# CS473 - Algorithms I

#### Lecture 11 Greedy Algorithms

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# CS473 - Algorithms I

#### **Activity Selection Problem**

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## Activity Selection Problem

#### • We have:

- □ A set of activities with fixed start and finish times
- One shared resource (only one activity can use at any time)
- <u>Objective</u>: Choose the <u>max number</u> of compatible activities

Note: Objective is to maximize the number of activities, not the total time of activities.

#### • <u>Example</u>:

Activities: Meetings with fixed start and finish times Shared resource: A meeting room Objective: Schedule the max number of meetings

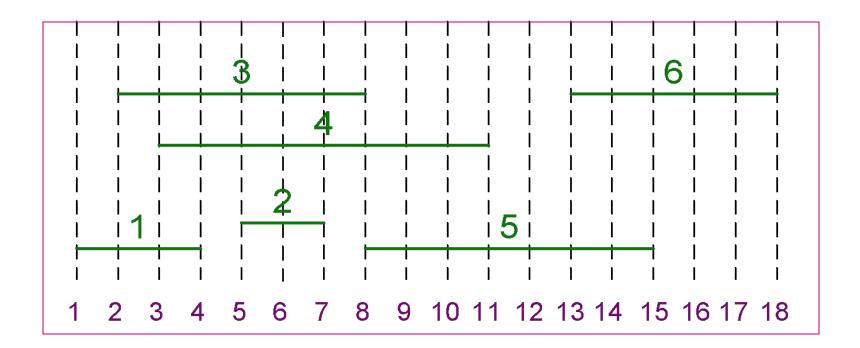
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# Activity Selection Problem

- Input: a set  $S = \{a_1, a_2, ..., a_n\}$  of *n* activities  $-s_i$ : Start time of activity  $a_i$ ,  $-f_i$ : Finish time of activity  $a_i$ Activity *i* takes place in  $[s_i, f_i]$
- <u>Aim</u>: Find max-size subset *A* of mutually *compatible* activities
  - Max number of activities, not max time spent in activities
  - Activities *i* and *j* are compatible if intervals  $[s_i, f_i)$ and  $[s_j, f_j)$  do not overlap, i.e., either  $s_i \ge f_j$  or  $s_j \ge f_i$

# Activity Selection Problem: An Example

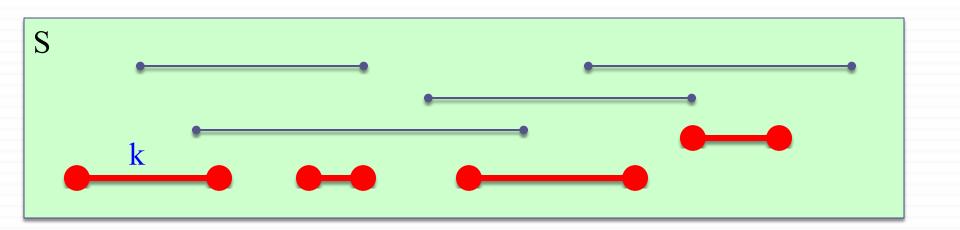
 $S = \{ [1, 4], [5, 7], [2, 8], [3, 11], [8, 15], [13, 18] \}$ 



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### **Optimal Substructure Property**

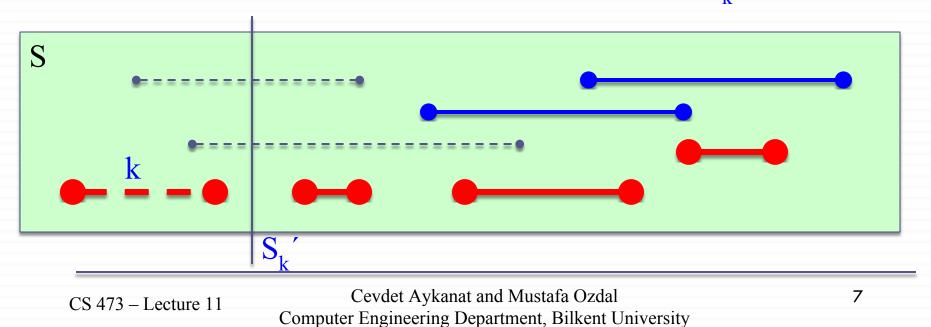
- Consider an optimal solution A for activity set S.
- $\square$  Let k be the activity in A with the earliest finish time



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### **Optimal Substructure Property**

- Consider an optimal solution A for activity set S.
- $\square$  Let k be the activity in A with the earliest finish time
- Now, consider the subproblem  $S_k'$  that has the activities that start after k finishes, i.e.  $S_k' = \{a_i \in S: s_i \ge f_k\}$
- What can we say about the optimal solution to  $S_{k}$ ?

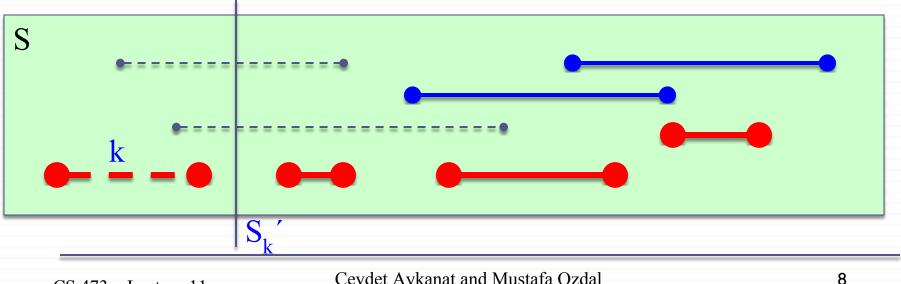


### **Optimal Substructure Property**

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- Now, consider the subproblem  $S_k'$  that has the activities that start after k finishes, i.e.  $S_k' = \{a_i \in S: s_i \ge f_k\}$

 $- A-\{k\}$  is an optimal solution for  $S_k'$ . Why?

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# **Optimal Substructure**

Theorem: Let k be the activity with the earliest finish time in an optimal soln  $A \subseteq S$  then

 $A - \{k\}$  is an optimal solution to subproblem  $S_k' = \{a_i \in S: s_i \ge f_k\}$ 

**Proof** (by contradiction):

Let B' be an optimal solution to S<sub>k</sub>' and |B'| > |A-{k}| = |A| - 1
Then, B = B' ∪ {k} is compatible and |B| = |B'|+1 > |A|
Contradiction to the optimality of A

O.E.D.

### **Optimal Substructure**

- <u>Recursive formulation</u>: Choose the first activity  $\mathbf{k}$ , and then solve the remaining subproblem  $\mathbf{S}_{\mathbf{k}}'$
- How to choose the first activity k?
   DP, memoized recursion?
   i.e. choose the k value that will have the max size for S<sub>k</sub>'
- DP would work,
   but is it necessary to try all possible values for k?

## Greedy Choice Property

- Assume (without loss of generality)  $f_1 \leq f_2 \leq \ldots \leq f_n$ 
  - If not, sort activities according to their finish times in non-decreasing order
- □ <u>Greedy choice property</u>: a sequence of locally optimal (greedy) choices  $\Rightarrow$  an optimal solution
- How to choose the first activity greedily without losing optimality?

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#### Greedy Choice Property - Theorem

Let activity set  $S = \{a_1, a_2, \dots, a_n\}$ , where  $f_1 \le f_2 \le \dots \le f_n$ 

<u>Theorem</u>: There exists an optimal solution  $A \subseteq S$  such that  $a_1 \in A$ 

In other words, the activity with the earliest finish time is guaranteed to be in an optimal solution.

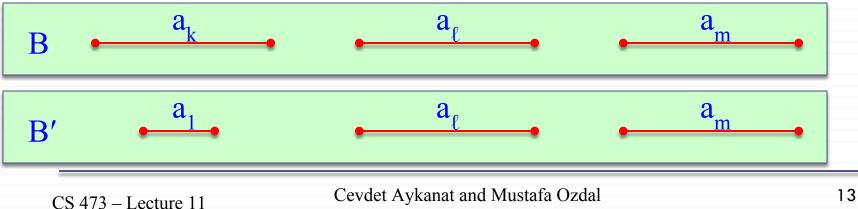
#### Greedy Choice Property - Proof

<u>*Theorem*</u>: There exists an optimal solution  $A \subseteq S$  such that  $a_1 \in S$ 

<u>*Proof*</u>: Consider an arbitrary optimal solution  $\mathbf{B} = \{\mathbf{a}_{k}, \mathbf{a}_{p}, \mathbf{a}_{m}, \ldots\},\$ where  $f_{k} < f_{\ell} < f_{m} < \dots$ 

If k = 1, then B starts with  $a_1$ , and the proof is complete

<u>If k > 1</u>, then create another solution B' by replacing  $a_k$  with  $a_1$ . Since  $f_1 \leq f_1$ , B' is guaranteed to be valid, and |B'| = |B|, hence also optimal



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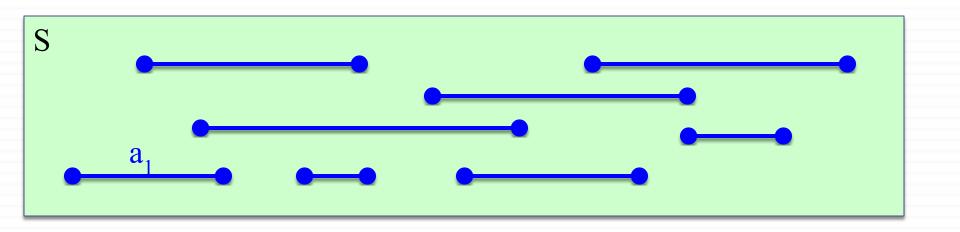
### Greedy Algorithm

