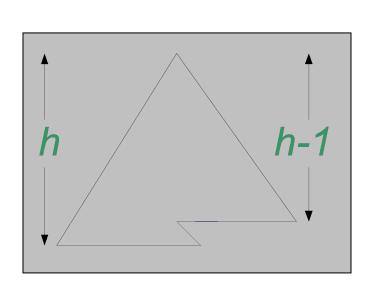
Heapsort

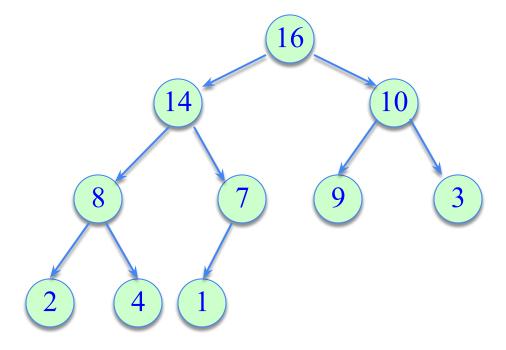
- Worst-case runtime: O(nlgn)
- Sorts in-place
- Uses a special data structure (heap) to manage information during execution of the algorithm
 - ☐ Another design paradigm

Heap Data Structure

Refer to Data Structures slides for heap details!

The largest element in any subtree is the root element in a max-heap





Nearly complete binary tree

☐ Completely filled on all levels except possibly the lowest level

Assume max-heaps

Heap Operations

- $\bullet \quad Max(A, n) \longrightarrow O(1)$
- Extract(A, n) \rightarrow O(lg n)
 - \circ Heapify(A, i, n) \rightarrow O(lg n)
- Insert(A, key, n) \rightarrow O(lg n)
- Build-Heap(A, n) \rightarrow O(n) [why not O(n lg n)?]
- $\bullet \quad Min(A, n) \qquad \rightarrow \quad O(n)$
- Search(A, key) \rightarrow O(n)
- Heap-Increase-Key(A, i, key) \rightarrow O(lg n)
- Heap-Decrease-Key(A, i, key) \rightarrow O(lg n)

Summary: Max Heap

Max(A, n)

Returns the max element of the heap (no modification)

Runtime: O(1)

Heapify(A, i, n)

Works when both child subtrees of node i are heaps

"Floats down" node i to satisfy the heap property

Runtime: O(lgn)

Extract(A, n)

Returns and removes the max element of the heap

Fills the gap in A[1] with A[n], then calls Heapify(A,1)

Runtime: O(lgn)

Summary: Max Heap

Build-Heap(A, n)

Given an arbitrary array, builds a heap from scratch

Runtime: O(n)

Min(A, n)

How to return the min element in a *max-heap*?

Worst case runtime: O(n)

because ~half of the heap elements are leaf nodes

Instead, use a *min-heap* for efficient min operations

Search(A, key)

For an arbitrary x value, the worst-case runtime: O(n)

Use a sorted array instead for efficient search operations

Summary: Max Heap

Increase-Key(A, i, x)

Increase the key of node i (from A[i] to x)

"Float up" x until heap property is satisfied

Runtime: O(lg n)

Decrease-Key(A, i, x)

Decrease the key of node i (from A[i] to x)

Call Heapify(A, i)

Runtime: O(lg n)

Heap Increase Key

• Key value of i-th element of heap is increased from A[i] to key

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HEAP-INCREASE-KEY(A, i, key)

if key < A[i] then

return error

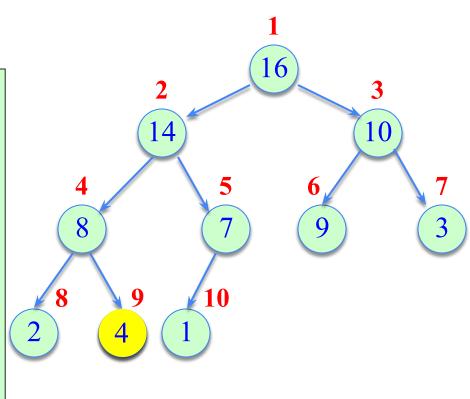
while i > 1 and A[\lfloor i/2 \rfloor] < \text{key do}