- So far, we have:
  - Optimal substructure property: If  $A = \{a_k, ...\}$  is an optimal solution, then  $A \{a_k\}$  must be optimal for subproblem  $S'_k$ , where  $S'_k = \{a_i \in S: s_i \ge f_k\}$ Note:  $a_k$  is the activity with the earliest finish time in A
  - <u>Greedy choice property</u>: There is an optimal solution A that contains a<sub>1</sub>

*Note: a*<sub>1</sub> *is the activity with the earliest finish time in S* 

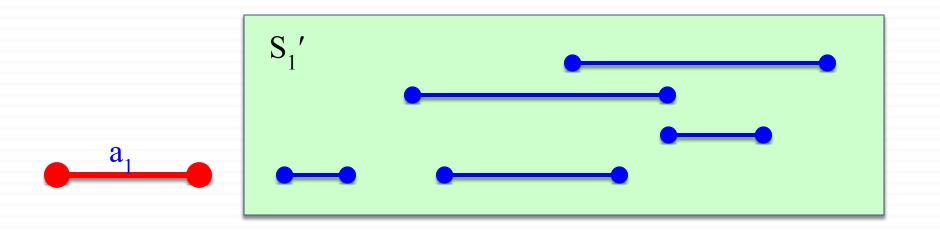
### Greedy Algorithm

- Basic idea of the greedy algorithm:
  - 1. Add  $a_1$  to A
  - 2. Solve the remaining subproblem  $S_1'$ , and then append the result to A



### Greedy Algorithm

- Basic idea of the greedy algorithm:
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### Greedy Algorithm for Activity Selection

*j*: specifies the index of most recent activity added to A

 $f_j = Max \{f_k : k \in A\}, max finish$ time of any activity in *A*; because activities are processed in non-decreasing order of finish times

Thus, " $s_i \ge f_j$  "checks the compatibility of *i* to current *A* 

<u>Running time</u>:  $\Theta(n)$  assuming that the activities were already sorted

```
GAS (s, f, n)

A \leftarrow \{1\}

j \leftarrow 1

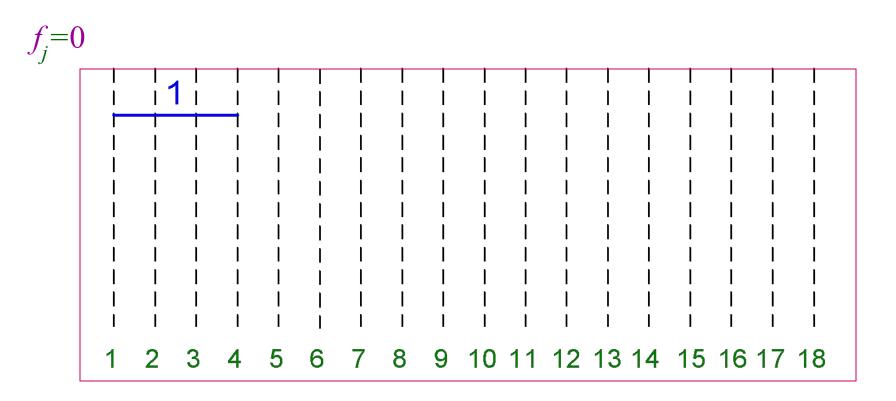
for i \leftarrow 2 to n do

if s_i \ge f_j then

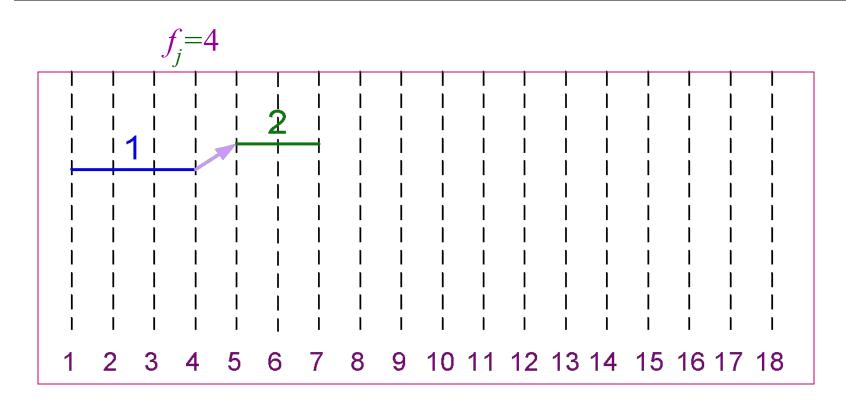
A \leftarrow A \cup \{i\}

j \leftarrow i

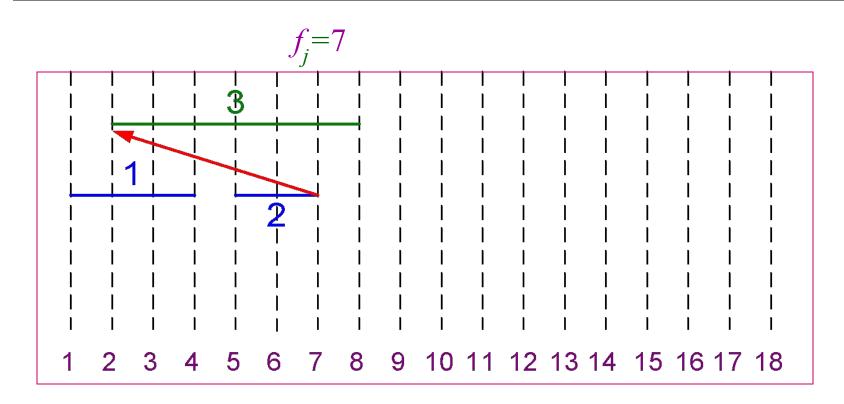
return A
```



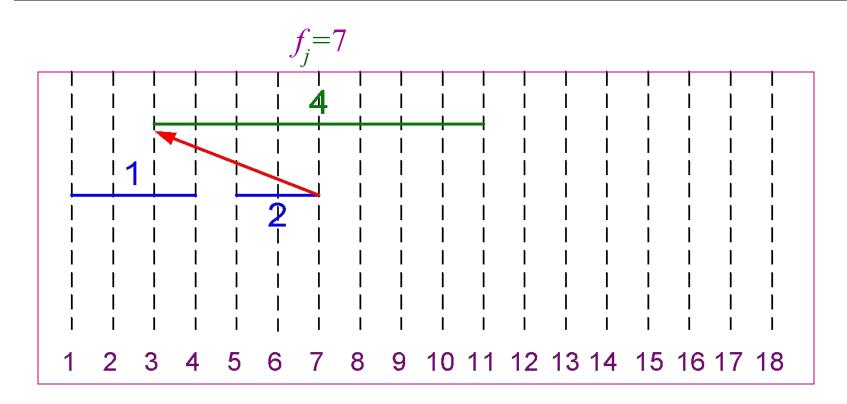
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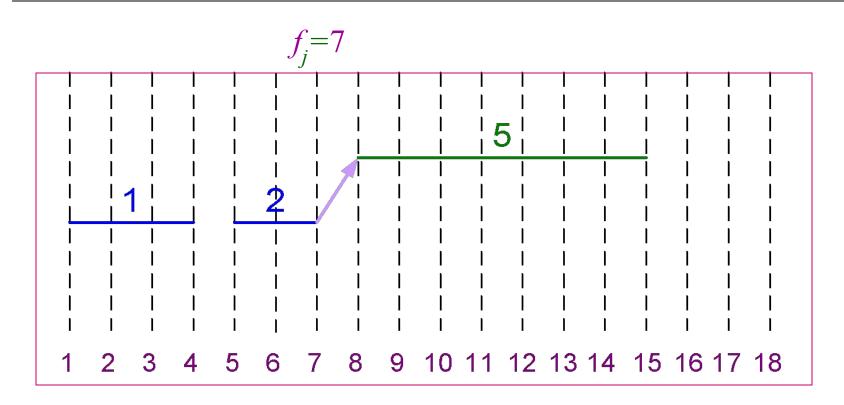
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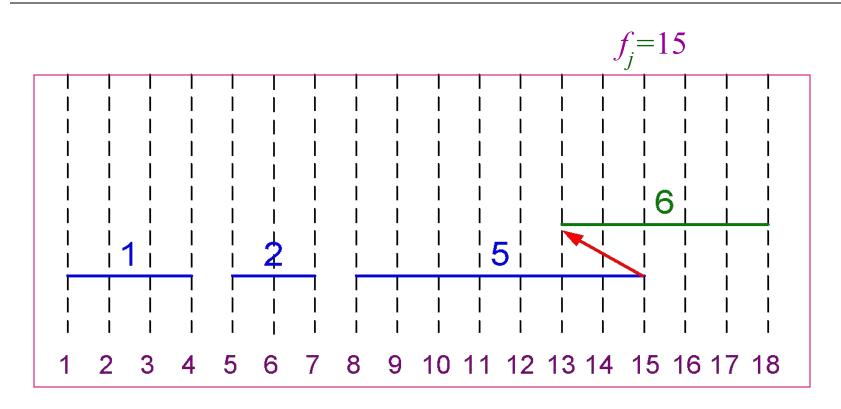
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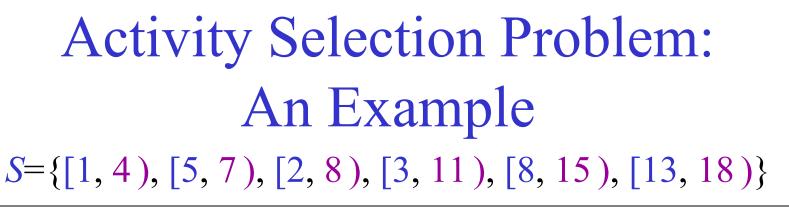
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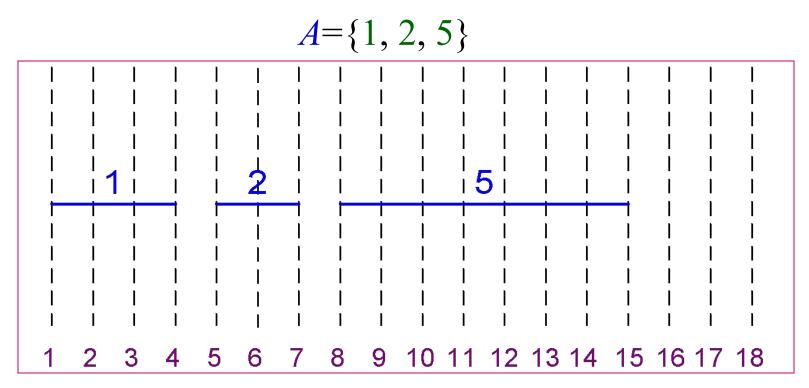


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# CS473 - Algorithms I

#### Comparison of DP and Greedy Algorithms

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#### Reminder: DP-Based Matrix Chain Order

$$m_{ij} = \min_{i \le k < j} \{ m_{ik} + m_{k+1,j} + p_{i-1} p_k p_j \}$$

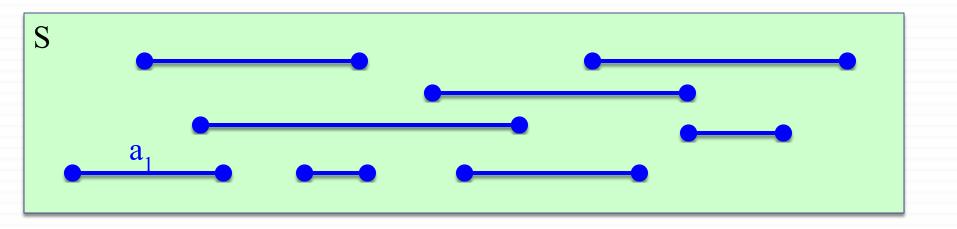
- We don't know ahead of time which k value to choose.
- We first need to compute the results of subproblems  $m_{ik}$ and  $m_{k+1,j}$  before computing  $m_{ij}$

The selection of k is done based on the results of the subproblems.

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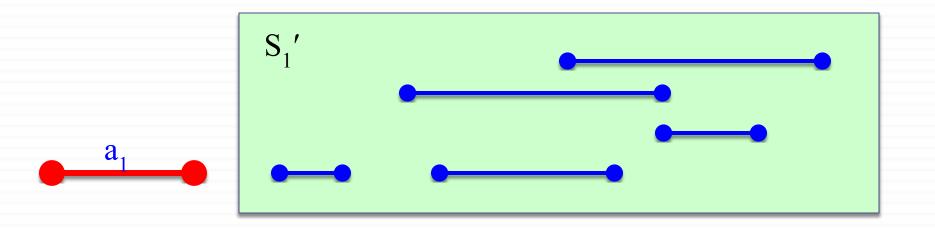
### Greedy Algorithm for Activity Selection

 Make a greedy selection in the beginning: Choose a<sub>1</sub> (the activity with the earliest finish time)
 Solve the remaining subproblem S<sub>1</sub>' (all activities that start after a<sub>1</sub>)



### Greedy Algorithm for Activity Selection

 Make a greedy selection in the beginning: Choose a<sub>1</sub> (the activity with the earliest finish time)
 Solve the remaining subproblem S<sub>1</sub>' (all activities that start after a<sub>1</sub>)



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# Greedy vs Dynamic Programming

- Optimal substructure property exploited by both Greedy and DP strategies
- Greedy Choice Property: A sequence of locally optimal choices ⇒ an optimal solution
  - We make the choice that seems best at the moment
  - Then solve the subproblem arising after the choice is made
- DP: We also make a choice/decision at each step, but the choice may depend on the optimal solutions to subproblems
- Greedy: The choice may depend on the choices made so far, but it cannot depend on any future choices or on the solutions to subproblems

# Greedy vs Dynamic Programming

- **DP** is a bottom-up strategy
- Greedy is a top-down strategy
  - each greedy choice in the sequence iteratively reduces each problem to a similar but smaller problem

# Proof of Correctness of Greedy Algorithms

- Examine a globally optimal solution
- Show that this soln can be modified so that
  - 1) A greedy choice is made as the first step
  - 2) This choice reduces the problem to a similar but smaller problem
- Apply induction to show that a greedy choice can be used at every step
- Showing (2) reduces the proof of correctness to proving that the problem exhibits optimal substructure property

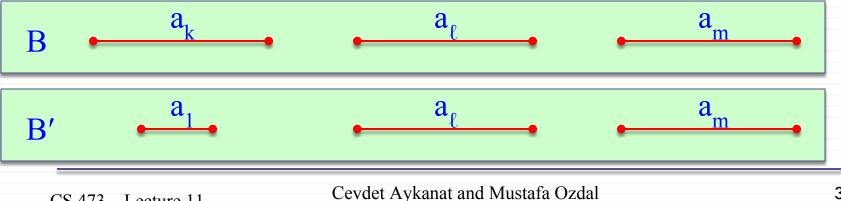
#### Greedy Choice Property - Proof

<u>*Theorem*</u>: There exists an optimal solution  $A \subseteq S$  such that  $a_1 \in A$ 

<u>*Proof*</u>: Consider an arbitrary optimal solution  $B = \{a_k, a_\ell, a_m, ...\},\$ where  $f_k < f_\ell < f_m < ...$ 

If k = 1, then B starts with  $a_1$ , and the proof is complete

If k > 1, then create another solution B' by replacing  $a_k$  with  $a_1$ . Since  $f_1 \le f_k$ , B' is guaranteed to be valid, and |B'| = |B|, hence also optimal



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# Elements of Greedy Strategy

- How can you judge whether
- A greedy algorithm will solve a particular optimization problem?
  - Two key ingredients
  - Greedy choice property
  - Optimal substructure property

# Key Ingredients of Greedy Strategy

- Greedy Choice Property: A globally optimal solution can be arrived at by making locally optimal (greedy) choices
- In DP, we make a choice at each step but the choice may depend on the solutions to subproblems
- In Greedy Algorithms, we make the choice that seems best at that moment then solve the subproblems arising after the choice is made
  - The choice may depend on choices so far, but it cannot depend on any future choice or on the solutions to subproblems
- DP solves the problem bottom-up
- Greedy usually progresses in a top-down fashion by making one greedy choice after another reducing each given problem instance to a smaller one

# Key Ingredients: Greedy Choice Property

- We must prove that a greedy choice at each step yields a globally optimal solution
- The proof examines a globally optimal solution
- Shows that the soln can be modified so that a greedy choice made as the first step reduces the problem to a similar but smaller subproblem
- Then induction is applied to show that a greedy choice can be used at each step
- Hence, this induction proof reduces the proof of correctness to demonstrating that an optimal solution must exhibit optimal substructure property

## Key Ingredients: Greedy Choice Property

■ How to prove the greedy choice property?

- 1. Consider the greedy choice c
- 2. Assume that there is an optimal solution B that doesn't contain c.
- 3. Show that it is possible to convert B to another optimal solution B', where B' contains c.
- *Example*: Activity selection algorithm

Greedy choice:  $a_1$  (the activity with the earliest finish time) Consider an optimal solution B without  $a_1$ Replace the first activity in B with  $a_1$  to construct B' Prove that B' must be an optimal solution

# Key Ingredients: Optimal Substructure

• A problem exhibits optimal substructure if an optimal solution to the problem contains within it optimal solutions to subproblems

Example: Activity selection problem *S* 

If an optimal solution A to S begins with activity  $a_1$  then the set of activities

$$A' = A - \{a_1\}$$

is an optimal solution to the activity selection problem

$$S' = \{a_i \in S: s_i \ge f_1\}$$

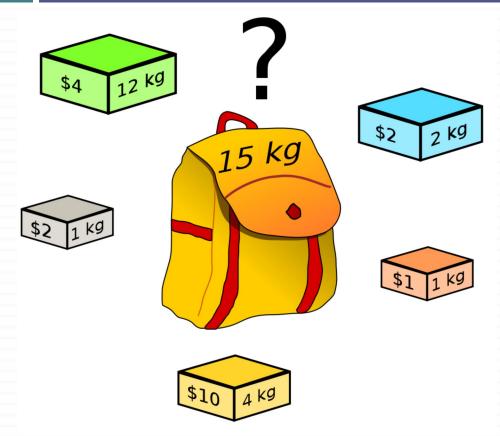
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# Key Ingredients: Optimal Substructure

- Optimal substructure property is exploited by both Greedy and dynamic programming strategies
- Hence one may
  - Try to generate a dynamic programming soln to a problem when a greedy strategy suffices □ inefficient
  - Or, may mistakenly think that a greedy soln works when in fact a DP soln is required  $\Box$  incorrect
- Example: Knapsack Problems(*S*, *w*)

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## **Knapsack Problems**



Each item i has:

weight w<sub>i</sub>

value v<sub>i</sub>

- A thief has a knapsack of weight capacity w
- Which items to choose to maximize the value of the items in the knapsack?

Image source: Wikimedia Commons

## Knapsack Problem: Two Versions

#### <u>The 0-1 knapsack problem:</u>

Each item is discrete.

Each item either chosen as a whole or not chosen.

Examples: TV, laptop, gold bricks, etc.

## The fractional knapsack problem:

Can choose fractional part of each item. If item i has weight  $w_i$ , we can choose any amount  $\leq w_i$ Examples: Gold dust, silver dust, rice, etc.