A[i] \leftarrow A[\lfloor i/2 \rfloor]

i \leftarrow \lfloor i/2 \rfloor

A[i] \leftarrow key
```

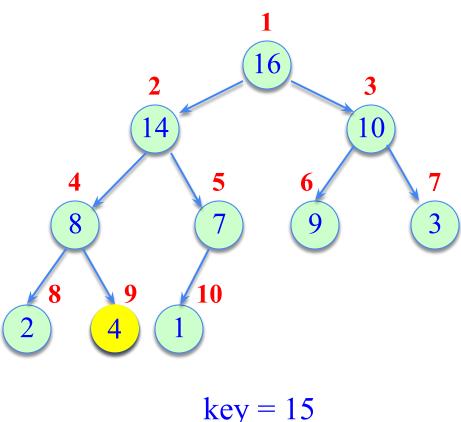
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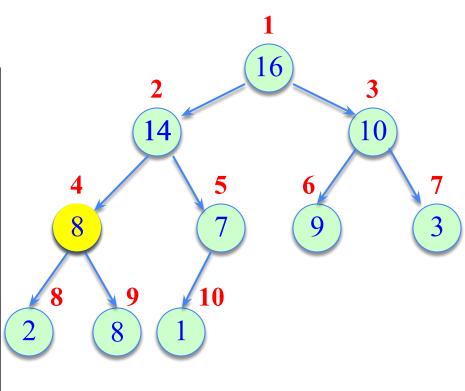
key = 15

 $A[i] \leftarrow key$

HEAP-INCREASE-KEY(A, i, key) if key < A[i] then return error while i > 1 and $A[\lfloor i/2 \rfloor] < \ker do$ $A[i] \leftarrow A[\lfloor i/2 \rfloor]$ $i \leftarrow \lfloor i/2 \rfloor$ $A[i] \leftarrow \ker do$

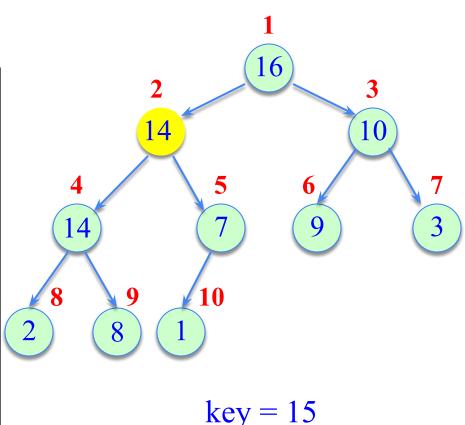


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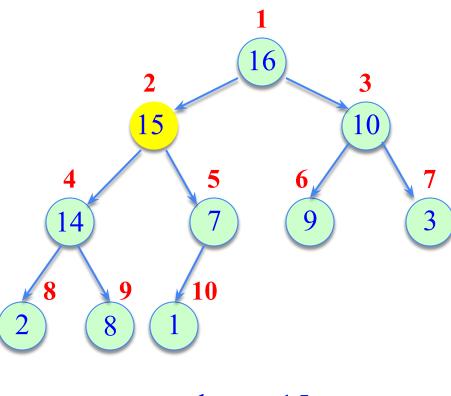


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Example Application: Phone Operator



A phone operator answering n phones

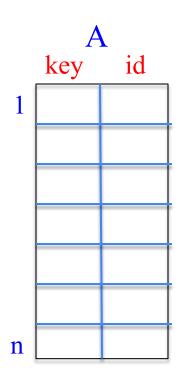
Each phone i has x_i people waiting in line for their calls to be answered.

Phone operator needs to answer the phone with the largest number of people waiting in line.

New calls come continuously, and some people hang up after waiting.

Solution

Step 1: Define the following array:



A[i]: the ith element in heap

A[i].id: the index of the corresponding phone

A[i].key: # of people waiting in line for phone with index A[i].id

Solution

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Step 2: Build-Max-Heap (A, n)
Execution:
   When the operator wants to answer a phone:
       id = A[1].id
       Decrease-Key(A, 1, A[1].key-1)
       answer phone with index id
   When a new call comes in to phone i:
       Increase-Key(A, i, A[i].key+1)
   When a call drops from phone i:
       Decrease-Key(A, i, A[i].key-1)
```