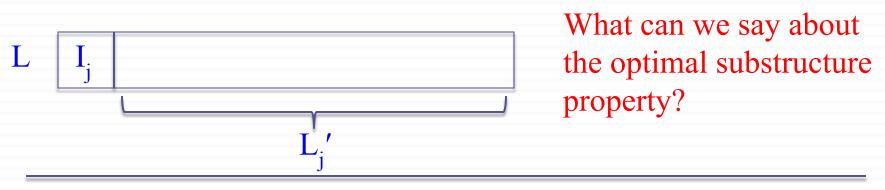
# **Knapsack Problems**

- The 0-1Knapsack Problem(*S*, *W*)
  - A thief robbing a store finds *n* items  $S = \{I_1, I_2, ..., I_n\}$ , the *i*th item is worth  $v_i$  dollars and weighs  $w_i$  pounds, where  $v_i$  and  $w_i$  are integers
  - He wants to take as valuable a load as possible, but he can carry at most W pounds in his knapsack, where W is an integer
  - The thief cannot take a fractional amount of an item
- The Fractional Knapsack Problem (S, W)
  - The scenario is the same
  - But, the thief can take fractions of items rather than having to make binary (0-1) choice for each item

## Optimal Substructure Property for the 0-1 Knapsack Problem (S, W)

- Consider an optimal load L for the problem (S, W).
- Let  $I_i$  be an item chosen in L with weight  $w_i$
- Assume we remove  $I_i$  from L, and let:

 $L_j' = L - \{I_j\}$  $S_j' = S - \{I_j\}$  $W_j' = W - W_j$ 

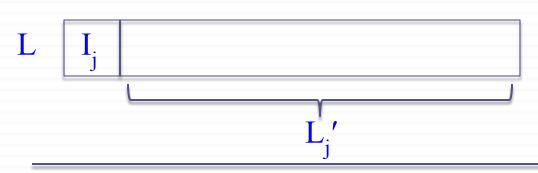


Optimal Substructure Property for the 0-1 Knapsack Problem (S, W)

$$L_j' = L - \{I_j\}$$
$$S_j' = S - \{I_j\}$$
$$W_j' = W - W_j$$

Optimal substructure property:

 $L_{j}'$  must be an optimal solution for  $(S_{j}', W_{j}')$  Why?



Optimal Substructure Property for the 0-1 Knapsack Problem (S, W)

$$L_j' = L - \{I_j\}$$
  $S_j' = S - \{I_j\}$   $W_j' = W - W_j$   
Optimal substructure:  $L_i'$  must be an optimal solution for  $(S_i', W_i')$ 

<u>**Proof</u>**: By contradiction, assume there is a solution  $B_j'$  for  $(S_j', W_j')$ , which is better than  $L_i'$ .</u>

We can construct a solution B for the original problem (S, W) as:  $B = B'_i \cup \{I_i\}.$ 

The total value of B is now higher than L, which is a contradiction because L is optimal for (S, W).

Q.E.D.

Optimal Substructure Property for the Fractional Knapsack Problem (S, W)

- $\square$  Consider an optimal solution *L* for (S, W)
- □ If we remove a weight  $0 \le w \le w_j$  of item *j* from optimal load *L* The remaining load

 $L_j' = L - \{w \text{ pounds of } I_j\}$ 

must be a most valuable load weighing at most

 $W_{j}' = W - W$ 

pounds that the thief can take from

 $S_j' = S - \{I_j\} \cup \{w_j - w \text{ pounds of } I_j\}$ 

• That is,  $L_i'$  should be an optimal soln to the

Fractional Knapsack Problem $(S_i', W_i')$ 

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## **Knapsack Problems**

- Two different problems:
  - 0-1 knapsack problem
  - Fractional knapsack problem
- The problems are similar.
- Both problems have optimal substructure property.
- Which algorithm to solve each problem?

## Fractional Knapsack Problem

- Can we use a greedy algorithm?
- <u>Greedy choice</u>: Take as much as possible from the item with the largest value per pound  $v_i/w_i$

#### Does the greedy choice property hold?

Let j be the item with the largest value per pound  $v_i/w_i$ 

Need to prove that there is an optimal load that has as much j as possible.

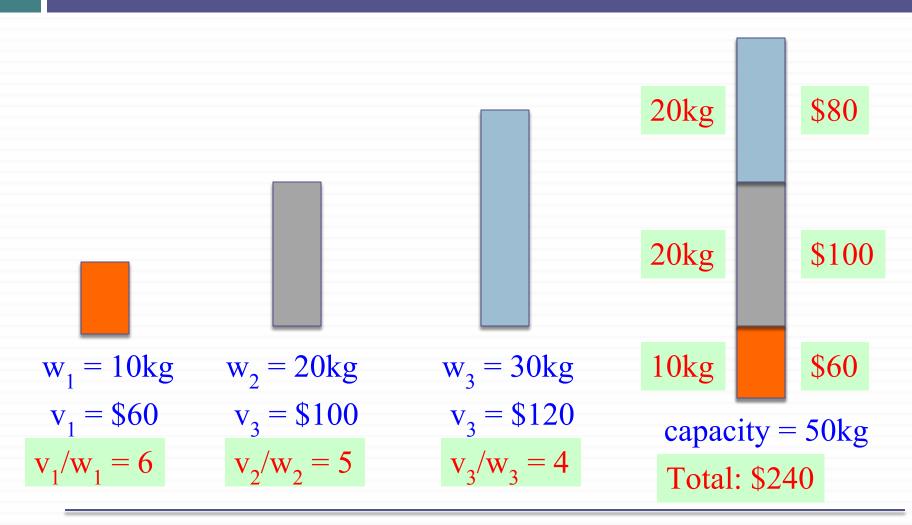
<u>Proof</u>: Consider an optimal solution L that does not have the maximum amount of item j. We could replace the items in L with item j until L has maximum amount of j. L would still be optimal, because item j has the highest value per pound.

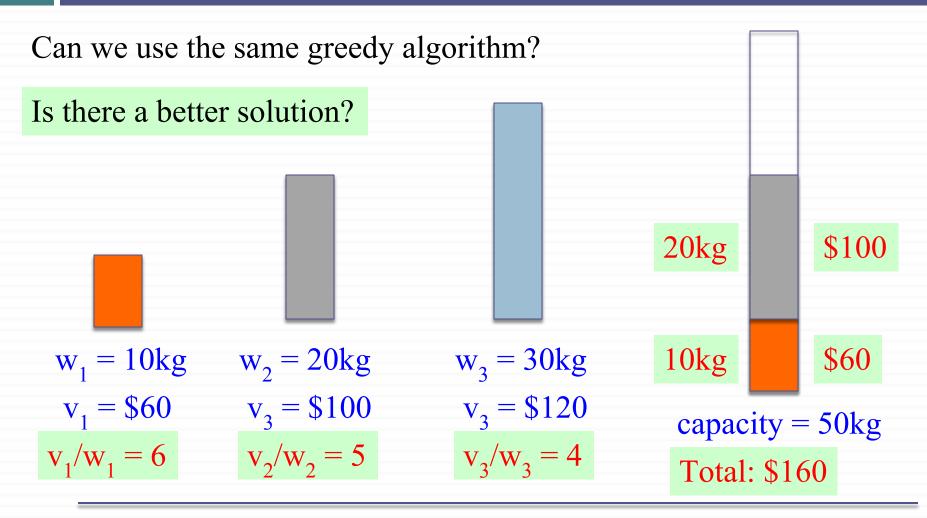
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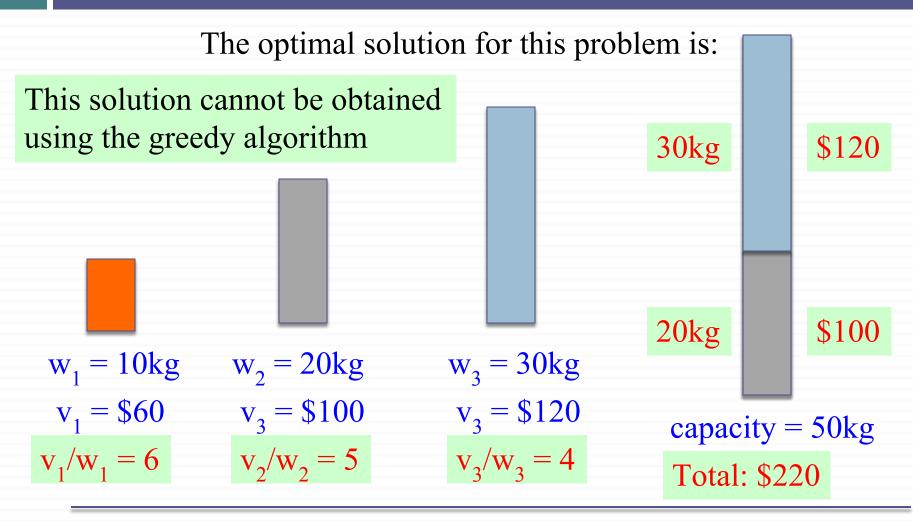
# Greedy Solution to Fractional Knapsack

- 1) Compute the value per pound  $v_i / w_i$  for each item
- 2) The thief begins by taking, as much as possible, of the item with the greatest value per pound
- 3) If the supply of that item is exhausted before filling the knapsack, then he takes, as much as possible, of the item with the next greatest value per pound
- 4) Repeat (2-3) until his knapsack becomes full
  - Thus, by sorting the items by value per pound the greedy algorithm runs in O(*n*lg *n*) time

## Fractional Knapsack Problem: Example







• When we consider an item *I<sub>j</sub>* for inclusion we must compare the solutions to two subproblems

- Subproblems in which  $I_i$  is included and excluded

• The problem formulated in this way gives rise to many

overlapping subproblems (a key ingredient of DP)

In fact, dynamic programming can be used to solve the 0-1 Knapsack problem

- A thief robbing a store containing *n* articles
  - $\{a_1, a_2, \dots, a_n\}$
  - The value of *i*th article is  $v_i$  dollars ( $v_i$  is integer)
  - The weight of *i*th article is  $w_i \text{ kg}(w_i \text{ is integer})$
- Thief can carry at most W kg in his knapsack
- Which articles should he take to maximize the value of his load?
- Let  $K_{n,W} = \{a_1, a_2, \dots, a_n: W\}$  denote 0-1 knapsack problem
- Consider the solution as a sequence of *n* decisions
  - i.e., *i*th decision: whether thief should pick  $a_i$  for optimal load

## **Optimal Substructure Property**

- Notation: K<sub>n,W</sub>: The items to choose from: {a<sub>1</sub>, ..., a<sub>n</sub>} The knapsack capacity: W
- Consider an optimal load L for problem  $K_{n,W}$
- Let's consider two cases:
   1) a<sub>n</sub> is in L
   2) a<sub>n</sub> is not in L

## **Optimal Substructure Property**

#### $\Box \quad \underline{\text{Case 1}}: \text{ If } a_n \in L$

What can we say about the optimal substructure?

 $L - \{a_n\}$  must be optimal for  $K_{n-1,W-wn}$ 

 $K_{n-1,W-wn}$ : The items to choose from  $\{a_1, \dots, a_{n-1}\}$ The knapsack capacity:  $W - W_n$ 

 $\Box \quad \underline{\text{Case 2}}: \text{ If } a_n \notin L$ 

What can we say about the optimal substructure? L must be optimal for  $K_{n-1 W}$ 

 $K_{n-1,W}$ : The items to choose from  $\{a_1, \dots, a_{n-1}\}$ The knapsack capacity: W

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## **Optimal Substructure Property**

In other words, optimal solution to  $K_{n,W}$  contains an optimal solution to:

either:  $K_{n-1,W-wn}$  (if  $a_n$  is selected) or:  $K_{n-1,W}$  (if  $a_n$  is not selected)

### **Recursive Formulation**

c[i, w]: The value of an optimal solution to  $K_{i,w}$ where  $K_{i,w}$ : { $a_1, \dots a_i$ : w}

$$c[i,w] = \begin{cases} 0, & \text{if } i = 0 \text{ or } w = 0\\ c[i-1,w], & \text{if } w_i > w\\ max\{v_i + c[i-1,w-w_i], c[i-1,w]\} & \text{o/w} \end{cases}$$

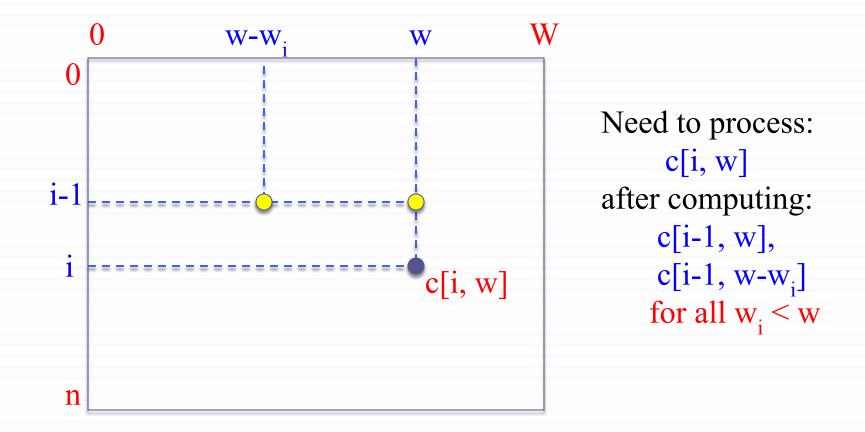
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Recursive definition for value of optimal soln:

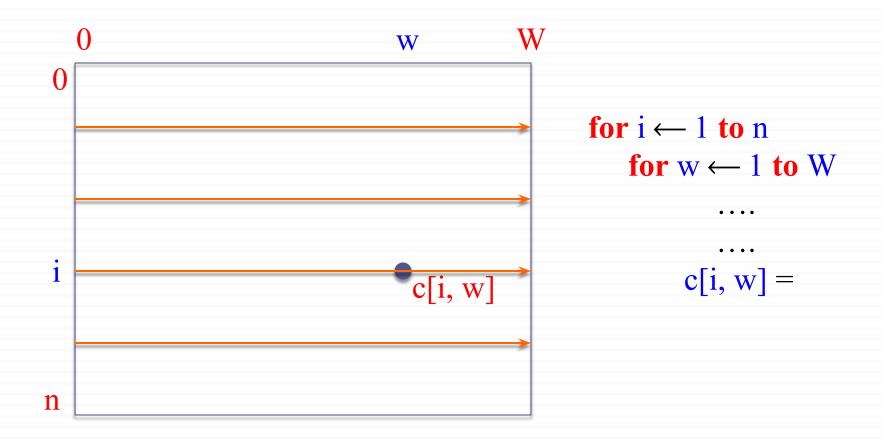
This recurrence says that an optimal solution  $S_{i,w}$  for  $K_{i,w}$ 

- either contains  $a_i \Rightarrow c(S_{i,w}) = v_i + c(S_{i-1,w-wi})$
- or does not contain  $a_i \Rightarrow c(S_{i,w}) = c(S_{i-1,w})$
- If thief decides to pick  $a_i$ 
  - He takes  $v_i$  value and he can choose from  $\{a_1, a_2, \dots, a_{i-1}\}$ up to the weight limit  $w - w_i$  to get  $c[i - 1, w - w_i]$
- If he decides not to pick  $a_i$ 
  - He can choose from  $\{a_1, a_2, \dots, a_{i-1}\}$  up to the weight limit w to get c[i-1,w]
- The better of these two choices should be made

## Bottom-up Computation



## Bottom-up Computation



#### DP Solution to 0-1 Knapsack **KNAP0-1**(*v*, *w*, *n*, *W*) c is an $(n+1)\times(W+1)$ array; c[0...n:0..W]for $\mathbf{\omega} \leftarrow 0$ to W do $c[0, \omega] \leftarrow 0$ Note: table is computed for $i \leftarrow 1$ to n do in row-major order $c[i, 0] \leftarrow 0$ **for** *i*←1 **to** *n* **do** Run time: $T(n) = \Theta(nW)$ for $\omega \leftarrow 1$ to W do if $w_i \leq \omega$ then $c[i, \omega] \leftarrow max\{\mathbf{v}_i + c[i-1, \omega - \mathbf{w}_i], c[i-1, \omega]\}$ else $c[i, \omega] \leftarrow c[i-1, \omega]$ return c[n, W]

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## Constructing an Optimal Solution

 No extra data structure is maintained to keep track of the choices made to compute c[i, w]

i.e. The choice of whether choosing item i or not

Possible to understand the choice done by comparing c[i, w] with c[i-1, w]

If c[i,w] = c[i-1, w] then it means item i was assumed to be not chosen for the best c[i, w]

# Finding the Set *S* of Articles in an Optimal Load

SOLKNAP0-1(a, v, w, n, W, c)  $i \leftarrow n; \omega \leftarrow W$  $S \leftarrow \varnothing$ 

while i > 0 do if  $c[i, \omega] = c[i-1, \omega]$  then  $i \leftarrow i-1$ else  $S \leftarrow S \cup \{a_i\}$   $\omega \leftarrow \omega - w_i$  $i \leftarrow i-1$ 

#### return S

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# 0-1 Knapsack Example

Item i	1	2	3	4
Value (\$)	100	20	60	40
Weight (kg)	3	2	4	1

c(i,w)	0	1	2	3	4	W=5
0	0	0	0	0	0	0
1	0					
2	0					
3	0					
n=4	0					

# 0-1 Knapsack Example

Item i	1	2	3	4
Value (\$)	100	20	60	40
Weight (kg)	3	2	4	1

c(i,w)	0	1	2	3	4	W=5
0	0	0	0	0	0	0
1	0	0	0	100	100	100
2	0	0	20	100	100	120
3	0	0	20	100	100	120
n=4	0	40	40	100	140	140

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## CS473 - Algorithms I

## Huffman Codes

## Huffman Codes for Compression

 Widely used and very effective for data compression
 Savings of 20% - 90% typical (depending on the characteristics of the data)

 In summary: Huffman's greedy algorithm uses a table of frequencies of character occurrences to build up an optimal way of representing each character as a binary string.

## Binary String Representation - Example

- Consider a data file with:
  - □ 100K characters
  - □ Each character is one of {a, b, c, d, e, f}
- □ Frequency of each character in the file:

a b c d e f

frequency 45K 13K 12K 16K 9K 5K

- <u>Binary character code</u>: Each character is represented by a unique binary string.
- $\Box \quad \underline{Intuition}: Frequent characters \iff shorter codewords$ Infrequent characters  $\iff longer codewords$

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## Binary String Representation - Example

	a	b	С	d	е	f
frequency	45K	13K	12K	16K	9K	5K
fixed-length	000	001	010	011	100	101
variable-length(1)	0	101	100	111	1101	1100
variable-length(2)	0	10	110	1110	11110	11111

How many total bits needed for fixed-length codewords? 100K \* 3 = 300K bits

How many total bits needed for variable-length(1) codewords? 45K\*1 + 13K\*3 + 12K\*3 + 16K\*3 + 9K\*4 + 5K\*4 = 224KHow many total bits needed for variable-length(2) codewords? 45K\*1 + 13K\*2 + 12K\*3 + 16K\*4 + 9K\*5 + 5K\*5 = 241K

## Prefix Codes

- Prefix codes: No codeword is also a prefix of some other codeword
- Example:

	a	b	С	d	е	f
codeword	0	101	100	111	1101	1100

□ It can be shown that:

Optimal data compression is achievable with a prefix code

 In other words, optimality is not lost due to prefix-code restriction.