- (1) Build a heap on array A[1...n] by calling BUILD-HEAP(A, n)
- (2) The largest element is stored at the root A[1] Put it into its correct final position A[n] by A[1] \leftrightarrow A[n]
- (3) Discard node *n* from the heap
- (4) Subtrees ($S_2 \& S_3$) rooted at children of root remain as heaps but the new root element may violate the heap property Make A[1...n-1] a heap by calling HEAPIFY(A, 1, n-1)
- (5) $n \leftarrow n 1$
- (6) Repeat steps 2-4 until n=2

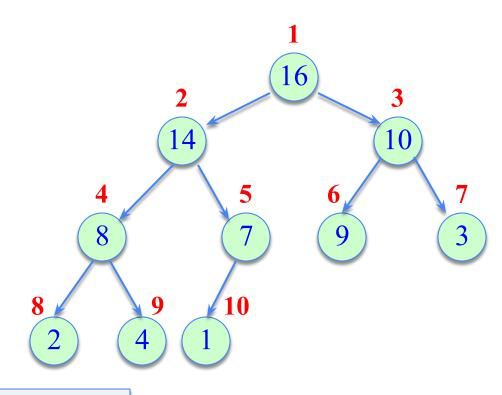
HEAPSORT(A, n)

BUILD-HEAP(A, n)

for $i \leftarrow n$ downto 2 do

exchange A[1] \leftrightarrow A[i]

HEAPIFY(A, 1, i -1)