## Prefix Codes: Encoding

	a	b	С	d	е	f
codeword	0	101	100	111	1101	1100

 <u>Encoding</u>: Concatenate the codewords representing each character of the file

■ <u>Example</u>: Encode file "abc" using the codewords above abc  $\Rightarrow 0.101.100 \Rightarrow 0101100$ 

Note: "." denotes the concatenation operation. It is just for illustration purposes, and does not exist in the encoded string

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# Prefix Codes: Decoding

- Decoding is quite simple with a prefix code
- The first codeword in an encoded file is unambiguous
   *because no codeword is a prefix of any other*
- □ <u>Decoding algorithm</u>:
  - 1. Identify the initial codeword
  - 2. Translate it back to the original character
  - 3. Remove it from the encoded file
  - 4. Repeat the decoding process on the remainder of the encoded file.

#### Prefix Codes: Decoding - Example

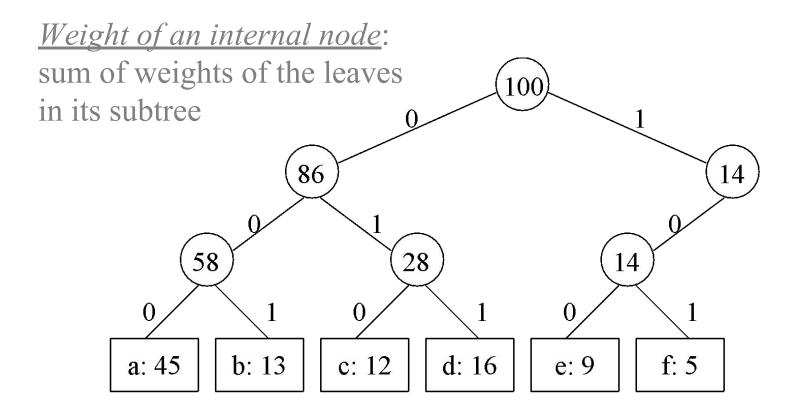
	a	b	С	d	е	f
codeword	0	101	100	111	1101	1100

<u>Example</u>: Decode encoded file 001011101 001011101  $\Rightarrow$  0.01011101  $\Rightarrow$  0.0.1011101 0.0.101.1101  $\Rightarrow$  0.0.101.1101  $\Rightarrow$  aabe Convenient representation for the prefix code: a binary tree whose leaves are the given characters

Binary codeword for a character is the path from the root to that character in the binary tree

"0" means "go to the left child" "1" means "go to the right child"

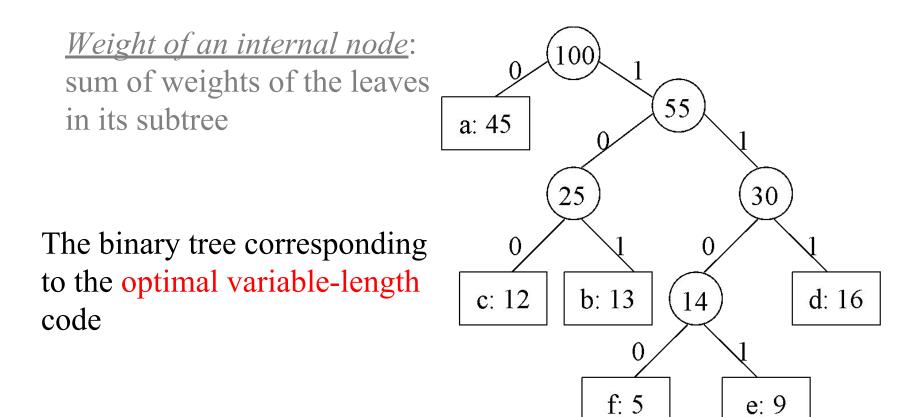
#### Binary Tree Representation of Prefix Codes



#### The binary tree corresponding to the fixed-length code

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#### Binary Tree Representation of Prefix Codes



#### An optimal code for a file is always represented by a full binary tree

Cevdet Aykanat - Bilkent University Computer Engineering Department Consider an FBT corresponding to an optimal prefix code

It has |C| leaves (external nodes)

One for each letter of the alphabet where *C* is the alphabet from which the characters are drawn

Lemma: An FBT with |C| external nodes has exactly |C|-1 internal nodes

#### Full Binary Tree Representation of Prefix Codes

- Consider an FBT T, corresponding to a prefix code.
- Notation:

f(c): frequency of character c in the file
d<sub>T</sub>(c): depth of c's leaf in the FBT T
B(T): the number of bits required to encode the file

• What is the length of the codeword for c?

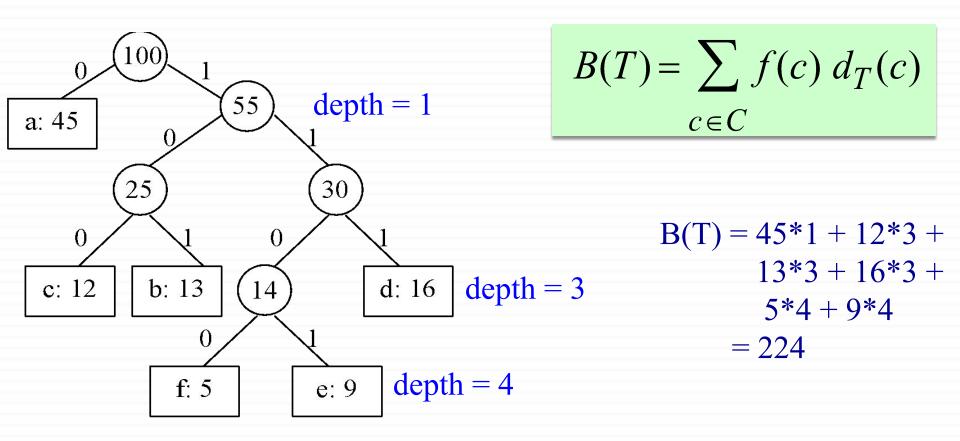
 $d_{T}(c)$ , same as the depth of c in T

• How to compute B(T), cost of tree T?

$$B(T) = \sum_{c \in C} f(c) d_T(c)$$

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#### Cost Computation - Example



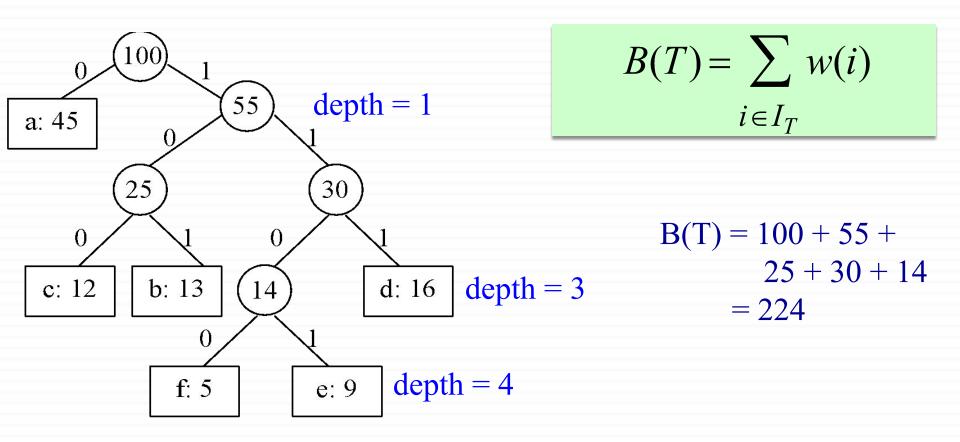
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Lemma: Let each internal node i is labeled with the sum of the weight w(i) of the leaves in its subtree

Then 
$$B(T) = \sum_{c \in C} f(c) d_T(c) = \sum_{i \in I_T} w(i)$$
 where  $I_T$  denotes the set of internal nodes in  $T$ 

**Proof:** Consider a leaf node *c* with  $f(c) \& d_T(c)$ Then, f(c) appears in the weights of  $d_T(c)$  internal node along the path from *c* to the root Hence, f(c) appears  $d_T(c)$  times in the above summation

#### Cost Computation - Example



#### Constructing a Huffman Code

<u>Problem Formulation</u>: For a given character set C, construct an optimal prefix code with the minimum total cost

Huffman invented a greedy algorithm that constructs an optimal prefix code called a Huffman code

The greedy algorithm

- builds the FBT corresponding to the optimal code in a bottom-up manner
- begins with a set of |C| leaves
- performs a sequence of |C|-1 "merges" to create the final tree

A priority queue Q, keyed on f, is used to identify the two least-frequent objects to merge

The result of the merger of two objects is a new object

- inserted into the priority queue according to its frequency
- which is the sum of the frequencies of the two objects merged

#### Constructing a Huffman Code

HUFFMAN(C)  

$$n \leftarrow |C|$$
  
 $Q \leftarrow BUILD-HEAP(C)$   
for  $i \leftarrow 1$  to  $n-1$  do  
 $z \leftarrow ALLOCATE-NODE()$   
 $x \leftarrow left[z] \leftarrow EXTRACT-MIN(Q)$   
 $y \leftarrow right[z] \leftarrow EXTRACT-MIN(Q)$   
 $f[z] \leftarrow f[x] + f[y]$   
INSERT(Q, z)  
return EXTRACT-MIN(Q)  $\Delta$  only one object left in Q  
Priority queue is implemented as a binary heap

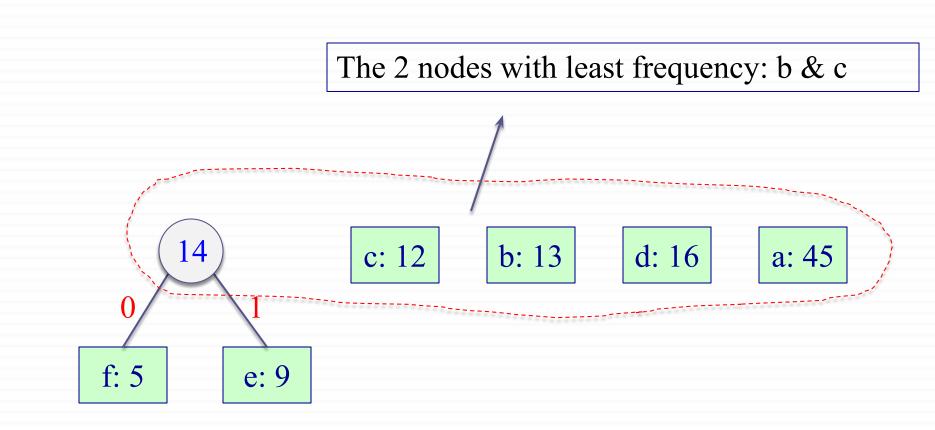
Initiation of Q (BUILD-HEAP): O(n) time EXTRACT-MIN & INSERT take  $O(\lg n)$  time on Q with n objects

$$T(n) = \sum_{i=1}^{n} \lg i = O(\lg(n!)) = O(n \lg n)$$

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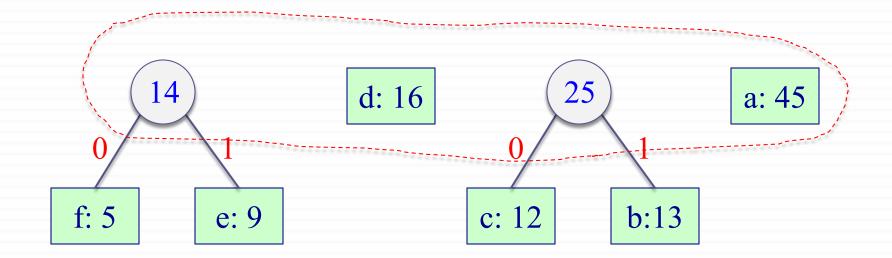
Start with one leaf node for each character

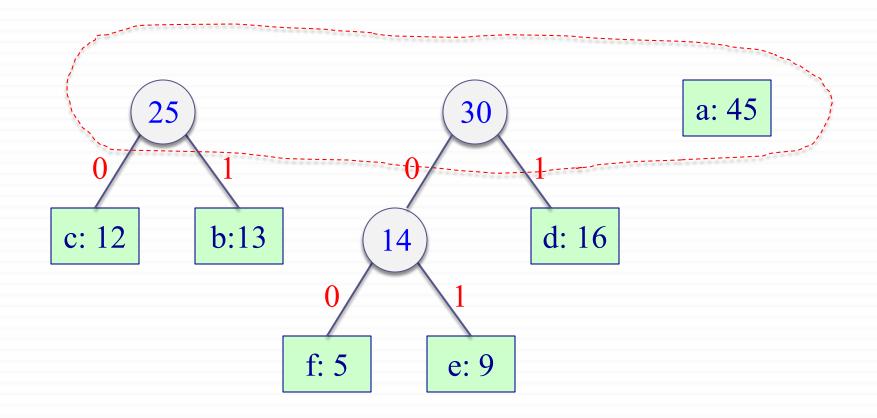
The 2 nodes with the least frequencies: f & eMerge f & e and create an internal node Set the internal node frequency to 5 + 9 = 14



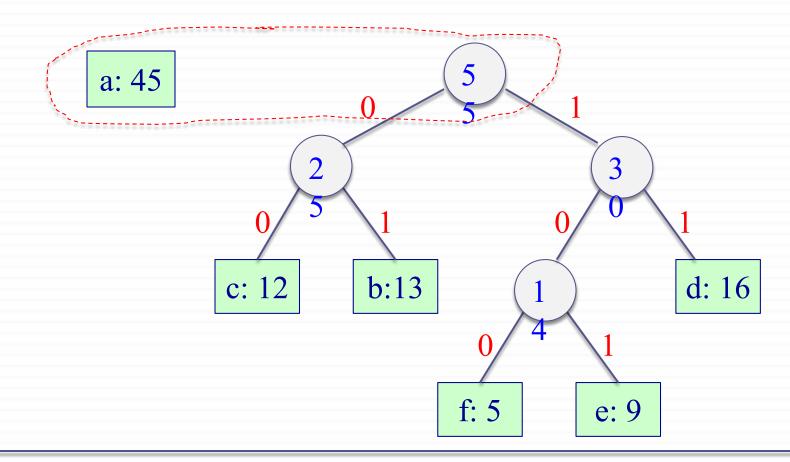
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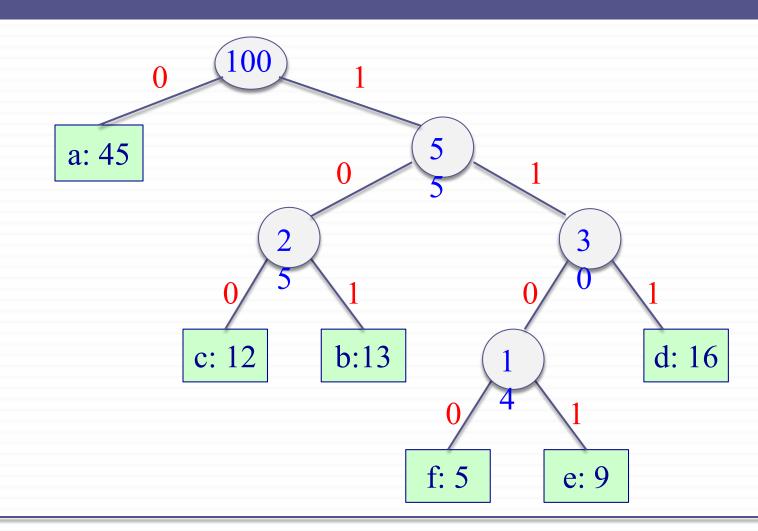




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# Correctness Proof of Huffman's Algorithm

- We need to prove:
  - The greedy choice property
  - The optimal substructure property
- What is the greedy step in Huffman's algorithm?
   Merging the two characters with the lowest frequencies
- We will first prove the greedy choice property

# Greedy Choice Property

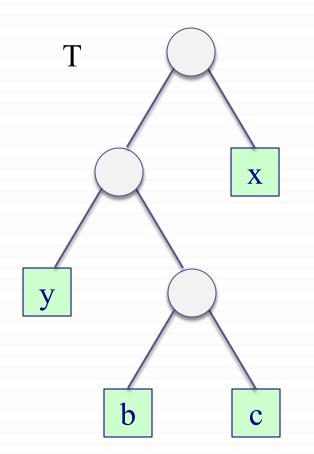
*Lemma 1*: Let x & y be two characters in C having the lowest frequencies.

Then,  $\exists$  an optimal prefix code for C in which the codewords for *x* & *y* have the same length and differ only in the last bit

<u>Note</u>: If x & y are merged in Huffman's algorithm, their codewords are guaranteed to have the same length and they will differ only in the last bit. Lemma 1 states that there exists an optimal solution where this is the case.

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- Outline of the proof:
  - Start with an arbitrary optimal solution
  - Convert it to an optimal solution that satisfies the greedy choice property.
- *Proof*: Let T be an arbitrary optimal solution where:
   b & c are the sibling leaves with the max depth
   x & y are the characters with the lowest frequencies



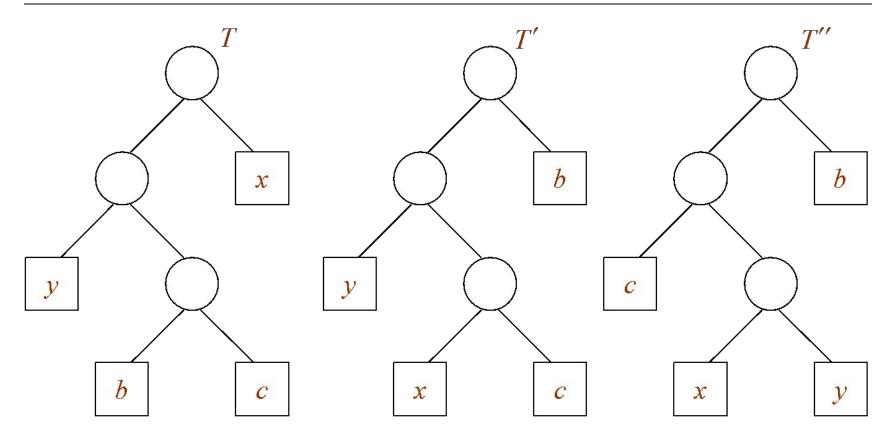
Reminder:

b & c are the nodes with max depthx & y are the nodes with min freq.