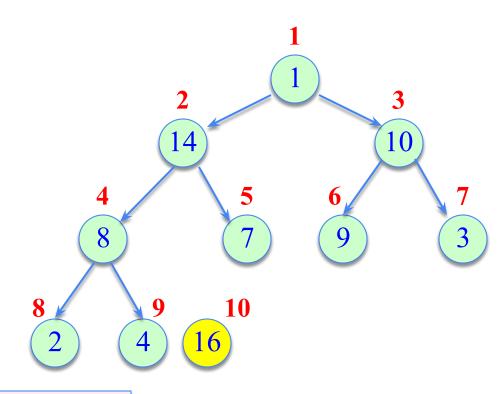
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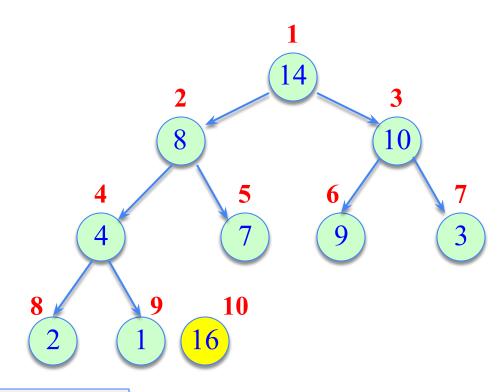
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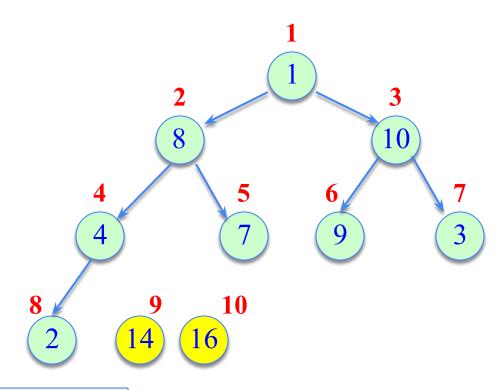
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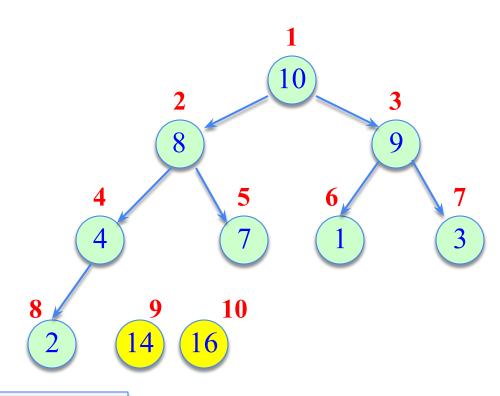
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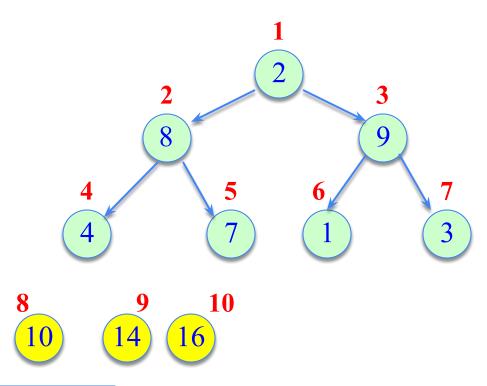
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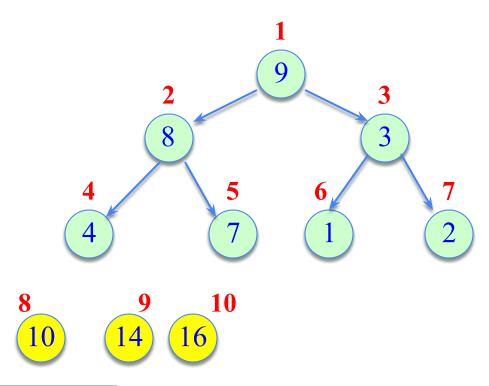
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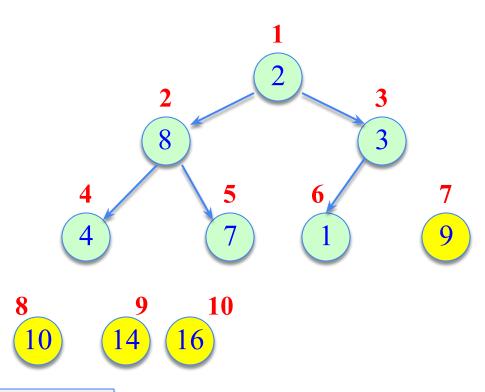
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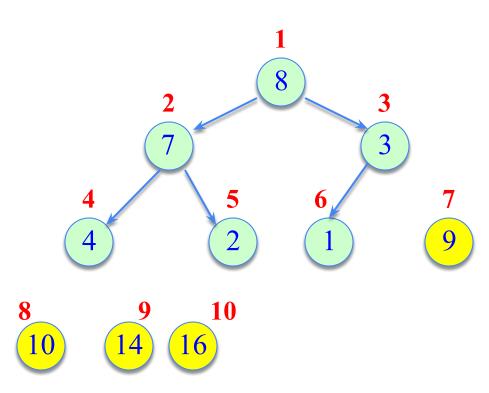
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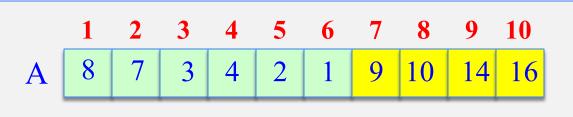
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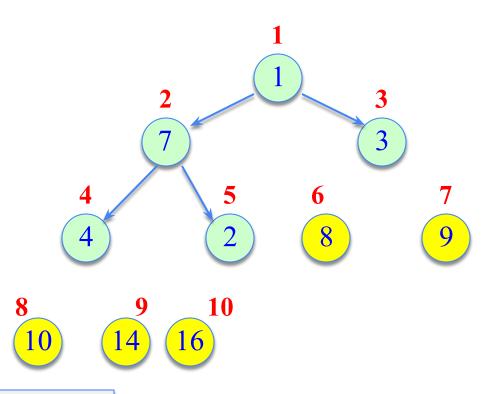
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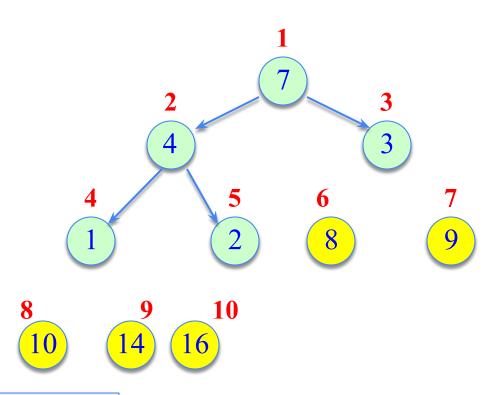
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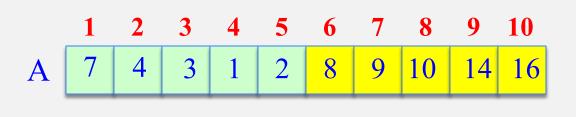
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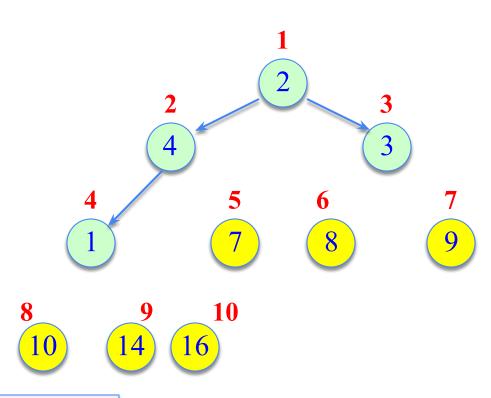
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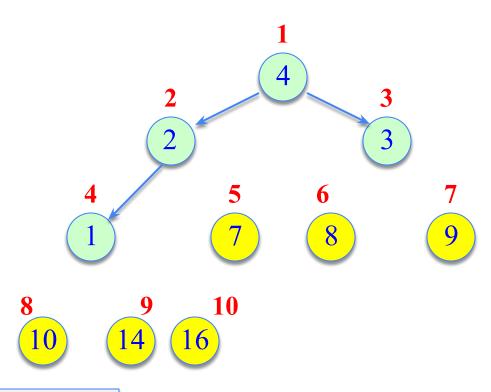
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 $\frac{HEAPSORT(A, n)}{\text{BUILD-HEAP}(A, n)}$ $\text{for } i \leftarrow n \text{ downto } 2 \text{ do}$ $\text{exchange A}[1] \leftrightarrow \text{A}[i]$