Without loss of generality, assume:  $f(x) \le f(y)$   $f(b) \le f(c)$ 

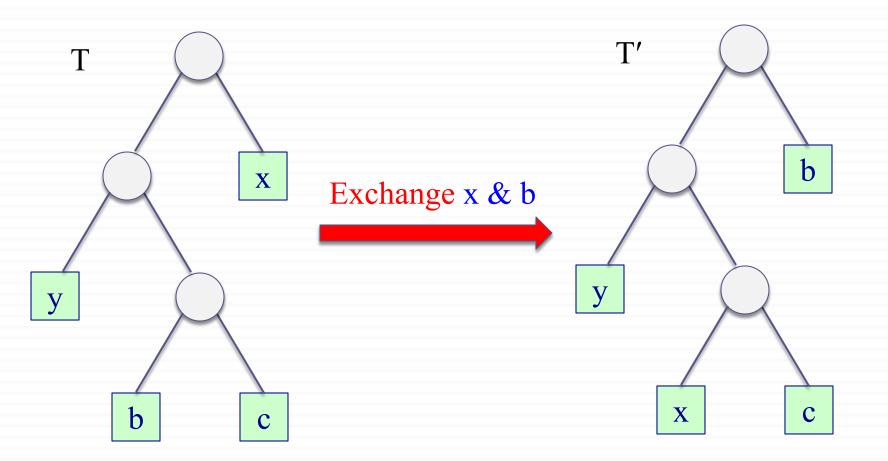
Then, it must be the case that:  $f(x) \le f(b)$  $f(y) \le f(c)$ 

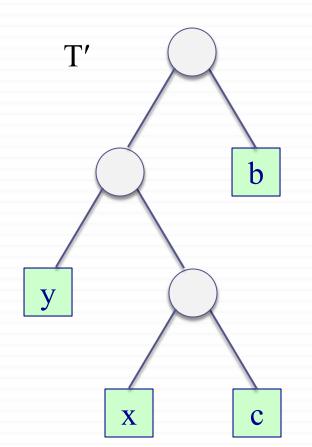
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 $T \Rightarrow T'$ : exchange the positions of the leaves b & x $T' \Rightarrow T''$ : exchange the positions of the leaves c & y

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<u>*Reminder*</u>: Cost of tree T':

$$B(T') = \sum_{c \in C} f(c) d_{T'}(c)$$

How does B(T') compare to B(T)?

**<u>Reminder</u>:**  $f(x) \le f(b)$  $d_{T'}(x) = d_{T}(b)$  and  $d_{T'}(b) = d_{T}(x)$ 

**Reminder:** 
$$f(x) \le f(b)$$
  
 $d_{T'}(x) = d_{T}(b)$  and  $d_{T'}(b) = d_{T}(x)$ 

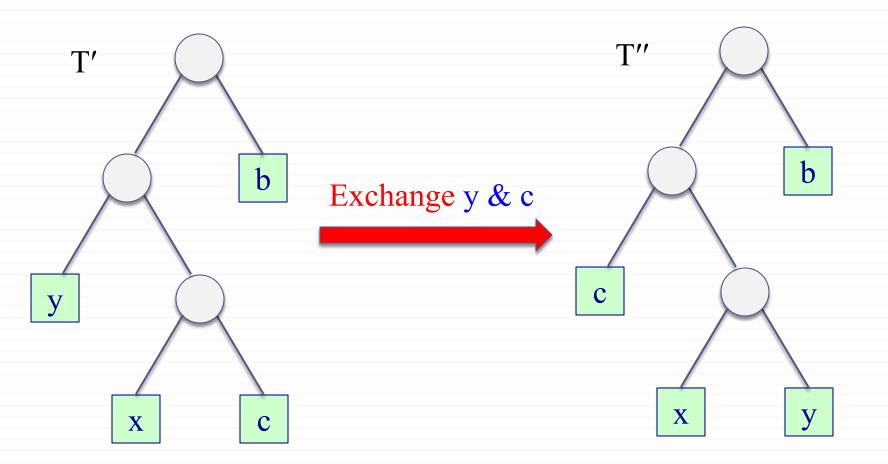
The difference in cost between T and T':

$$\begin{split} B(T) - B(T') &= \sum_{c \in C} f(c)d_T(c) - \sum_{c \in C} f(c)d_{T'}(c) \\ &= f[x]d_T(x) + f[b]d_T(b) - f[x]d_{T'}(x) - f[b]d_{T'}(b) \\ &= f[x]d_T(x) + f[b]d_T(b) - f[x]d_T(b) - f[b]d_T(x) \\ &= f[b](d_T(b) - d_T(x)) - f[x](d_T(b) - d_T(x)) \\ &= (f[b] - f[x])(d_T(b) - d_T(x)) \end{split}$$

$$B(T) - B(T') = (f[b] - f[x])(d_T(b) - d_T(x))$$

Since  $f[b] - f[x] \ge 0$  and  $d_T(b) \ge d_T(x)$ therefore  $B(T') \le B(T)$ 

In other words, T' is also optimal



- We can similarly show that

  B(T')−B(T'') ≥ 0 ⇒ B(T'') ≤ B(T')
  which implies B(T'') ≤ B(T)

  Since T is optimal ⇒ B(T'') = B(T) ⇒ T'' is also optimal
- <u>Note</u>: T" contains our greedy choice:
   Characters x & y appear as sibling leaves of max-depth in T"
- Hence, the proof for the greedy choice property is complete

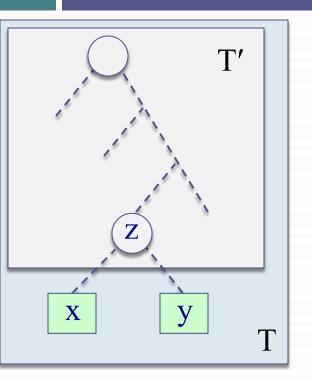
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	Computer Engineering Department, Bilkent University	

#### Lemma 1 implies that process of building an optimal tree by mergers can begin with the greedy choice of merging those two characters with the lowest frequency

We have already proved that  $B(T) = \sum w(i)$ , that is, the total cost of the tree constructed is the sum of the costs of its mergers (internal nodes) of all possible mergers

# At each step Huffman chooses the merger that incurs the least cost

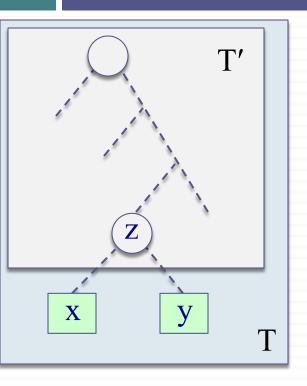
# **Optimal Substructure Property**



Consider an optimal solution T for alphabet C. Let x and y be any two sibling leaf nodes in T. Let z be the parent node of x and y in T.

Consider the subtree T' where  $T' = T - \{x, y\}$ . Here, consider z as a new character, where f[z] = f[x] + f[y]

<u>*Optimal substructure property*</u>: T' must be optimal for the alphabet C', where  $C' = C - \{x, y\} \cup \{z\}$ 



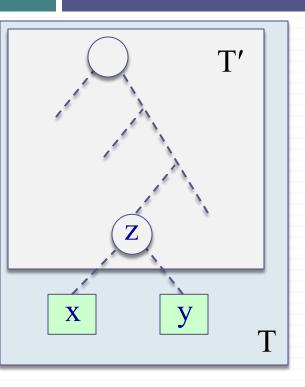
<u>Reminder:</u>

$$B(T) = \sum_{c \in C} f[c] d_T(c)$$

Try to express B(T) in terms of B(T'). Note: All characters in C' have the same depth in T and T'.

B(T) = B(T') - cost(z) + cost(x) + cost(y)

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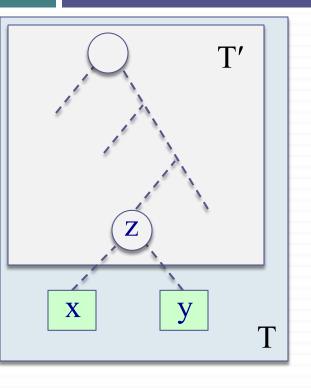
Reminder:

$$B(T) = \sum_{c \in C} f[c] d_T(c)$$

$$\begin{split} B(T) &= B(T') - cost(z) + cost(x) + cost(y) \\ &= B(T') - f[z].d_T(z) + f[x].d_T(x) + f[y].d_T(y) \\ &= B(T') - f[z].d_T(z) + (f[x] + f[y]) (d_T[z] + 1) \\ &= B(T') - f[z].d_T(z) + f[z] (d_T[z] + 1) \\ &= B(T') + f[z] \end{split}$$

$$d_{T}(x) = d_{T}(z) + 1$$
  
$$d_{T}(y) = d_{T}(z) + 1$$

B(T) = B(T') + f[x] + f[y]



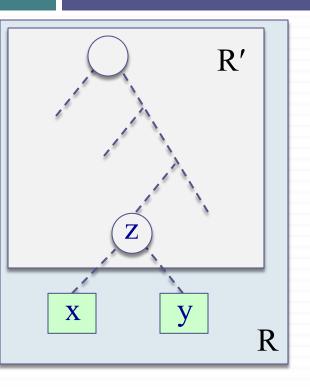
We want to prove that T' is optimal for  $C' = C - \{x, y\} \cup \{z\}$ 

Assume by contradiction that that there exists another solution for C' with smaller cost than T'. Call this solution R':

#### $B(R') \le B(T')$

Let us construct another prefix tree R by adding x & y as children of z in R'

#### B(T) = B(T') + f[x] + f[y]



Let us construct another prefix tree R by adding x & y as children of z in R'.

We have: B(R) = B(R') + f[x] + f[y]In the beginning, we assumed that: B(R') < B(T')So, we have: B(R) < B(T') + f[x] + f[y] = B(T)Contradiction!  $\Rightarrow$  Proof complete

#### Greedy Algorithm for Huffman Coding - Summary

- □ For the greedy algorithm, we have proven that:
  - □ The greedy choice property holds.
  - The optimal substructure property holds.
- So, the greedy algorithm is optimal.