HEAPIFY(A, 1, i-1)





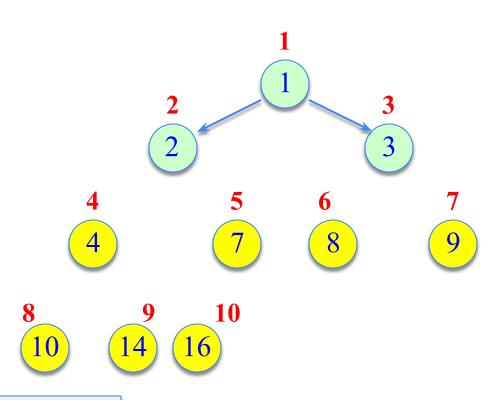
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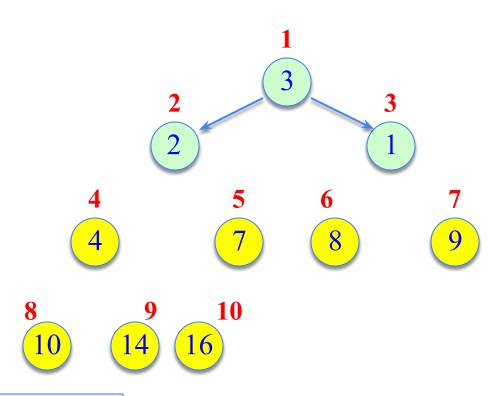
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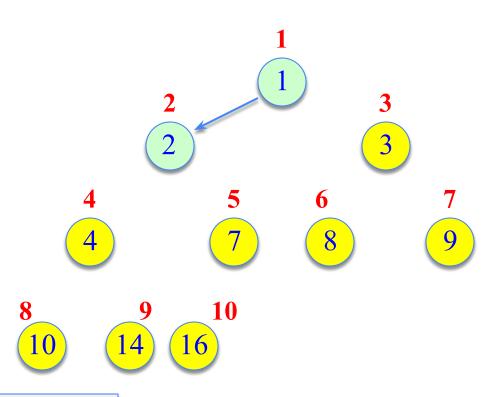
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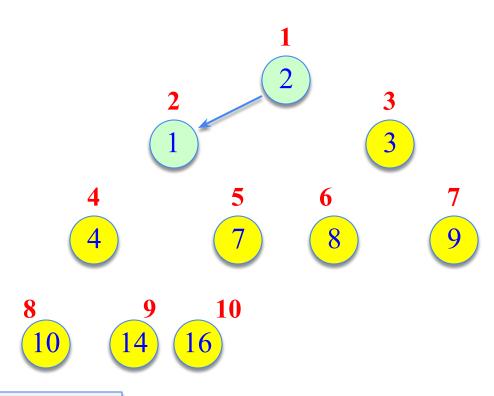
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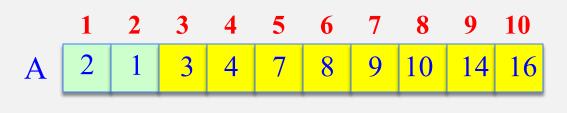
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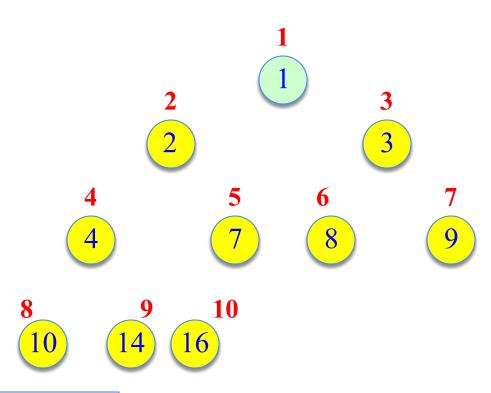
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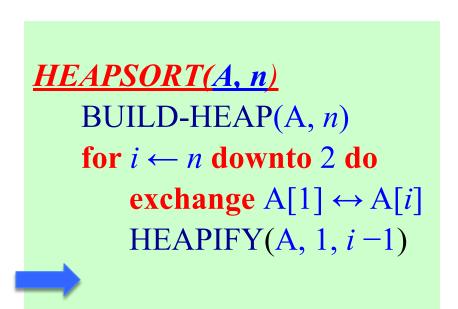


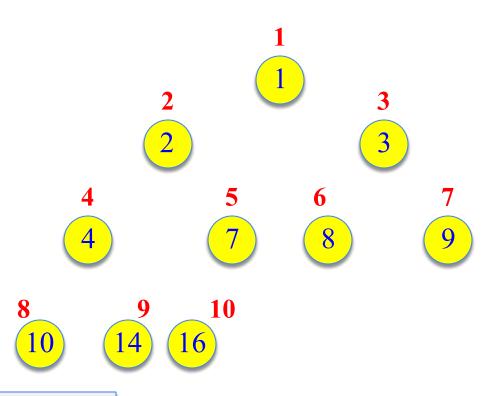














Heapsort Algorithm: Runtime Analysis

HEAPSORT(A, n) $\Theta(n)$ BUILD-HEAP(A, n) $\Theta(n)$ for $i \leftarrow n$ downto 2 do \exp change A[1] \leftrightarrow A[i] $\Theta(1)$ HEAPIFY(A, 1, i -1) $O(\lg(i-1))$

$$T(n) = \Theta(n) + \sum_{i=2}^{n} O(\lg i) = \Theta(n) + O\left(\sum_{i=2}^{n} O(\lg n)\right) = O(n \lg n)$$

Heapsort Algorithm: Performance

- Heapsort is a very good algorithm but, a good implementation of quicksort always beats heapsort in practice
- However, heap data structure has many popular applications, and it can be efficiently used for implementing priority queues